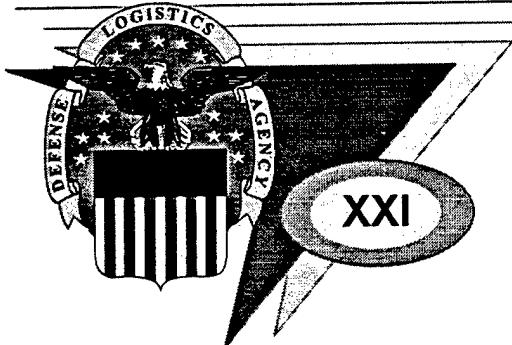


DORRA

Final Report

"Insight through Analysis"



**DEVELOPMENT OF
DCMC SITE SELECTION
MODEL**

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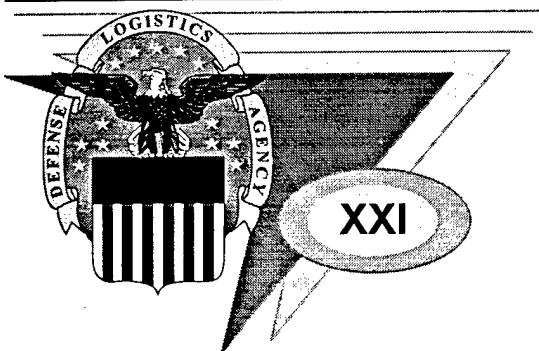
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**DEFENSE CONTRACT MANAGEMENT COMMAND
SITE SELECTION MODEL**

**Major Randy Zimmerman
Captain Jeffery L. Huisingsh**

MAY 1998

**DEPARTMENT OF DEFENSE
DEFENSE LOGISTICS AGENCY
Office of Operations Research and
Resource Analysis**

**c/o Defense Supply Center Richmond
8000 Jefferson Davis Highway
Richmond, VA 23297-5082**



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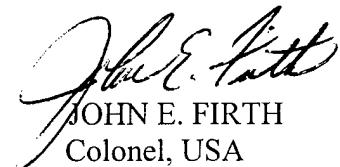
IN REPLY
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FOREWORD

This report documents a new automated method for selection of meeting and training event locations. The program developed for this project, OffSite, optimizes the selection of training locations by a modified use of Dykstra's algorithm, used to minimize the travel costs between more than 260 cities across the United States. OffSite considers both travel and per diem costs for all potential training locations.

We would like to thank Mr. Steve Herlihy of the Defense Contract Management Command for his guidance and assistance with this project. Additionally, we would like to thank Captain Jeff Huisingsh of TRAC - Monterey and Mr. Harold Yamauchi of Rolands & Associates Corporation. Their work on this project was key to the success of this project.


JOHN E. FIRTH
Colonel, USA
Chief, DLA Office of Operations Research
and Resource Analysis

EXECUTIVE SUMMARY

The Defense Contract Management Command (DCMC) Workforce Strategy team asked the DLA Office of Operations Research and Resource Analysis (DORRA) office to develop a methodology that would select the least cost training sites for DCMC employees. The resulting program, Offsite, works by optimizing the airfare, and individually the meals and incidental expense and lodging cost elements of the per diem costs. A conservative estimate of possible model savings is about \$400,000 annually if a level of savings of 5% are achieved. Actual savings could be even higher.

All of the data used in this model are available to the public on the Internet. In the past, such data were not readily available in electronic form. Plans are underway to make the model available to all potential DLA users on the DCMC website. This will help ensure the best possible distribution, availability, and usage to further maximize the potential savings.

Every effort was made to make the OffSite program easy to use. An intuitive graphical user interface requiring few user inputs allows a typical user to have results in a minute or less. The drop-down menus and other features of the user screens are of the same grade and quality as the best commercially available software.

OffSite uses a database of 4,640 GSA contracted airfare rates to solve for the 2^{261} possible origin-destination airport pair combinations. OffSite uses a modification of Dykstra's algorithm to select the optimal route from among thousands of possibilities.

The problem of finding the most cost-effective location for a training course, meeting, or conference is not unique to DCMC. It is a problem for the entire Federal government. The alternative to using this model, a manual site selection method, seldom yields the best solution when considering several alternatives. Frequently, the best solution can be counter-intuitive. For example, the optimal site can change, even though the candidate sites remain unchanged, if the number meeting day's changes or the number of people coming from each origin changes. Thus, selection experience with familiar candidate cities does not help the manual selection process.

The potential savings through possible government-wide application are enormous. The Federal government spends about \$7 billion annually on travel, about half of which is for DoD. It is possible that \$2 billion, or more, of the \$7 billion is for the type of training and meetings that have discretionary site locations. If so, Internet availability and promotion of the model through reengineering laboratories could result in government wide savings of tens of millions, or possibly even more. Currently DORRA is exploring reinvention laboratory possibilities that could promote government wide use.

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SECTION 1 - STUDY DESCRIPTION

PROBLEM STATEMENT

Develop a site selection model to assist the DCMC management in selecting cost-effective training locations.

BACKGROUND

The travel costs associated with the locations chosen for DCMC training are a significant component of the DCMC annual training budget. The DCMC management is interested in developing a site selection model that will minimize the travel costs for personnel attending DCMC sponsored training.

OBJECTIVES

1.3.1 Review current DCMC methodology for selecting training locations.

1.3.2 Develop a site selection model using operations research techniques to minimize the travel costs of DCMC personnel.

SCOPE

Overall project functional guidance for this effort was provided by DCMC-BG, HQ DLA. All operational analysis support was accomplished by the technical support staff assigned by DORRA in Richmond, Virginia and TRAC – Monterey, Monterey, California.

ASSUMPTIONS

There are several core assumptions associated with this study. The first assumption is that any model developed must be simple for the user to use and provide useful information. The second central assumption is that the model can not cover all possible travel situations. For example, the model will not account for the traveler who commutes to the training event in a Government owned vehicle or rides as a passenger in a POV. Special cases are left up to the user. Other assumptions used: (1) All travel is done individually, i.e., no ride or room sharing. (2) Travelers will use commercial planes or POV. (3) No government meals or lodging are available. (4) Travelers with a permanent duty station (PDS) greater than 100 statute miles will fly to the training event site. Otherwise, they will drive. (5) Attendees who fly to the training event will arrive the day before the training event begins and will return to their point of origin on the last day of the training event. (6) Attendees who drive to the training event will depart the PDS the day the training event begins and return to their PDS the day the training event ends. (7) The GSA contracted airfare is available for all flights.

LITERATURE OVERVIEW

After a review of the relevant literature and an extensive search of the Internet, it was determined that no commercial software is available to solve the site selection problem for DCMC. The DCMC problem lends itself to being solved as a minimal spanning tree problem. It was not the intent of this study to evaluate every available minimal spanning

algorithm, but rather to focus on a proven technique that might result in better information about the travel costs for training events. With this in mind, Dykstra's algorithm was used to solve for the least cost between all 261 airports using GSA contracted airfares to define the distances between airports.

SECTION 2 - STUDY APPROACH

EXAMPLE SOLUTION

The solution methodology used to optimize the results for this problem involves simple arithmetic and can be explained as follows. Given travelers from different cities who must come together for a meeting, the total travel cost is computed by multiplying the number of travelers from each city times the round trip transportation cost to a candidate city. The additional costs of lodging, meal and incidental expenses (M&IE) are multiplied by the number of people traveling to the training event site times the duration of the meeting in days. This can be best illustrated by example. Consider the situation where 11 people from four cities must attend a four-day meeting in St. Louis. The expense data is shown below:

Origin City	Number of Travelers	Meals and Incidental Expenses Per Day	Lodging Per Day
Atlanta	2	\$38	\$97
Chicago	3	\$42	\$120
Springfield, IL	2	\$30	\$55
St. Louis	4	\$42	\$75

Travel Costs:

Route	Round Trip Travel Cost per Person
Atlanta(ATL)-St. Louis(STL)	\$204
Chicago(ORD)- St. Louis(STL)	\$70
Springfield(SPI) - St. Louis(STL)	\$52 (Driving Cost, 84 miles)

To hold the meeting in St. Louis, the costs are computed as follows:

- Transportation costs from all points of origin are:

$$(\# \text{ ATL Passengers}) * (\text{ATL-STL Airfare}) = (2) * (204) = \$408$$

$$(\# \text{ ORD Passengers}) * (\text{ORD-STL Airfare}) = (3) * (70) = \$210$$

$$(\# \text{ SPI Passengers}) * (\text{ORD-STL Airfare}) = (2) * (168 \text{ mi.} * \$.31/\text{mi}) = \$104$$

Total transportation costs are \$722.

- Meals and Incidental Expenses (M&IE) are computed as per The Joint Travel Regulations allowing 75% for the first and last days traveled with 100% given for full travel days. We can calculate the St. Louis M&IE at:

(Total # of participants flying to St. Louis)*(St. Louis M&IE)*(# of days-.5(assuming the meeting is more than one day))=(5)*(42)*(4.5)=\$945

(Total # of participants driving to St. Louis)*(St. Louis M&IE)*(# of days-.5(assuming the meeting is more than one day))=(2)*(42)*(3.5)=\$294

- ** Note: .5 is used in the M&IE calculations to account for the 75% of first and last days M&IE allowed by the Joint Travel Regulation.
- Total M&IE expense is \$1,239
- Lodging costs for passengers that fly are calculated assuming they arrive the day before the meeting and depart the day the meeting ends.

(Total # of participants who fly to STL)*(STL maximum lodging rate)*(# of days for the training event)=(5)*(75)*(4)=\$1,500

- Lodging costs for passengers that drive are calculated assuming they drive to the training event the day of the meeting and depart the day the meeting ends.

(Total # of participants who drive to STL)*(STL maximum lodging rate)*(# of days for the training event - 1)=(2)*(75)*(3)=\$450

Total lodging expense is \$1,950

Thus the total cost to host the training event in St. Louis is:

$$\$722 + \$1,239 + \$1,950 = \$3,911$$

Computing the costs for Atlanta, Chicago, and Springfield using the same methodology yields the following results:

City	Travel	M&IE	Lodging	\$ Total	
Atlanta	1,768	1,539	3,492	6,799	
Chicago	788	1,512	3,840	6,140	
St. Louis	722	1,239	1,950	3,911	
Springfield, IL	1,034	1,095	1,760	3,889	Lowest cost meeting site

It quickly becomes obvious that while this is a straight forward, albeit time consuming task, to manually calculate all of the costs, a spreadsheet would be useful for performing the calculations. However, the inherent difficulty with developing a spreadsheet based solution to this problem lie in the difficulty in obtaining all of the data required to solve the example problem.

DATA COLLECTION AND PREPROCESSING

All data points used in the model were verified by hand prior to inclusion in the model. Verification became necessary when examination of trial output revealed solution errors. It was discovered that spelling errors and abbreviations of location names and states in the source data are a problem. All six coordinates used in the latitude and longitude locations of the 261 airports and both values used in the per diem rates were verified. Once the input data were checked, the model results were verified using a combination of the General Algebraic Modeling System (GAMS) and hand calculations for test models. The OffSite results corresponded to the GAMS output and hand check of the chosen locations.

The data used for the model were collected from a variety of public sources. The General Services Agency (GSA) provided the city pair flight data at its website: <http://pub.fss.gsa.gov/services/citypair.html>. As previously noted, there are only 4,640 city pair GSA airfares available for 261 different airports located in the coterminous United States. The problem for the training event planner is that there remain 63,220 city pair combinations without contracted airfares.

After determining that no commercial software is available to solve for the optimal training event location, an algebraic representation of the problem was developed and is presented below.

$$\text{Min Cost } \sum_j X_j * (\sum_i T_{ij} + P_j)$$

$$\text{Subject to } \sum_j X_j \geq 1$$

where: i,j = cities (261)

P_i = Per Diem rate at city i

T_{ij} = the cost to travel to city j from city i

X_j = 1 if meeting in city j, 0 otherwise

Dr. Dimitri P. Bertsekas of the Massachusetts Institute of Technology provided the minimal spanning tree algorithm used to solve for the least cost between airports. Dr. Bertsekas's algorithm, Relax-IV, is a schema that involves a new use of Dykstra's algorithm modified for non-capacitated shortest path network optimization. The algorithm optimizes the routes between all 261 airports in the model. The output from the algorithm is used by OffSite to calculate the flight travel costs for the training event locations chosen. The Relax-IV algorithm conducts an iterative search through all 2^{261} airport pair combinations to determine the optimal connecting route for each airport. Once the search is complete, the data are stored in an array that is used to determine the travel costs for the chosen cities. Dr. Bertsekas Relax-IV code and authorization for use in this project are on file with DORRA.

GSA publishes monthly changes to the city pair rates at <http://pub.fss.gsa.gov/services/citypair.html>. The rates change for a variety of reasons which can include; dropping a route or city by an airline, airline mergers, and others. However, according to Ms. Renita Nowlin of the GSA, there is normally little change with the domestic carriers that are included in this model. The contract for the city pair airfares is competed annually. Hence, the OffSite program will require annual updates. A sample of the GSA rates used in the model was compared to the "real-time" airline reservation system at the Omega World Travel office located in Richmond, Virginia. The travel agent, Ms. Heather Perez confirmed that the sample airfares were all within $\pm 5\%$ of the price quoted for 26 March 1998.

The per diem rates used for the locations in the model were provided by The Per Diem, Travel, and Transportation Allowance Committee website at: <http://www.dtic.mil/perdiem/>. The rates are published on an annual basis. As previously specified, the model calculations incorporate the 75% allowance for the first and last days travel of the Meals and Incidental Expenses. In the cases where seasonal per diem rates are available the higher rate is used. The lodging rate is based upon the maximum allowable rate for each area.

Driving rates are calculated using the standard \$.31 cents per mile rate authorized for POV travel. The distance between airports is calculated using the latitude and longitude locations of the airports. If the distance between airports is greater than 100 miles, the program default is that the traveler will fly to the training event. If the distance is 100 miles or less the default is the calculated mileage between airports.

Rental car costs are not considered in this model for a variety of reasons. Currently, the GSA does not have contracted rates with rental car agencies. Hence the variability of rates by city and rental agency is impractical to model. Additionally, training location

planners can choose to use airport hotels for their training events. Frequently airport hotels provide no cost shuttle transportation from the hotel to the airport, avoiding the cost of rental cars altogether. Discussions with Ms. Heather Perez revealed that as a rule, travelers should expect to pay an average of \$45/day in rental car expenses.

The dynamics of the airline flight-scheduling system, coupled with the lack of an accounting system, prohibit any model from determining the *exact* cost for a training event. This is largely due to uncontrollable variations in potential departure and arrival locations. For example, the least cost one-way airfare from the Washington DC (BWI) airport to the CAO office in Wichita KS is \$161 with travel through three airports. The same trip from Washington (National) to Wichita is \$150 with travel through two airports, National and Wichita. To travel from Washington (Dulles) to Wichita is \$134, with no connecting flights. The model makes its calculations based on input from the user. If the traveler normally uses BWI for departures then it will calculate his flight cost as \$322. When the traveler makes his reservations, the travel agent might show the traveler that the flight is indirect and costs more than a direct flight from National or Dulles, changing his departure location. Conversely, the flights from National and Dulles might be booked, and the only available flight is the BWI flight. The model output must be considered as an estimate of the actual travel cost for the event. This is the "Catch-22" of the problem and why it is impossible to get exact costs to the most efficient meeting site. For any model to choose the most effective multiple travel routes it must know the final destination, which of course is also what this model is determining. Therefore, some basic assumptions must be made up front for the model to determine the optimal location. As previously stated the model produces reasonable and nearly optimal travel plans and destination guidelines, but there is no claim of an *exact* solution.

SECTION 3 - CONCLUSIONS

OffSite was tested using data from a recent two-day training event DCMC sponsored by DCMC at Monterey, California. Representatives from every CAO office attended the training event. The table below shows the results of the site selection model for the Monterey training event. OffSite revealed that Monterey is \$10,522 more than the least cost alternative, Tulsa OK at \$27,060. This represents a 39% savings on this training event alone. If OffSite is constrained to choose one of the CAO cities, then St. Louis MO is chosen at \$29,896. St. Louis is 26% less expensive than Monterey.

Monterey	CA	\$37,582
----------	----	----------

The 10 least expensive places in the United States:

Tulsa	OK	\$27,060
Oklahoma City	OK	\$27,180
Little Rock	AR	\$27,622
Moline	IL	\$28,114
Louisville	KY	\$28,857
Reno	NV	\$29,148

Ontario	CA	\$29,314
Albuquerque	NM	\$29,742
Lawton	OK	\$29,792
St. Louis	MO	\$29,896

If one origin city hosts the conference:

St. Louis	MO	\$29,896
Indianapolis	IN	\$30,110
Dayton	OH	\$30,129
Orlando	FL	\$30,466
Hartford	CT	\$30,513
Cleveland	OH	\$30,624
Birmingham	AL	\$30,658
Albany	NY	\$31,081
Wichita	KS	\$31,157
Jacksonville	FL	\$31,381

If DCMC could save 39% on every training event, it might realize potential \$3.1 million dollar savings based upon the FY97 training budget. Even if a more conservative estimate of 5% annual savings is used, its possible that DCMC could realize an annual \$400,000 saving on travel related to training.

The larger implication is that a 5% savings in the Federal training and meeting travel budget could result in as much as \$100 million dollars a year in savings based upon a estimate of the annual Federal travel budget by Dennis Fischer, GSA Chief Financial Officer (www.federaltimes.com/federaltraveler/reinvent.html). These savings are achievable because all Federal Government and Department of Defense employees have access to GSA airfares, and all are subject to the per diem rates used in the calculations. This assumes widespread use of the model by meeting and training event planners. Posting OffSite on the DCMC website will provide worldwide distribution to other users.

SECTION 4 - RECOMMENDATIONS

Recommend immediate implementation of the OffSite software and funding for continued refinement of the user interface and software updates. Additionally, recommend releasing OffSite to other Federal agencies for use.

APPENDIX A

Appendix A is the source code for solving both the DCMC transportation problem and the code for the OffSite graphical user interface.

RELAX-IV MINIMAL SPANNING TREE ALGORITHM

```
C SAMPLE CALLING PROGRAM FOR RELAX-IV
C
C-----
C
C PURPOSE - THIS PROGRAM READS IN DATA FOR A LINEAR COST
C ORDINARY NETWORK FLOW PROBLEM FROM THE FILE 'RELAX4.INP',
C CALLS THE ROUTINE INIDAT TO CONSTRUCT LINKED LIST FOR THE
C PROBLEM,
C AND THEN CALLS THE ROUTINE RELAX4 TO SOLVE THE PROBLEM.
C
C-----
C
C PROGRAM MAIN
C IMPLICIT INTEGER (A-Z)
C
C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C PARAMETER (MAXNN=10000, MAXNA=70000)
C
C INPUT PARAMETERS
C
C N      = NUMBER OF NODES
C NA     = NUMBER OF ARCS
C LARGE   = A VERY LARGE INTEGER TO REPRESENT INFINITY
C STARTN(J) = STARTING NODE FOR ARC J,           J = 1,...,NA
C ENDN(J)  = ENDING NODE FOR ARC J,           J = 1,...,NA
C C(J)    = COST OF ARC J,           J = 1,...,NA
C
C INTEGER STARTN(MAXNA),ENDN(MAXNA),C(MAXNA)
C COMMON /INPUT/N,NA,LARGE
C COMMON /ARRAYS/STARTN/ARRAYE/ENDN/ARRAYC/C
C
C UPDATED PARAMETERS
C
C U(J)   = CAPACITY OF ARC J ON INPUT AND RESIDUAL CAPACITY
C          ON OUTPUT,           J = 1,...,NA
C B(I)   = DEMAND AT NODE I ON INPUT AND ZERO ON OUTPUT,
C          I = 1,...,N
```

```

C
  INTEGER U(MAXNA),B(MAXNN)
  COMMON /ARRAYU/U/ARRAYB/B
C
C OUTPUT PARAMETERS
C
C   X(J)    = FLOW ON ARC J,           J = 1,...,NA
C   RC(J)   = REDUCED COST OF ARC J,   J = 1,...,NA
C   NMULTINODE = NUMBER OF MULTINODE RELAXATION ITERATIONS IN
RELAX4
C   ITER    = NUMBER OF RELAXATION ITERATIONS IN RELAX4
C   NUM_AUGM = NUMBER OF FLOW AUGMENTATION STEPS IN RELAX4
C   NUM_ASCNT = NUMBER OF MULTINODE ASCENT STEPS IN RELAX4
C   NSP     = NUMBER OF AUCTION/SHORTEST PATH ITERATIONS
C   TCOST   = COST OF FLOW
C
  INTEGER X(MAXNA),RC(MAXNA)
  REAL*8 TCOST
  COMMON /ARRAYX/X/ARRAYRC/RC
  COMMON /OUTPUT/NMULTINODE,ITER,NUM_AUGM,NUM_ASCNT,NSP
C
C WORKING PARAMETERS
C
  INTEGER I1(MAXNN),I2(MAXNN),I3(MAXNN),I4(MAXNA)
  INTEGER I5(MAXNN),I6(MAXNA),I7(MAXNA)
  INTEGER TFSTOU(MAXNN),TNXTOU(MAXNA)
  INTEGER TFSTIN(MAXNN),TNXTIN(MAXNA)
  INTEGER I14(MAXNN),I15(MAXNN),I16(MAXNN),I17(MAXNN)
  LOGICAL*1 SCAN(MAXNN),MARK(MAXNN)
  LOGICAL*1 REPEAT
  COMMON /BLK1/I1/BLK2/I2/BLK3/I3/BLK4/I4
  COMMON /BLK5/I5/BLK6/I6/BLK7/I7
  COMMON /BLK8/SCAN/BLK9/MARK
  COMMON /BLK10/TFSTOU/BLK11/TNXTOU/BLK12/TFSTIN/BLK13/TNXTIN
  COMMON /BLK14/I14/BLK15/I15/BLK16/I16/BLK17/I17
  COMMON /CR/CRASH
  COMMON /BLKR/REPEAT
C
C OPTIONAL WORKING PARAMETERS (FOR SENSITIVITY ANALYSIS ONLY)
C
  INTEGER CAP(MAXNA)
  COMMON /BLKCAP/CAP
C
C DECLARE TIMING VARIABLES FOR UNIX SYSTEM
C
  REAL*4 TIME0,TIME1,TIME2

```

```

COMMON /T/TIME0,TIME1
C
C-----
C   READ PROBLEM DATA FROM FILE RELAX4.INP
C
C   PRINT*,READ PROBLEM DATA FROM RELAX4.INP'
C     OPEN(13,FILE='RELAX4.INP',STATUS='OLD')
C     REWIND(13)
C
C   READ NUMBER OF NODES AND ARCS
C
C   READ(13,1000) N,NA
C
C   READ START NODE, END NODE, COST, AND CAPACITY OF EACH ARC
C
C   DO 20 I=1,NA
C     READ(13,1000) STARTN(I),ENDN(I),C(I),U(I)
20  CONTINUE
C
C   READ SUPPLY OF EACH NODE; CONVERT IT TO DEMAND
C
C   DO 30 I=1,N
C     READ(13,1000) B(I)
C     B(I)=-B(I)
30  CONTINUE
C
1000 FORMAT(4I8)
REWIND(13)
CLOSE(13)

C
C   PRINT*,END OF READING'
C   PRINT*,NUMBER OF NODES =',N,', NUMBER OF ARCS =',NA
C
C   SET LARGE TO A LARGE INTEGER FOR YOUR MACHINE
C
C   LARGE=500000000
C   DANGER_THRESH=LARGE/10
C
C   CHECK DATA IS WITHIN RANGE OF MACHINE
C
C   FLAG1=0
C   FLAG2=0
C   FLAG3=0
DO 40 I=1,NA
  IF (ABS(C(I)).GT.LARGE) FLAG1=1

```

```

        IF (U(I).GT.LARGE) FLAG2=1
        IF (ABS(C(I)).GT.DANGER_THRESH) FLAG3=1
40  CONTINUE
        IF (FLAG1.EQ.1) THEN
          PRINT*, 'SOME COSTS EXCEED THE ALLOWABLE RANGE'
          PRINT*, 'PROGRAM CANNOT RUN; PRESS <CR> TO EXIT'
          PAUSE
          STOP
        END IF
        IF (FLAG2.EQ.1) THEN
          PRINT*, 'SOME ARC CAPACITIES EXCEED THE ALLOWABLE RANGE'
          PRINT*, 'PROGRAM CANNOT RUN; PRESS <CR> TO EXIT'
          PAUSE
          STOP
        END IF
        IF (FLAG3.EQ.1) THEN
          PRINT*, 'SOME COSTS ARE DANGEROUSLY LARGE'
          PRINT*, 'PROGRAM MAY NOT RUN CORRECTLY'
        END IF
C
C-----
C
C  CONSTRUCT LINKED LISTS FOR THE PROBLEM
C
C  PRINT*, 'CONSTRUCT LINKED LISTS FOR THE PROBLEM'

      CALL INIDAT
C
C-----
C
C  INITIALIZE DUAL PRICES
C  (DEFAULT: ALL DUAL PRICES = 0, SO REDUCED COST IS SET
C  EQUAL TO COST)
C
      DO 60 I=1,NA
60    RC(I)=C(I)
C
C  SPECIFY THAT WE ARE SOLVING THE PROBLEM FROM SCRATCH
C
C  REPEAT=.FALSE.
C
C  STORE CAPACITY OF ARCS IN CAP
C  (OPTIONAL IF SENSITIVITY ANALYSIS WILL NOT BE ACTIVATED)
C
      DO 70 I=1,NA
70    CAP(I)=U(I)

```

```

C
C-----
C
C   SET CRASH EQUAL TO 1 TO ACTIVATE AN AUCTION/SHORTEST PATH
SUBROUTINE FOR
C   GETTING THE INITIAL PRICE-FLOW PAIR. THIS IS RECOMMENDED FOR
DIFFICULT
C   PROBLEMS WHERE THE DEFAULT INITIALIZATION YIELDS
C   LONG SOLUTION TIMES.
C
PRINT*,'ENTER THE INITIALIZATION DESIRED'
PRINT*, '<0> FOR THE DEFAULT INITIALIZATION'
PRINT*, '<1> FOR AUCTION INITIALIZATION'
READ*,CRASH
C
C   CALL RELAX4 TO SOLVE THE PROBLEM
C
75 CONTINUE
PRINT*, 'CALLING RELAX4 TO SOLVE THE PROBLEM'
PRINT*, *****
C
C   INITIALIZE SYSTEM TIMER
C
C   TIME0 = LONG(362)/60.0
TIME0 = SECNDS(0.0)
C
CALL RELAX4
C
C   CALL SYSTEM TIMER TO DISPLAY EXECUTION TIME FOR RELAX4
C
C   TIME2 = LONG(362)/60.0 - TIME0
TIME2 = SECNDS(TIME0)

PRINT*, TOTAL SOLUTION TIME =',TIME2,' SECS.'
PRINT*, TIME IN INITIALIZATION =',TIME1,' SECS.'
C
C-----
C
C   CHECK CORRECTNESS OF OUTPUT PARAMETERS
C
DO 80 NODE=1,N
IF (B(NODE).NE.0) THEN
  PRINT*,NONZERO SURPLUS AT NODE ',NODE
END IF
80 CONTINUE
DO 90 ARC=1,NA

```

```

IF (X(ARC).GT.0) THEN
  IF (RC(ARC).GT.0) THEN
    PRINT*, 'COMPLEMENTARY SLACKNESS VIOLATED AT ARC ',ARC
  ENDIF
ENDIF
IF (U(ARC).GT.0) THEN
  IF (RC(ARC).LT.0) THEN
    PRINT*, 'COMPLEMENTARY SLACKNESS VIOLATED AT ARC ',ARC
  ENDIF
ENDIF
90 CONTINUE
C
C COMPUTE AND DISPLAY COST OF FLOWS (IN DOUBLE PRECISION)
C
TCOST=FLOAT(0)
DO 100 I=1,NA
  TCOST=TCOST + DFLOAT(X(I)*C(I))
100 CONTINUE
PRINT*, 'OPTIMAL COST = ',TCOST
C
C DISPLAY RELAX4 STATISTICS
C
IF (CRASH.EQ.1) THEN
  PRINT*, 'NUMBER OF AUCTION/SHORTEST PATH ITERATIONS = ',NSP
END IF
PRINT*, 'NUMBER OF ITERATIONS = ',ITER
PRINT*, 'NUMBER OF MULTINODE ITERATIONS = ',NMULTINODE
PRINT*, 'NUMBER OF MULTINODE ASCENT STEPS = ',NUM_ASCNT
PRINT*, 'NUMBER OF REGULAR AUGMENTATIONS = ',NUM_AUGM
PRINT*, '*****'
C
C TO ACTIVATE SENSITIVITY ANALYSIS, INSERT THE FOLLOWING
C THREE LINES HERE.
C
CALL SENSTV
REPEAT=.TRUE.
GO TO 75
C
END
C
C
SUBROUTINE INIDAT
IMPLICIT INTEGER (A-Z)
C
C-----
C

```

```

C PURPOSE - THIS ROUTINE CONSTRUCTS TWO LINKED LISTS FOR
C THE NETWORK TOPOLOGY: ONE LIST (GIVEN BY FOU, NXTOU) FOR
C THE OUTGOING ARCS OF NODES AND ONE LIST (GIVEN BY FIN,
C NXTIN) FOR THE INCOMING ARCS OF NODES. THESE TWO LISTS
C ARE REQUIRED BY RELAX4.
C
C -----
C
C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C PARAMETER (MAXNN=10000, MAXNA=70000)
C
C INPUT PARAMETERS
C
C N      = NUMBER OF NODES
C NA     = NUMBER OF ARCS
C STARTN(J) = STARTING NODE FOR ARC J,      J = 1,...,NA
C ENDN(J)  = ENDING NODE FOR ARC J,      J = 1,...,NA
C
C INTEGER STARTN(MAXNA),ENDN(MAXNA)
C COMMON /ARRAYS/STARTN/ARRAYE/ENDN
C COMMON /INPUT/N,NA,LARGE
C
C OUTPUT PARAMETERS
C
C FOU(I)  = FIRST ARC OUT OF NODE I,      I = 1,...,N
C NXTOU(J) = NEXT ARC OUT OF THE STARTING NODE OF ARC J,
C           J = 1,...,NA
C FIN(I)   = FIRST ARC INTO NODE I,      I = 1,...,N
C NXTIN(J) = NEXT ARC INTO THE ENDING NODE OF ARC J,
C           J = 1,...,NA
C
C INTEGER FOU(MAXNN),NXTOU(MAXNA),FIN(MAXNN),NXTIN(MAXNA)
C COMMON /BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
C
C WORKING PARAMETERS
C
C INTEGER TEMPIN(MAXNN),TEMPOU(MAXNN)
C COMMON /BLK1/TEMPIN/BLK2/TEMPOU
C
C -----
C
DO 10 I=1,N
  FIN(I)=0
  FOU(I)=0

```

```

        TEMPIN(I)=0
10     TEMPOU(I)=0
        DO 20 I=1,NA
        NXTIN(I)=0
        NXTOU(I)=0
        I1=STARTN(I)
        I2=ENDN(I)
        IF (FOU(I1).NE.0) THEN
            NXTOU(TEMPOU(I1))=I
        ELSE
            FOU(I1)=I
        END IF
        TEMPOU(I1)=I
        IF (FIN(I2).NE.0) THEN
            NXTIN(TEMPIN(I2))=I
        ELSE
            FIN(I2)=I
        END IF
20     TEMPIN(I2)=I
        RETURN
        END
C
C
C          SUBROUTINE RELAX4
C          IMPLICIT INTEGER (A-Z)
C
C-----C
C
C          RELAX-IV (VERSION OF OCTOBER 1994)
C
C          RELEASE NOTE - THIS VERSION OF RELAXATION CODE HAS OPTION FOR
C          A SPECIAL CRASH PROCEDURE FOR
C          THE INITIAL PRICE-FLOW PAIR. THIS IS RECOMMENDED FOR
C          DIFFICULT
C          PROBLEMS WHERE THE DEFAULT INITIALIZATION
C          RESULTS IN LONG RUNNING TIMES.
C          CRASH =1 CORRESPONDS TO AN AUCTION/SHORTEST PATH METHOD
C
C          THESE INITIALIZATIONS ARE RECOMMENDED IN THE ABSENCE OF
C          ANY
C          PRIOR INFORMATION ON A FAVORABLE INITIAL FLOW-PRICE VECTOR
C          PAIR
C          THAT SATISFIES COMPLEMENTARY SLACKNESS
C
C          THE RELAXATION PORTION OF THE CODE DIFFERS FROM THE CODE
C          RELAXT-III

```

C AND OTHER EARLIER RELAXATION CODES IN THAT IT MAINTAINS
C THE SET OF NODES WITH NONZERO DEFICIT IN A FIFO QUEUE.
C LIKE ITS PREDECESSOR RELAXT-III, THIS CODE MAINTAINS A LINKED
LIST
C OF BALANCED (I.E., OF ZERO REDUCED COST) ARCS SO TO REDUCE
C THE WORK IN LABELING AND SCANNING.
C UNLIKE RELAXT-III, IT DOES NOT USE SELECTIVELY
C SHORTEST PATH ITERATIONS FOR INITIALIZATION.

C

C-----

C

C PURPOSE - THIS ROUTINE IMPLEMENTS THE RELAXATION METHOD
C OF BERTSEKAS AND TSENG (SEE [1], [2]) FOR LINEAR
C COST ORDINARY NETWORK FLOW PROBLEMS.

C

C [1] BERTSEKAS, D. P., "A UNIFIED FRAMEWORK FOR PRIMAL-DUAL
METHODS ..."

C MATHEMATICAL PROGRAMMING, VOL. 32, 1985, PP. 125-145.

C [2] BERTSEKAS, D. P., AND TSENG, P., "RELAXATION METHODS FOR
MINIMUM COST ..." OPERATIONS RESEARCH, VOL. 26, 1988, PP. 93-114.

C

C THE RELAXATION METHOD IS ALSO DESCRIBED IN THE BOOKS:

C

C [3] BERTSEKAS, D. P., "LINEAR NETWORK OPTIMIZATION: ALGORITHMS
AND CODES"

C MIT PRESS, 1991.

C [4] BERTSEKAS, D. P. AND TSITSIKLIS, J. N., "PARALLEL AND
DISTRIBUTED

C COMPUTATION: NUMERICAL METHODS", PRENTICE-HALL, 1989.

C

C

C-----

C

C SOURCE - THIS CODE WAS WRITTEN BY DIMITRI P. BERTSEKAS
C AND PAUL TSENG, WITH A CONTRIBUTION BY JONATHAN ECKSTEIN
C IN THE PHASE II INITIALIZATION. THE ROUTINE AUCTION WAS
WRITTEN
C BY DIMITRI P. BERTSEKAS AND IS BASED ON THE METHOD DESCRIBED
IN
C THE PAPER:
C
C [5] BERTSEKAS, D. P., "AN AUCTION/SEQUENTIAL SHORTEST PATH
ALGORITHM
C FOR THE MINIMUM COST FLOW PROBLEM", LIDS REPORT P-2146, MIT,
NOV. 1992.

C
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C
C-----
C
C USER GUIDELINES -
C
C THIS ROUTINE IS IN THE PUBLIC DOMAIN TO BE USED ONLY FOR
RESEARCH
C PURPOSES. IT CANNOT BE USED AS PART OF A COMMERCIAL
PRODUCT, OR
C TO SATISFY IN ANY PART COMMERCIAL DELIVERY REQUIREMENTS TO
C GOVERNMENT OR INDUSTRY, WITHOUT PRIOR AGREEMENT WITH THE
AUTHORS.
C USERS ARE REQUESTED TO ACKNOWLEDGE THE AUTHORSHIP OF THE
CODE,
C AND THE RELAXATION METHOD. THEY SHOULD ALSO REGISTER WITH
THE
C AUTHORS TO RECEIVE UPDATES AND SUBSEQUENT RELEASES.
C
C NO MODIFICATION SHOULD BE MADE TO THIS CODE OTHER
C THAN THE MINIMAL NECESSARY
C TO MAKE IT COMPATIBLE WITH THE FORTRAN COMPILERS OF
SPECIFIC
C MACHINES. WHEN REPORTING COMPUTATIONAL RESULTS PLEASE BE
SURE
C TO DESCRIBE THE MEMORY LIMITATIONS OF YOUR MACHINE.
GENERALLY
C RELAX4 REQUIRES MORE MEMORY THAN PRIMAL SIMPLEX CODES
AND MAY
C BE PENALIZED SEVERELY BY LIMITED MACHINE MEMORY.
C
C-----
C
C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
PARAMETER (MAXNN=10000, MAXNA=70000)
C
C INPUT PARAMETERS (SEE NOTES 1, 2, 4)

```

C
C   N      = NUMBER OF NODES
C   NA     = NUMBER OF ARCS
C   LARGE   = A VERY LARGE INTEGER TO REPRESENT INFINITY
C             (SEE NOTE 3)
C   REPEAT  = .TRUE. IF INITIALIZATION IS TO BE SKIPPED
C             (.FALSE. OTHERWISE)
C   CRASH   = 0 IF DEFAULT INITIALIZATION IS USED
C             1 IF AUCTION INITIALIZATION IS USED
C   STARTN(J) = STARTING NODE FOR ARC J,           J = 1,...,NA
C   ENDN(J)   = ENDING NODE FOR ARC J,           J = 1,...,NA
C   FOU(I)    = FIRST ARC OUT OF NODE I,          I = 1,...,N
C   NXTOU(J)  = NEXT ARC OUT OF THE STARTING NODE OF ARC J,
C                 J = 1,...,NA
C   FIN(I)    = FIRST ARC INTO NODE I,            I = 1,...,N
C   NXTIN(J)  = NEXT ARC INTO THE ENDING NODE OF ARC J,
C                 J = 1,...,NA
C
C   INTEGER STARTN(MAXNA),ENDN(MAXNA)
C   INTEGER FOU(MAXNN),NXTOU(MAXNA),FIN(MAXNN),NXTIN(MAXNA)
C   LOGICAL*1 REPEAT
C   COMMON /INPUT/N,NA,LARGE
C   COMMON /ARRAYS/STARTN/ARRAYE/ENDN
C   COMMON /BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
C   COMMON /BLKR/REPEAT
C   COMMON /CR/CRASH
C
C   UPDATED PARAMETERS (SEE NOTES 1, 3, 4)
C
C   RC(J)   = REDUCED COST OF ARC J,           J = 1,...,NA
C   U(J)    = CAPACITY OF ARC J ON INPUT
C             AND (CAPACITY OF ARC J) - X(J) ON OUTPUT,
C                 J = 1,...,NA
C   DFCT(I) = DEMAND AT NODE I ON INPUT
C             AND ZERO ON OUTPUT,           I = 1,...,N
C
C   INTEGER RC(MAXNA),U(MAXNA),DFCT(MAXNN)
C   COMMON /ARRAYRC/RC/ARRAYU/U/ARRAYB/DFCT
C
C   OUTPUT PARAMETERS (SEE NOTES 1, 3, 4)
C
C   X(J)    = FLOW ON ARC J,           J = 1,...,NA
C   NMULTINODE = NUMBER OF MULTINODE RELAXATION ITERATIONS IN
C                 RELAX4
C   ITER    = NUMBER OF RELAXATION ITERATIONS IN RELAX4
C   NUM_AUGM = NUMBER OF FLOW AUGMENTATION STEPS IN RELAX4

```

```

C  NUM_ASCNT = NUMBER OF MULTINODE ASCENT STEPS IN RELAX4
C  NSP      = NUMBER OF AUCTION/SHORTEST PATH ITERATIONS
C
C     INTEGER X(MAXNA)
C     COMMON /ARRAYX/X
C     COMMON/OUTPUT/NMULTINODE,ITER,NUM_AUGM,NUM_ASCNT,NSP
C
C  WORKING PARAMETERS (SEE NOTES 1, 4, 5)
C
C     INTEGER LABEL(MAXNN),PRDCSR(MAXNN),SAVE(MAXNA)
C     INTEGER
C     TFSTOU(MAXNN),TNXTOU(MAXNA),TFSTIN(MAXNN),TNXTIN(MAXNA)
C     INTEGER DDPOS(MAXNN),DDNEG(MAXNN),NXTQUEUE(MAXNN)
C     INTEGER I15(MAXNN),I16(MAXNN),I17(MAXNN)
C     LOGICAL*1 SCAN(MAXNN),MARK(MAXNN)
C     LOGICAL*1 FEASBL,QUIT,SWITCH,POSIT,PCHANGE
C     COMMON /BLK1/LABEL/BLK2/PRDCSR/BLK7/SAVE
C     COMMON /BLK10/TFSTOU/BLK11/TNXTOU/BLK12/TFSTIN/BLK13/TNXTIN
C     COMMON /BLK14/NXTQUEUE/BLK15/I15/BLK16/I16/BLK17/I17
C     COMMON /BLK8/SCAN/BLK9/MARK
C     EQUIVALENCE(DDPOS,TFSTOU),(DDNEG,TFSTIN)
C
C  TIMING PARAMETERS
C
C     REAL*4 TIME0,TIME1
C     COMMON /T/TIME0,TIME1
C
C  NOTE 1 -
C     TO RUN IN LIMITED MEMORY SYSTEMS, DECLARE THE ARRAYS
C     STARTN, ENDN, NXTIN, NXTOU, FIN, FOU, LABEL,
C     PRDCSR, SAVE, TFSTOU, TNXTOU, TFSTIN, TNXTIN,
C     DDPOS, DDNEG, NXTQUEUE AS INTEGER*2 INSTEAD.
C
C  NOTE 2 -
C     THIS ROUTINE MAKES NO EFFORT TO INITIALIZE WITH A FAVORABLE
C     X
C     FROM AMONGST THOSE FLOW VECTORS THAT SATISFY
C     COMPLEMENTARY SLACKNESS
C     WITH THE INITIAL REDUCED COST VECTOR RC.
C     IF A FAVORABLE X IS KNOWN, THEN IT CAN BE PASSED, TOGETHER
C     WITH THE CORRESPONDING ARRAYS U AND DFCT, TO THIS ROUTINE
C     DIRECTLY. THIS, HOWEVER, REQUIRES THAT THE CAPACITY
C     TIGHTENING PORTION AND THE FLOW INITIALIZATION PORTION
C     OF THIS ROUTINE (UP TO LINE LABELED 90) BE SKIPPED.
C
C  NOTE 3 -

```

C ALL PROBLEM DATA SHOULD BE LESS THAN LARGE IN MAGNITUDE,
C AND LARGE SHOULD BE LESS THAN, SAY, 1/4 THE LARGEST INTEGER*4
C OF THE MACHINE USED. THIS WILL GUARD PRIMARILY AGAINST
C OVERFLOW IN UNCAPACITATED PROBLEMS WHERE THE ARC
CAPACITIES
C ARE TAKEN FINITE BUT VERY LARGE. NOTE, HOWEVER, THAT AS IN
C ALL CODES OPERATING WITH INTEGERS, OVERFLOW MAY OCCUR IF
SOME
C OF THE PROBLEM DATA TAKES VERY LARGE VALUES.
C
C NOTE 4 -
C EACH COMMON BLOCK CONTAINS JUST ONE ARRAY, SO THE ARRAYS
IN RELAX4
C CAN BE DIMENSIONED TO 1 AND TAKE THEIR DIMENSION FROM THE
C MAIN CALLING ROUTINE. WITH THIS TRICK, RELAX4 NEED NOT BE
RECOMPILED
C IF THE ARRAY DIMENSIONS IN THE CALLING ROUTINE CHANGE.
C IF YOUR FORTRAN COMPILER DOES NOT SUPPORT THIS FEATURE,
THEN
C CHANGE THE DIMENSION OF ALL THE ARRAYS TO BE THE SAME AS
THE ONES
C DECLARED IN THE MAIN CALLING PROGRAM.
C
C NOTE 5 -
C DDPOS AND DDNEG ARE ARRAYS THAT GIVE THE DIRECTIONAL
DERIVATIVES FOR
C ALL POSITIVE AND NEGATIVE SINGLE-NODE PRICE CHANGES. THESE
ARE USED
C ONLY IN PHASE II OF THE INITIALIZATION PROCEDURE, BEFORE THE
C LINKED LIST OF BALANCED ARCS COMES TO PLAY. THEREFORE, TO
REDUCE
C STORAGE, THEY ARE EQUIVALENCE TO TFSTOU AND TFSTIN,
C WHICH ARE OF THE SAME SIZE (NUMBER OF NODES) AND ARE USED
C ONLY AFTER THE TREE COMES INTO USE.
C
C-----
C
C INITIALIZATION PHASE I
C
C IN THIS PHASE, WE REDUCE THE ARC CAPACITIES BY AS MUCH AS
C POSSIBLE WITHOUT CHANGING THE PROBLEM;
C THEN WE SET THE INITIAL FLOW ARRAY X, TOGETHER WITH
C THE CORRESPONDING ARRAYS U AND DFCT.
C
C THIS PHASE AND PHASE II (FROM HERE UP TO LINE LABELED 90)

```

C CAN BE SKIPPED (BY SETTING REPEAT TO .TRUE.) IF THE CALLING
PROGRAM
C PLACES IN COMMON USER-CHOSEN VALUES FOR THE ARC FLOWS, THE
RESIDUAL ARC
C CAPACITIES, AND THE NODAL DEFICITS. WHEN THIS IS DONE,
C IT IS CRITICAL THAT THE FLOW AND THE REDUCED COST FOR EACH
ARC
C SATISFY COMPLEMENTARY SLACKNESS
C AND THE DFCT ARRAY PROPERLY CORRESPOND TO THE INITIAL
ARC/FLOWS.
C
    IF (REPEAT) GO TO 90
C
    DO 10 NODE=1,N

        NODE_DEF=DFCT(NODE)
        DDPOS(NODE)=NODE_DEF
        DDNEG(NODE)=-NODE_DEF
        MAXCAP=0
        SCAPOU=0
        ARC=FOU(NODE)
11   IF (ARC.GT.0) THEN
        IF (SCAPOU.LE.LARGE-U(ARC)) THEN
            SCAPOU=SCAPOU+U(ARC)
        ELSE
            GO TO 10
        END IF
        ARC=NXTOU(ARC)
        GO TO 11
    END IF
    IF (SCAPOU.LE.LARGE-NODE_DEF) THEN
        CAPOUT=SCAPOU+NODE_DEF
    ELSE
        GO TO 10
    END IF
    IF (CAPOUT.LT.0) THEN
C
C PROBLEM IS INFEASIBLE - EXIT
C
        PRINT*, 'EXIT DURING CAPACITY ADJUSTMENT'
        PRINT*, 'EXOGENOUS FLOW INTO NODE', NODE,
$      ' EXCEEDS OUT CAPACITY'
        CALL PRINTFLOWS(NODE)
        GO TO 4400
    END IF
C

```

```

SCAPIN=0
ARC=FIN(NODE)
12 IF (ARC.GT.0) THEN
    U(ARC)=MIN0(U(ARC),CAPOUT)
    IF (MAXCAP.LT.U(ARC)) MAXCAP=U(ARC)
    IF (SCAPIN.LE.LARGE-U(ARC)) THEN
        SCAPIN=SCAPIN+U(ARC)
    ELSE
        GO TO 10
    END IF
    ARC=NXTIN(ARC)
    GO TO 12
END IF
IF (SCAPIN.LE.LARGE+NODE_DEF) THEN
    CAPIN=SCAPIN-NODE_DEF
ELSE
    GO TO 10
END IF
IF (CAPIN.LT.0) THEN
C
C PROBLEM IS INFEASIBLE - EXIT
C
    PRINT*, 'EXIT DURING CAPACITY ADJUSTMENT'
    PRINT*, 'EXOGENOUS FLOW OUT OF NODE', NODE,
$  'EXCEEDS IN CAPACITY'
    CALL PRINTFLOWS(NODE)
    GO TO 4400
END IF
C
ARC=FOU(NODE)
15 IF (ARC.GT.0) THEN
    U(ARC)=MIN0(U(ARC),CAPIN)
    ARC=NXTOU(ARC)
    GO TO 15
END IF
10 CONTINUE
C
C -----
C
C INITIALIZATION PHASE II
C
C IN THIS PHASE, WE INITIALIZE THE PRICES AND FLOWS BY EITHER
CALLING
C THE ROUTINE AUCTION OR BY PERFORMING ONLY SINGLE NODE
(COORDINATE)
C RELAXATION ITERATIONS.

```

```

C
IF (CRASH.EQ.1) THEN
  NSP=0
  CALL AUCTION
  GO TO 70
END IF
C
C  INITIALIZE THE ARC FLOWS TO SATISFY COMPLEMENTARY
SLACKNESS WITH THE
C  PRICES. U(ARC) IS THE RESIDUAL CAPACITY OF ARC, AND X(ARC) IS
THE FLOW.
C  THESE TWO ALWAYS ADD UP TO THE TOTAL CAPACITY FOR ARC.
C  ALSO COMPUTE THE DIRECTIONAL DERIVATIVES FOR EACH
COORDINATE
C  AND COMPUTE THE ACTUAL DEFICITS.
C
DO 20 ARC=1,NA
  X(ARC) = 0
  IF (RC(ARC).LE. 0) THEN
    T = U(ARC)
    T1 = STARTN(ARC)
    T2 = ENDN(ARC)
    DDPOS(T1) = DDPOS(T1) + T
    DDNEG(T2) = DDNEG(T2) + T
    IF (RC(ARC).LT. 0) THEN
      X(ARC) = T
      U(ARC) = 0
      DFCT(T1) = DFCT(T1) + T
      DFCT(T2) = DFCT(T2) - T
      DDNEG(T1) = DDNEG(T1) - T
      DDPOS(T2) = DDPOS(T2) - T
    END IF
  END IF
20 CONTINUE
C
C  MAKE 2 OR 3 PASSES THROUGH ALL NODES, PERFORMING ONLY
C  SINGLE NODE RELAXATION ITERATIONS. THE NUMBER OF
C  PASSES DEPENDS ON THE DENSITY OF THE NETWORK
C
IF (NA.GT.N*10) THEN
  NUMPASSES=2
ELSE
  NUMPASSES=3
END IF
C
DO 30 PASSES = 1,NUMPASSES

```

```

DO 40 NODE=1,N

IF (DFCT(NODE).EQ. 0) GO TO 40

IF (DDPOS(NODE).LE. 0) THEN
C
C COMPUTE DELPRC, THE STEPSIZE TO THE NEXT BREAKPOINT
C IN THE DUAL COST AS THE PRICE OF NODE IS INCREASED.
C [SINCE THE REDUCED COST OF ALL OUTGOING (RESP.,
C INCOMING) ARCS WILL DECREASE (RESP., INCREASE) AS
C THE PRICE OF NODE IS INCREASED, THE NEXT BREAKPOINT IS
C THE MINIMUM OF THE POSITIVE REDUCED COST ON OUTGOING
C ARCS AND OF THE NEGATIVE REDUCED COST ON INCOMING ARCS.]
C

DELPRC = LARGE
ARC = FOU(NODE)
51 IF (ARC.GT.0) THEN
    TRC = RC(ARC)
    IF ((TRC.GT. 0).AND.(TRC.LT.DELPRC)) THEN
        DELPRC = TRC
    END IF
    ARC = NXTOU(ARC)
    GOTO 51
END IF
ARC = FIN(NODE)
52 IF (ARC.GT.0) THEN
    TRC = RC(ARC)
    IF ((TRC.LT.0).AND.(TRC.GT.-DELPRC)) THEN
        DELPRC = -TRC
    END IF
    ARC = NXTIN(ARC)
    GOTO 52
END IF
C
C IF NO BREAKPOINT IS LEFT AND DUAL ASCENT IS STILL
C POSSIBLE, THE PROBLEM IS INFEASIBLE.
C

IF (DELPRC.GE.LARGE) THEN
    IF (DDPOS(NODE).EQ.0) GOTO 40
    GOTO 4400
END IF
C
C DELPRC IS THE STEPSIZE TO NEXT BREAKPOINT. INCREASE
C PRICE OF NODE BY DELPRC AND COMPUTE THE STEPSIZE TO
C THE NEXT BREAKPOINT IN THE DUAL COST.

```

```

C
53   NXTBRK = LARGE
C
C   LOOK AT ALL ARCS OUT OF NODE.
C
      ARC = FOU(NODE)
54   IF (ARC.GT.0) THEN
        TRC = RC(ARC)
        IF (TRC .EQ. 0) THEN
          T1 = ENDN(ARC)
          T = U(ARC)
          IF (T.GT.0) THEN
            DFCT(NODE) = DFCT(NODE) + T
            DFCT(T1) = DFCT(T1) - T
            X(ARC) = T
            U(ARC) = 0
          ELSE
            T = X(ARC)
          END IF
          DDNEG(NODE) = DDNEG(NODE) - T
          DDPOS(T1) = DDPOS(T1) - T
        END IF
C
C   DECREASE THE REDUCED COST ON ALL OUTGOING ARCS.
C
      TRC = TRC - DELPRC
      IF ((TRC.GT.0).AND.(TRC.LT.NXTBRK)) THEN
        NXTBRK = TRC
      ELSE IF (TRC.EQ.0) THEN
C
C   ARC GOES FROM INACTIVE TO BALANCED. UPDATE THE
C   RATE OF DUAL ASCENT AT NODE AND AT ITS NEIGHBOR.
C
        DDPOS(NODE) = DDPOS(NODE) + U(ARC)
        DDNEG(ENDN(ARC)) = DDNEG(ENDN(ARC)) + U(ARC)
      END IF
      RC(ARC) = TRC
      ARC = NXTOU(ARC)
      GOTO 54
    END IF
C
C   LOOK AT ALL ARCS INTO NODE.
C
      ARC = FIN(NODE)
55   IF (ARC.GT.0) THEN
        TRC = RC(ARC)

```

```

IF (TRC.EQ.0) THEN
    T1 = STARTN(ARC)
    T = X(ARC)
    IF (T.GT.0) THEN
        DFCT(NODE) = DFCT(NODE) + T
        DFCT(T1) = DFCT(T1) - T
        U(ARC) = T
        X(ARC) = 0
    ELSE
        T = U(ARC)
    END IF
    DDPOS(T1) = DDPOS(T1) - T
    DDNEG(NODE) = DDNEG(NODE) - T
END IF

C
C INCREASE THE REDUCED COST ON ALL INCOMING ARCS.
C

    TRC = TRC + DELPRC
    IF ((TRC.LT.0).AND.(TRC.GT.-NXTBRK)) THEN
        NXTBRK = -TRC
    ELSE IF (TRC.EQ.0) THEN
        C
        C ARC GOES FROM ACTIVE TO BALANCED. UPDATE THE
        C RATE OF DUAL ASCENT AT NODE AND AT ITS NEIGHBOR.
        C

        DDNEG(STARTN(ARC)) = DDNEG(STARTN(ARC)) + X(ARC)
        DDPOS(NODE) = DDPOS(NODE) + X(ARC)
    END IF
    RC(ARC) = TRC
    ARC = NXTIN(ARC)
    GOTO 55
END IF

C
C IF PRICE OF NODE CAN BE INCREASED FURTHER WITHOUT
DECREASING
C THE DUAL COST (EVEN IF THE DUAL COST DOESNT INCREASE),
C RETURN TO INCREASE THE PRICE FURTHER.
C

    IF ((DDPOS(NODE).LE.0).AND.(NXTBRK.LT.LARGE)) THEN
        DELPRC = NXTBRK
        GOTO 53
    END IF

    ELSE IF (DDNEG(NODE).LE.0) THEN
C
C COMPUTE DELPRC, THE STEPSIZE TO THE NEXT BREAKPOINT

```

```

C IN THE DUAL COST AS THE PRICE OF NODE IS DECREASED.
C [SINCE THE REDUCED COST OF ALL OUTGOING (RESP.,
C INCOMING) ARCS WILL INCREASE (RESP., DECREASE) AS
C THE PRICE OF NODE IS DECREASED, THE NEXT BREAKPOINT IS
C THE MINIMUM OF THE NEGATIVE REDUCED COST ON OUTGOING
C ARCS AND OF THE POSITIVE REDUCED COST ON INCOMING ARCS.]
C

C DELPRC = LARGE
C ARC = FOU(NODE)
61 IF (ARC.GT.0) THEN
    TRC = RC(ARC)
    IF ((TRC.LT.0).AND.(TRC.GT.-DELPRC)) THEN
        DELPRC = -TRC
    ENDIF
    ARC = NXTOU(ARC)
    GOTO 61
END IF
ARC = FIN(NODE)
62 IF (ARC.GT.0) THEN
    TRC = RC(ARC)
    IF ((TRC.GT.0).AND.(TRC.LT.DELPRC)) THEN
        DELPRC = TRC
    END IF
    ARC = NXTIN(ARC)
    GOTO 62
END IF

C
C IF NO BREAKPOINT IS LEFT AND DUAL ASCENT IS STILL
C POSSIBLE, THE PROBLEM IS INFEASIBLE.
C

C IF (DELPRC.EQ.LARGE) THEN
    IF (DDNEG(NODE).EQ.0) GOTO 40
    GOTO 4400
END IF

C
C DELPRC IS THE STEPSIZE TO NEXT BREAKPOINT. DECREASE
C PRICE OF NODE BY DELPRC AND COMPUTE THE STEPSIZE TO
C THE NEXT BREAKPOINT IN THE DUAL COST.
C

63 NXTBRK = LARGE
C
C LOOK AT ALL ARCS OUT OF NODE.
C

C ARC = FOU(NODE)
64 IF (ARC.GT.0) THEN
    TRC = RC(ARC)

```

```

IF (TRC.EQ.0) THEN
  T1 = ENDN(ARC)
  T = X(ARC)
  IF (T.GT.0) THEN
    DFCT(NODE) = DFCT(NODE) - T
    DFCT(T1) = DFCT(T1) + T
    U(ARC) = T
    X(ARC) = 0
  ELSE
    T = U(ARC)
  END IF
  DDPOS(NODE) = DDPOS(NODE) - T
  DDNEG(T1) = DDNEG(T1) - T
END IF

C
C INCREASE THE REDUCED COST ON ALL OUTGOING ARCS.
C
  TRC = TRC + DELPRC
  IF ((TRC.LT.0).AND.(TRC.GT.-NXTBRK)) THEN
    NXTBRK = -TRC
  ELSE IF (TRC.EQ.0) THEN
    C
    C ARC GOES FROM ACTIVE TO BALANCED. UPDATE THE
    C RATE OF DUAL ASCENT AT NODE AND AT ITS NEIGHBOR.
    C
    DDNEG(NODE) = DDNEG(NODE) + X(ARC)
    DDPOS(ENDN(ARC)) = DDPOS(ENDN(ARC)) + X(ARC)
  END IF
  RC(ARC) = TRC
  ARC = NXTOU(ARC)
  GOTO 64
END IF

C
C LOOK AT ALL ARCS INTO NODE.
C
  ARC = FIN(NODE)
65  IF (ARC.GT.0) THEN
    TRC = RC(ARC)
    IF (TRC.EQ.0) THEN
      T1 = STARTN(ARC)
      T = U(ARC)
      IF (T.GT.0) THEN
        DFCT(NODE) = DFCT(NODE) - T
        DFCT(T1) = DFCT(T1) + T
        X(ARC) = T
        U(ARC) = 0
      END IF
    END IF
  END IF

```

```

        ELSE
          T = X(ARC)
        END IF
        DDNEG(T1) = DDNEG(T1) - T
        DDPOS(NODE) = DDPOS(NODE) - T
      END IF

C
C  DECREASE THE REDUCED COST ON ALL INCOMING ARCS.
C
      TRC = TRC - DELPRC
      IF ((TRC.GT.0).AND.(TRC.LT.NXTBRK)) THEN
        NXTBRK = TRC
      ELSE IF (TRC.EQ.0) THEN
C
C  ARC GOES FROM INACTIVE TO BALANCED. UPDATE THE
C  RATE OF DUAL ASCENT AT NODE AND AT ITS NEIGHBOR.
C
        DDPOS(STARTN(ARC)) = DDPOS(STARTN(ARC)) + U(ARC)
        DDNEG(NODE) = DDNEG(NODE) + U(ARC)
      END IF
      RC(ARC) = TRC
      ARC = NXTIN(ARC)
      GOTO 65
    END IF

C
C  IF PRICE OF NODE CAN BE DECREASED FURTHER WITHOUT
DECREASING
C  THE DUAL COST (EVEN IF THE DUAL COST DOESNT INCREASE),
C  RETURN TO DECREASE THE PRICE FURTHER.
C
      IF ((DDNEG(NODE).LE.0).AND.(NXTBRK.LT.LARGE)) THEN
        DELPRC = NXTBRK
        GOTO 63
      END IF

    END IF

40  CONTINUE

30  CONTINUE
C
C
70  CONTINUE
C
C  READ TIME FOR INITIALIZATION
C

```

```

C   TIME1 = LONG(362)/60.0 - TIME0
    TIME1 = SECNDS(TIME0)
C
C-----
C
C   C INITIALIZE TREE DATA STRUCTURE.

DO 80 I=1,N
  TFSTOU(I)=0
  TFSTIN(I)=0
80  CONTINUE
DO 81 I=1,NA
  TNXTIN(I)=-1
  TNXTOU(I)=-1
  IF (RC(I).EQ.0) THEN
    TNXTOU(I)=TFSTOU(STARTN(I))
    TFSTOU(STARTN(I))=I
    TNXTIN(I)=TFSTIN(ENDN(I))
    TFSTIN(ENDN(I))=I
  END IF
81  CONTINUE

C
C   C INITIALIZE OTHER VARIABLES.
C
90  FEASBL=.TRUE.
  ITER=0
  NMULTINODE=0
  NUM_AUGM=0
  NUM_ASCNT=0
  NUM_PASSES=0
  NUMNZ=N
  NUMNZ_NEW=0
  SWITCH=.FALSE.
  DO 91 I=1,N
    MARK(I)=.FALSE.
    SCAN(I)=.FALSE.
91  CONTINUE
  NLABEL=0
C
C   C RELAX4 USES AN ADAPTIVE STRATEGY TO DECIDE WHETHER TO
C   C CONTINUE THE SCANNING PROCESS AFTER A MULTINODE PRICE
C   C CHANGE.
C   C THE THRESHOLD PARAMETER TP AND TS THAT CONTROL
C   C THIS STRATEGY ARE SET IN THE NEXT TWO LINES.
C

```

```

TP=10
TS=INT(N/15)
C
C   INITIALIZE THE QUEUE OF NODES WITH NONZERO DEFICIT
C
DO 92 NODE=1,N-1
  NXTQUEUE(NODE)=NODE+1
92 CONTINUE
NXTQUEUE(N)=1
NODE=N
LASTQUEUE=N
C
C-----.
C
C   START THE RELAXATION ALGORITHM.
C
100 CONTINUE
C
C   CODE FOR ADVANCING THE QUEUE OF NONZERO DEFICIT NODES
C
PREVNODE=NODE
NODE=NXTQUEUE(NODE)
DEFCIT=DFCT(NODE)
IF (NODE.EQ.LASTQUEUE) THEN
  NUMNZ=NUMNZ_NEW
  NUMNZ_NEW=0
  LASTQUEUE=PREVNODE
  NUM_PASSES=NUM_PASSES+1
END IF
C
C   CODE FOR DELETING A NODE FROM THE QUEUE
C
IF (DEFCIT.EQ.0) THEN
  NXTNODE=NXTQUEUE(NODE)
  IF (NODE.EQ.NXTNODE) THEN
    RETURN
  ELSE
    NXTQUEUE(PREVNODE)=NXTNODE
    NXTQUEUE(NODE)=0
    NODE=NXTNODE
    GO TO 100
  END IF
ELSE
  POSIT = (DEFCIT.GT.0)
END IF
C

```

```

ITER=ITER+1
NUMNZ_NEW=NUMNZ_NEW+1
C
IF (POSIT) THEN
C
C ATTEMPT A SINGLE NODE ITERATION FROM NODE WITH POSITIVE
DEFICIT
C
PCHANGE = .FALSE.
INDEF=DEFCIT
DELX=0
NB=0
C
C CHECK OUTGOING (PROBABLY) BALANCED ARCS FROM NODE.
C
ARC=TFSTOU(NODE)
4500 IF (ARC.GT.0) THEN
  IF ((RC(ARC).EQ.0).AND.(X(ARC).GT.0)) THEN
    DELX = DELX + X(ARC)
    NB = NB + 1
    SAVE(NB) = ARC
  ENDIF
  ARC = TNXTOU(ARC)
  GOTO 4500
END IF
C
C CHECK INCOMING ARCS.
C
ARC = TFSTIN(NODE)
4501 IF (ARC.GT.0) THEN
  IF ((RC(ARC).EQ.0).AND.(U(ARC).GT.0)) THEN
    DELX = DELX + U(ARC)
    NB = NB + 1
    SAVE(NB) = -ARC
  ENDIF
  ARC = TNXTIN(ARC)
  GOTO 4501
END IF
C
C END OF INITIAL NODE SCAN.
C
4018 CONTINUE
C
C IF NO PRICE CHANGE IS POSSIBLE, EXIT.
C
IF (DELX.GT.DEFCIT) THEN

```

```

    QUIT = (DEFICIT .LT. INDEF)
    GO TO 4016
    END IF
C
C   RELAX4 SEARCHES ALONG THE ASCENT DIRECTION FOR THE
C   BEST PRICE BY CHECKING THE SLOPE OF THE DUAL COST
C   AT SUCCESSIVE BREAK POINTS. FIRST, WE
C   COMPUTE THE DISTANCE TO THE NEXT BREAK POINT.
C
    DELPRC = LARGE
    ARC = FOU(NODE)
4502 IF (ARC .GT. 0) THEN
    RDCOST = RC(ARC)
    IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC)) THEN
        DELPRC = -RDCOST
    END IF
    ARC = NXTOU(ARC)
    GOTO 4502
END IF
    ARC = FIN(NODE)
4503 IF (ARC .GT. 0) THEN
    RDCOST = RC(ARC)
    IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC)) THEN
        DELPRC = RDCOST
    END IF
    ARC = NXTIN(ARC)
    GOTO 4503
END IF
C
C   CHECK IF PROBLEM IS INFEASIBLE.
C
    IF ((DELX.LT.DEFCIT).AND.(DELPRC.EQ.LARGE)) THEN
C
C   THE DUAL COST CAN BE DECREASED WITHOUT BOUND.
C
        GO TO 4400
    END IF
C
C   SKIP FLOW ADJUSTMENT IF THERE IS NO FLOW TO MODIFY.
C
    IF (DELX.EQ.0) GO TO 4014
C
C   ADJUST THE FLOW ON THE BALANCED ARCS INCIDENT TO NODE TO
C   MAINTAIN COMPLEMENTARY SLACKNESS AFTER THE PRICE CHANGE.
C
    DO 4013 J=1,NB

```

```

ARC=SAVE(J)
IF (ARC.GT.0) THEN
  NODE2=ENDN(ARC)
  T1=X(ARC)
  DFCT(NODE2)=DFCT(NODE2)+T1
  IF (NXTQUEUE(NODE2).EQ.0) THEN
    NXTQUEUE(PREVNODE)=NODE2
    NXTQUEUE(NODE2)=NODE
    PREVNODE=NODE2
  END IF
  U(ARC)=U(ARC)+T1
  X(ARC)=0
ELSE
  NARC=-ARC
  NODE2=STARTN(NARC)
  T1=U(NARC)
  DFCT(NODE2)=DFCT(NODE2)+T1
  IF (NXTQUEUE(NODE2).EQ.0) THEN
    NXTQUEUE(PREVNODE)=NODE2
    NXTQUEUE(NODE2)=NODE
    PREVNODE=NODE2
  END IF
  X(NARC)=X(NARC)+T1
  U(NARC)=0
END IF
4013 CONTINUE
  DEFICIT=DEFICIT-DELX
4014 IF (DELPRC.EQ.LARGE) THEN
  QUIT=.TRUE.
  GO TO 4019
END IF
C
C  NODE CORRESPONDS TO A DUAL ASCENT DIRECTION. DECREASE
C  THE PRICE OF NODE BY DELPRC AND COMPUTE THE STEPSIZE TO THE
C  NEXT BREAKPOINT IN THE DUAL COST.
C
NB=0
PCHANGE = .TRUE.
DP=DELPRC
DELPRC=LARGE
DELX=0
ARC=FOU(NODE)
4504 IF (ARC.GT.0) THEN
  RDCOST=RC(ARC)+DP
  RC(ARC)=RDCOST
  IF (RDCOST.EQ.0) THEN

```

```

NB=NB+1
SAVE(NB)=ARC
DELX=DELX+X(ARC)
END IF
IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC)) DELPRC=-RDCOST
ARC=NXTOU(ARC)
GOTO 4504
END IF
ARC=FIN(NODE)
4505 IF (ARC.GT.0) THEN
RDCOST=RC(ARC)-DP
RC(ARC)=RDCOST
IF (RDCOST.EQ.0) THEN
NB=NB+1
SAVE(NB)=-ARC
DELX=DELX+U(ARC)
END IF
IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC)) DELPRC=RDCOST
ARC=NXTIN(ARC)
GOTO 4505
END IF
C
C RETURN TO CHECK IF ANOTHER PRICE CHANGE IS POSSIBLE.
C
C GO TO 4018
C
C PERFORM FLOW AUGMENTATION AT NODE.
C
4016 DO 4011 J=1,NB
ARC=SAVE(J)
IF (ARC.GT.0) THEN
C
C ARC IS AN OUTGOING ARC FROM NODE.
C
NODE2=ENDN(ARC)
T1=DFCT(NODE2)
IF (T1.LT.0) THEN
C
C DECREASE THE TOTAL DEFICIT BY DECREASING FLOW OF ARC.
C
QUIT=.TRUE.
T2=X(ARC)
DX=MIN0(DEFCIT,-T1,T2)
DEFCIT=DEFCIT-DX
DFCT(NODE2)=T1+DX
IF (NXTQUEUE(NODE2).EQ.0) THEN

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```

NXTQUEUE(PREVNODE)=NODE2
NXTQUEUE(NODE2)=NODE
PREVNODE=NODE2
END IF
X(ARC)=T2-DX
U(ARC)=U(ARC)+DX
IF (DEFCIT.EQ.0) GO TO 4019
END IF
ELSE
C
C -ARC IS AN INCOMING ARC TO NODE.
C
NARC=-ARC
NODE2=STARTN(NARC)
T1=DFCT(NODE2)
IF (T1.LT.0) THEN
C
C DECREASE THE TOTAL DEFICIT BY INCREASING FLOW OF -ARC.
C
QUIT=.TRUE.
T2=U(NARC)
DX=MIN0(DEFCIT,-T1,T2)
DEFCIT=DEFCIT-DX
DFCT(NODE2)=T1+DX
IF (NXTQUEUE(NODE2).EQ.0) THEN
NXTQUEUE(PREVNODE)=NODE2
NXTQUEUE(NODE2)=NODE
PREVNODE=NODE2
END IF
X(NARC)=X(NARC)+DX
U(NARC)=T2-DX
IF (DEFCIT.EQ.0) GO TO 4019
END IF
END IF
4011 CONTINUE
4019 DFCT(NODE)=DEFCIT
C
C RECONSTRUCT THE LINKED LIST OF BALANCE ARCS INCIDENT TO
THIS NODE.
C FOR EACH ADJACENT NODE, WE ADD ANY NEWLY BALANCED ARCS
C TO THE LIST, BUT DO NOT BOTHER REMOVING FORMERLY BALANCED
ONES
C (THEY WILL BE REMOVED THE NEXT TIME EACH ADJACENT NODE IS
SCANNED).
C
IF (PCHANGE) THEN

```

```

ARC = TFSTOU(NODE)
TFSTOU(NODE) = 0
4506 IF (ARC .GT. 0) THEN
    NXTARC = TNXTOU(ARC)
    TNXTOU(ARC) = -1
    ARC = NXTARC
    GOTO 4506
END IF
ARC = TFSTIN(NODE)
TFSTIN(NODE) = 0
4507 IF (ARC .GT. 0) THEN
    NXTARC = TNXTIN(ARC)
    TNXTIN(ARC) = -1
    ARC = NXTARC
    GOTO 4507
END IF
C
C NOW ADD THE CURRENTLY BALANCED ARCS TO THE LIST FOR THIS
NODE
C (WHICH IS NOW EMPTY), AND THE APPROPRIATE ADJACENT ONES.
C
DO 4508 J=1,NB
ARC = SAVE(J)
IF (ARC.LE.0) ARC=-ARC
IF (TNXTOU(ARC) .LT. 0) THEN
    TNXTOU(ARC) = TFSTOU(STARTN(ARC))
    TFSTOU(STARTN(ARC)) = ARC
END IF
IF (TNXTIN(ARC) .LT. 0) THEN
    TNXTIN(ARC) = TFSTIN(ENDN(ARC))
    TFSTIN(ENDN(ARC)) = ARC
END IF
4508 CONTINUE

END IF
C
C END OF SINGLE NODE ITERATION FOR POSITIVE DEFICIT NODE.
C
ELSE
C
C ATTEMPT A SINGLE NODE ITERATION FROM NODE WITH NEGATIVE
DEFICIT
C
PCHANGE = .FALSE.
DEFCIT=-DEFCIT
INDEF=DEFCIT

```

```

DELX=0
NB=0
C
ARC = TFSTIN(NODE)
4509 IF (ARC .GT. 0) THEN
  IF ((RC(ARC) .EQ. 0) .AND. (X(ARC) .GT. 0)) THEN
    DELX = DELX + X(ARC)
    NB = NB + 1
    SAVE(NB) = ARC
  END IF
  ARC = TNXTIN(ARC)
  GOTO 4509
END IF
ARC=TFSTOU(NODE)
4510 IF (ARC .GT. 0) THEN
  IF ((RC(ARC) .EQ. 0) .AND. (U(ARC) .GT. 0)) THEN
    DELX = DELX + U(ARC)
    NB = NB + 1
    SAVE(NB) = -ARC
  END IF
  ARC = TNXTOU(ARC)
  GOTO 4510
END IF
C
4028 CONTINUE
IF (DELX.GE.DEFCIT) THEN
  QUIT = (DEFCIT .LT. INDEF)
  GO TO 4026
END IF
C
C   COMPUTE DISTANCE TO NEXT BREAKPOINT.
C
DELPRC = LARGE
ARC = FIN(NODE)
4511 IF (ARC .GT. 0) THEN
  RDCOST = RC(ARC)
  IF ((RDCOST .LT. 0) .AND. (RDCOST.GT.-DELPRC)) THEN
    DELPRC = -RDCOST
  END IF
  ARC = NXTIN(ARC)
  GOTO 4511
END IF
ARC = FOU(NODE)
4512 IF (ARC .GT. 0) THEN
  RDCOST = RC(ARC)
  IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC)) THEN

```

```

      DELPRC = RDCOST
END IF
ARC = NXTOU(ARC)
GOTO 4512
END IF
C
C   CHECK IF PROBLEM IS INFEASIBLE.
C
IF ((DELX.LT.DEFCIT).AND.(DELPRC.EQ.LARGE)) THEN
  GO TO 4400
END IF
IF (DELX.EQ.0) GO TO 4024
C
C   FLOW AUGMENTATION IS POSSIBLE.
C
DO 4023 J=1,NB
  ARC=SAVE(J)
  IF (ARC.GT.0) THEN
    NODE2=STARTN(ARC)
    T1=X(ARC)
    DFCT(NODE2)=DFCT(NODE2)-T1
    IF (NXTQUEUE(NODE2).EQ.0) THEN
      NXTQUEUE(PREVNODE)=NODE2
      NXTQUEUE(NODE2)=NODE
      PREVNODE=NODE2
    END IF
    U(ARC)=U(ARC)+T1
    X(ARC)=0
  ELSE
    NARC=-ARC
    NODE2=ENDN(NARC)
    T1=U(NARC)
    DFCT(NODE2)=DFCT(NODE2)-T1
    IF (NXTQUEUE(NODE2).EQ.0) THEN
      NXTQUEUE(PREVNODE)=NODE2
      NXTQUEUE(NODE2)=NODE
      PREVNODE=NODE2
    END IF
    X(NARC)=X(NARC)+T1
    U(NARC)=0
  END IF
4023 CONTINUE
DEFCIT=DEFCIT-DELX
4024 IF (DELPRC.EQ.LARGE) THEN
  QUIT=.TRUE.
  GO TO 4029

```

```

END IF
C
C PRICE INCREASE AT NODE IS POSSIBLE.
C
NB=0
PCHANGE = .TRUE.
DP=DELPRC
DELPRC=LARGE
DELX=0
ARC=FIN(NODE)
4513 IF (ARC.GT.0) THEN
    RDCOST=RC(ARC)+DP
    RC(ARC)=RDCOST
    IF (RDCOST.EQ.0) THEN
        NB=NB+1
        SAVE(NB)=ARC
        DELX=DELX+X(ARC)
    END IF
    IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC)) DELPRC=-RDCOST
    ARC=NXTIN(ARC)
    GOTO 4513
END IF
ARC=FOU(NODE)
4514 IF (ARC.GT.0) THEN
    RDCOST=RC(ARC)-DP
    RC(ARC)=RDCOST
    IF (RDCOST.EQ.0) THEN
        NB=NB+1
        SAVE(NB)=-ARC
        DELX=DELX+U(ARC)
    END IF
    IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC)) DELPRC=RDCOST
    ARC=NXTOU(ARC)
    GOTO 4514
END IF
GO TO 4028
C
C PERFORM FLOW AUGMENTATION AT NODE.
C
4026 DO 4021 J=1,NB
    ARC=SAVE(J)
    IF (ARC.GT.0) THEN
C
C ARC IS AN INCOMING ARC TO NODE.
C
    NODE2=STARTN(ARC)

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```

T1=DFCT(NODE2)
IF (T1.GT.0) THEN
  QUIT=.TRUE.
  T2=X(ARC)
  DX=MIN0(DEFCIT,T1,T2)
  DEFCIT=DEFCIT-DX
  DFCT(NODE2)=T1-DX
  IF (NXTQUEUE(NODE2).EQ.0) THEN
    NXTQUEUE(PREVNODE)=NODE2
    NXTQUEUE(NODE2)=NODE
    PREVNODE=NODE2
  END IF
  X(ARC)=T2-DX
  U(ARC)=U(ARC)+DX
  IF (DEFCIT.EQ.0) GO TO 4029
END IF
ELSE
C
C -ARC IS AN OUTGOING ARC FROM NODE.
C
  NARC=-ARC
  NODE2=ENDN(NARC)
  T1=DFCT(NODE2)
  IF (T1.GT.0) THEN
    QUIT=.TRUE.
    T2=U(NARC)
    DX=MIN0(DEFCIT,T1,T2)
    DEFCIT=DEFCIT-DX
    DFCT(NODE2)=T1-DX
    IF (NXTQUEUE(NODE2).EQ.0) THEN
      NXTQUEUE(PREVNODE)=NODE2
      NXTQUEUE(NODE2)=NODE
      PREVNODE=NODE2
    END IF
    X(NARC)=X(NARC)+DX
    U(NARC)=T2-DX
    IF (DEFCIT.EQ.0) GO TO 4029
  END IF
END IF
4021 CONTINUE
4029 DFCT(NODE)=-DEFCIT
C
C RECONSTRUCT THE LIST OF BALANCED ARCS INCIDENT TO NODE.
C
  IF (PCHANGE) THEN

```

```

ARC = TFSTOU(NODE)
TFSTOU(NODE) = 0
4515 IF (ARC .GT. 0) THEN
    NXTARC = TNXTOU(ARC)
    TNXTOU(ARC) = -1
    ARC = NXTARC
    GOTO 4515
END IF
ARC = TFSTIN(NODE)
TFSTIN(NODE) = 0
4516 IF (ARC .GT. 0) THEN
    NXTARC = TNXTIN(ARC)
    TNXTIN(ARC) = -1
    ARC = NXTARC
    GOTO 4516
END IF
C
C   NOW ADD THE CURRENTLY BALANCED ARCS TO THE LIST FOR THIS
NODE
C   (WHICH IS NOW EMPTY), AND THE APPROPRIATE ADJACENT ONES.
C
DO 4517 J=1,NB
ARC = SAVE(J)
IF (ARC.LE.0) ARC=-ARC
IF (TNXTOU(ARC) .LT. 0) THEN
    TNXTOU(ARC) = TFSTOU(STARTN(ARC))
    TFSTOU(STARTN(ARC)) = ARC
END IF
IF (TNXTIN(ARC) .LT. 0) THEN
    TNXTIN(ARC) = TFSTIN(ENDN(ARC))
    TFSTIN(ENDN(ARC)) = ARC
END IF
4517 CONTINUE

END IF
C
C   END OF SINGLE NODE ITERATION FOR A NEGATIVE DEFICIT NODE.
C
END IF
C
IF (QUIT.OR.(NUM_PASSES.LE.3)) GO TO 100
C
C   DO A MULTINODE ITERATION FROM NODE.
C
NMULTINODE=NMULTINODE+1
C

```

```

C   IF NUMBER OF NONZERO DEFICIT NODES IS SMALL, CONTINUE
C   LABELING UNTIL A FLOW AUGMENTATION IS DONE.
C
C   SWITCH = (NUMNZ.LT.TP)
C
C   UNMARK NODES LABELED EARLIER.
C
C   DO 4090 J=1,NLABEL
      NODE2=LABEL(J)
      MARK(NODE2)=.FALSE.
      SCAN(NODE2)=.FALSE.
4090 CONTINUE
C
C   INITIALIZE LABELING.
C
C   NLABEL=1
      LABEL(1)=NODE
      MARK(NODE)=.TRUE.
      PRDCSR(NODE)=0
C
C   SCAN STARTING NODE.
C
C   SCAN(NODE)=.TRUE.
      NSCAN=1
      DM=DFCT(NODE)
      DELX=0
      DO 4095 J=1,NB
          ARC=SAVE(J)
          IF (ARC.GT.0) THEN
              IF (POSIT) THEN
                  NODE2=ENDN(ARC)
              ELSE
                  NODE2=STARTN(ARC)
              END IF
              IF (.NOT.MARK(NODE2)) THEN
                  NLABEL=NLABEL+1
                  LABEL(NLABEL)=NODE2
                  PRDCSR(NODE2)=ARC
                  MARK(NODE2)=.TRUE.
                  DELX=DELX+X(ARC)
              END IF
          ELSE
              NARC=-ARC
              IF (POSIT) THEN
                  NODE2=STARTN(NARC)
              ELSE

```

```

        NODE2=ENDN(NARC)
    END IF
    IF (.NOT.MARK(NODE2)) THEN
        NLABEL=NLABEL+1
        LABEL(NLABEL)=NODE2
        PRDCSR(NODE2)=ARC
        MARK(NODE2)=.TRUE.
        DELX=DELX+U(NARC)
    END IF
END IF
4095 CONTINUE
C
C   START SCANNING A LABELED BUT UNSCANNED NODE.
C
4120 NSCAN=NSCAN+1
C
C   CHECK TO SEE IF SWITCH NEEDS TO BE SET TO TRUE SO TO
C   CONTINUE SCANNING EVEN AFTER A PRICE CHANGE.
C
        SWITCH = SWITCH .OR.
        $((NSCAN .GT. TS).AND.(NUMNZ.LT.TS))
C
C   SCANNING WILL CONTINUE UNTIL EITHER AN OVERESTIMATE OF THE
RESIDUAL
C   CAPACITY ACROSS THE CUT CORRESPONDING TO THE SCANNED SET
OF NODES (CALLED
C   DELX) EXCEEDS THE ABSOLUTE VALUE OF THE TOTAL DEFICIT OF
THE SCANNED
C   NODES (CALLED DM), OR ELSE AN AUGMENTING PATH IS FOUND.
ARCS THAT ARE
C   IN THE TREE BUT ARE NOT BALANCED ARE REMOVED AS PART OF THE
SCANNING
C   PROCESS.
C
        I=LABEL(NSCAN)
        SCAN(I)=.TRUE.
        NAUGNOD=0
        IF (POSIT) THEN
C
C   SCANNING NODE I IN CASE OF POSITIVE DEFICIT.
C
        PRVARC=0
        ARC = TFSTOU(I)

4518 IF (ARC.GT.0) THEN
C

```

```

C   ARC IS AN OUTGOING ARC FROM NODE.
C
IF (RC(ARC) .EQ. 0) THEN
  IF (X(ARC) .GT. 0) THEN
    NODE2=ENDN(ARC)
    IF (.NOT. MARK(NODE2)) THEN
      C
      C   NODE2 IS NOT LABELED, SO ADD NODE2 TO THE LABELED SET.
      C
      PRDCSR(NODE2)=ARC
      IF (DFCT(NODE2).LT.0) THEN
        NAUGNOD=NAUGNOD+1
        SAVE(NAUGNOD)=NODE2
      END IF
      NLABEL=NLABEL+1
      LABEL(NLABEL)=NODE2
      MARK(NODE2)=.TRUE.
      DELX=DELX+X(ARC)
    END IF
  END IF
  PRVARC = ARC
  ARC = TNXTOU(ARC)
ELSE
  TMPARC = ARC
  ARC = TNXTOU(ARC)
  TNXTOU(TMPARC) = -1
  IF (PRVARC .EQ. 0) THEN
    TFSTOU(I) = ARC
  ELSE
    TNXTOU(PRVARC) = ARC
  END IF
END IF
GOTO 4518
END IF

PRVARC = 0
ARC=TFSTIN(I)
4519 IF (ARC.GT.0) THEN
C
C   ARC IS AN INCOMING ARC INTO NODE.
C
  IF (RC(ARC) .EQ. 0) THEN
    IF (U(ARC) .GT. 0) THEN
      NODE2=STARTN(ARC)
      IF (.NOT. MARK(NODE2)) THEN
        C

```

```

C NODE2 IS NOT LABELED, SO ADD NODE2 TO THE LABELED SET.
C
    PRDCSR(NODE2)=-ARC
    IF (DFCT(NODE2).LT.0) THEN
        NAUGNOD=NAUGNOD+1
        SAVE(NAUGNOD)=NODE2
    END IF
    NLABEL=NLABEL+1
    LABEL(NLABEL)=NODE2
    MARK(NODE2)=.TRUE.
    DELX=DELX+U(ARC)
    END IF
END IF
PRVARC = ARC
ARC = TNXTIN(ARC)
ELSE
    TMPARC = ARC
    ARC = TNXTIN(ARC)
    TNXTIN(TMPARC) = -1
    IF (PRVARC .EQ. 0) THEN
        TFSTIN(I) = ARC
    ELSE
        TNXTIN(PRVARC) = ARC
    END IF
END IF
GOTO 4519
END IF
C
C CORRECT THE RESIDUAL CAPACITY OF THE SCANNED NODE CUT.
C
    ARC=PRDCSR(I)
    IF (ARC.GT.0) THEN
        DELX=DELX-X(ARC)
    ELSE
        DELX=DELX-U(-ARC)
    END IF
C
C END OF SCANNING OF NODE I FOR POSITIVE DEFICIT CASE.
C
C ELSE
C
C SCANNING NODE I FOR NEGATIVE DEFICIT CASE.
C
    PRVARC = 0
    ARC=TFSTIN(I)
4520  IF (ARC.GT.0) THEN

```

```

IF (RC(ARC) .EQ. 0) THEN
  IF (X(ARC) .GT. 0) THEN
    NODE2=STARTN(ARC)
    IF (.NOT. MARK(NODE2)) THEN
      PRDCSR(NODE2)=ARC
      IF (DFCT(NODE2).GT.0) THEN
        NAUGNOD=NAUGNOD+1
        SAVE(NAUGNOD)=NODE2
      END IF
      NLABEL=NLABEL+1
      LABEL(NLABEL)=NODE2
      MARK(NODE2)=.TRUE.
      DELX=DELX+X(ARC)
    END IF
  END IF
  PRVARC = ARC
  ARC = TNXTIN(ARC)
ELSE
  TMPARC = ARC
  ARC = TNXTIN(ARC)
  TNXTIN(TMPARC) = -1
  IF (PRVARC .EQ. 0) THEN
    TFSTIN(I) = ARC
  ELSE
    TNXTIN(PRVARC) = ARC
  END IF
END IF
GOTO 4520
END IF

```

C

```

PRVARC = 0
ARC = TFSTOU(I)
4521 IF (ARC.GT.0) THEN
  IF (RC(ARC) .EQ. 0) THEN
    IF (U(ARC) .GT. 0) THEN
      NODE2=ENDN(ARC)
      IF (.NOT. MARK(NODE2)) THEN
        PRDCSR(NODE2)=-ARC
        IF (DFCT(NODE2).GT.0) THEN
          NAUGNOD=NAUGNOD+1
          SAVE(NAUGNOD)=NODE2
        END IF
        NLABEL=NLABEL+1
        LABEL(NLABEL)=NODE2
        MARK(NODE2)=.TRUE.
        DELX=DELX+U(ARC)
      END IF
    END IF
  END IF

```

```

        END IF
        END IF
        PRVARC = ARC
        ARC = TNXTOU(ARC)
    ELSE
        TMPARC = ARC
        ARC = TNXTOU(ARC)
        TNXTOU(TMPARC) = -1
        IF (PRVARC .EQ. 0) THEN
            TFSTOU(I) = ARC
        ELSE
            TNXTOU(PRVARC) = ARC
        END IF
    END IF
    GOTO 4521
END IF

C
ARC=PRDCSR(I)
IF (ARC.GT.0) THEN
    DELX=DELX-X(ARC)
ELSE
    DELX=DELX-U(-ARC)
END IF
END IF

C
C   ADD DEFICIT OF NODE SCANNED TO DM.
C
DM=DM+DFCT(I)

C
C   CHECK IF THE SET OF SCANNED NODES CORRESPOND
C   TO A DUAL ASCENT DIRECTION; IF YES, PERFORM A
C   PRICE ADJUSTMENT STEP, OTHERWISE CONTINUE LABELING.
C

IF (NSCAN.LT.NLABEL) THEN
    IF (SWITCH) GO TO 4210
    IF ((DELX.GE.DM).AND.(DELX.GE.-DM)) GO TO 4210
END IF

C
C   TRY A PRICE CHANGE.
C   [NOTE THAT SINCE DELX-ABS(DM) IS AN OVERESTIMATE OF ASCENT
SLOPE, WE
C   MAY OCCASIONALLY TRY A DIRECTION THAT IS NOT AN ASCENT
DIRECTION.
C   IN THIS CASE, THE ASCNT ROUTINES RETURN WITH QUIT=.FALSE.,
C   SO WE CONTINUE LABELING NODES.
C

```

```

IF (POSIT) THEN
  CALL ASCNT1(DM,DELX,NLABEL,FEASBL,
$ SWITCH,NSCAN,NODE,PREVNODE)
  NUM_ASCNT=NUM_ASCNT+1
ELSE
  CALL ASCNT2(DM,DELX,NLABEL,FEASBL,
$ SWITCH,NSCAN,NODE,PREVNODE)
  NUM_ASCNT=NUM_ASCNT+1
END IF
IF (.NOT.FEASBL) GO TO 4400
IF (.NOT.SWITCH) GO TO 100
C
C  STORE THOSE NEWLY LABELED NODES TO WHICH FLOW
AUGMENTATION IS POSSIBLE.
C
NAUGNOD=0
DO 530 J=NSCAN+1,NLABEL
  NODE2=LABEL(J)
  IF (POSIT.AND.(DFCT(NODE2).LT.0)) THEN
    NAUGNOD=NAUGNOD+1
    SAVE(NAUGNOD)=NODE2
  ELSE IF ((.NOT.POSIT).AND.(DFCT(NODE2).GT.0)) THEN
    NAUGNOD=NAUGNOD+1
    SAVE(NAUGNOD)=NODE2
  END IF
530 CONTINUE
C
C  CHECK IF FLOW AUGMENTATION IS POSSIBLE.
C  IF NOT, RETURN TO SCAN ANOTHER NODE.
C
4210 CONTINUE
C
  IF (NAUGNOD.EQ.0) GO TO 4120
C
  DO 4096 J=1,NAUGNOD
    NUM_AUGM=NUM_AUGM+1
    AUGNOD=SAVE(J)
    IF (POSIT) THEN
C
C  DO THE AUGMENTATION FROM NODE WITH POSITIVE DEFICIT.
C
      DX=-DFCT(AUGNOD)
      IB=AUGNOD
1500  IF (IB.NE.NODE) THEN
        ARC=PRDCSR(IB)
        IF (ARC.GT.0) THEN

```

```

DX=MIN0(DX,X(ARC))
IB=STARTN(ARC)
ELSE
  DX=MIN0(DX,U(-ARC))
  IB=ENDN(-ARC)
END IF
GOTO 1500
END IF
DX=MIN0(DX,DFCT(NODE))
IF (DX .GT. 0) THEN
C
C  INCREASE (DECREASE) THE FLOW OF ALL FORWARD (BACKWARD)
C  ARCS IN THE FLOW AUGMENTING PATH. ADJUST NODE DEFICIT
ACCORDINGLY.
C
  IF (NXTQUEUE(AUGNOD).EQ.0) THEN
    NXTQUEUE(PREVNODE)=AUGNOD
    NXTQUEUE(AUGNOD)=NODE
    PREVNODE=AUGNOD
  END IF
  DFCT(AUGNOD)=DFCT(AUGNOD)+DX
  DFCT(NODE)=DFCT(NODE)-DX
  IB=AUGNOD
1501  IF (IB.NE.NODE) THEN
    ARC=PRDCSR(IB)
    IF (ARC.GT.0) THEN
      X(ARC)=X(ARC)-DX
      U(ARC)=U(ARC)+DX
      IB=STARTN(ARC)
    ELSE
      NARC=-ARC
      X(NARC)=X(NARC)+DX
      U(NARC)=U(NARC)-DX
      IB=ENDN(NARC)
    END IF
    GOTO 1501
  END IF
END IF
ELSE
C
C  DO THE AUGMENTATION FROM NODE WITH NEGATIVE DEFICIT.
C
  DX=DFCT(AUGNOD)
  IB=AUGNOD
1502  IF (IB.NE.NODE) THEN
    ARC=PRDCSR(IB)

```

```

IF (ARC.GT.0) THEN
  DX=MIN0(DX,X(ARC))
  IB=ENDN(ARC)
ELSE
  DX=MIN0(DX,U(-ARC))
  IB=STARTN(-ARC)
END IF
GOTO 1502
END IF
DX=MIN0(DX,-DFCT(NODE))
IF (DX .GT. 0) THEN
C
C UPDATE THE FLOW AND DEFICITS.
C
  IF (NXTQUEUE(AUGNOD).EQ.0) THEN
    NXTQUEUE(PREVNODE)=AUGNOD
    NXTQUEUE(AUGNOD)=NODE
    PREVNODE=AUGNOD
  END IF
  DFCT(AUGNOD)=DFCT(AUGNOD)-DX
  DFCT(NODE)=DFCT(NODE)+DX
  IB=AUGNOD
1503  IF (IB.NE.NODE) THEN
  ARC=PRDCSR(IB)
  IF (ARC.GT.0) THEN
    X(ARC)=X(ARC)-DX
    U(ARC)=U(ARC)+DX
    IB=ENDN(ARC)
  ELSE
    NARC=-ARC
    X(NARC)=X(NARC)+DX
    U(NARC)=U(NARC)-DX
    IB=STARTN(NARC)
  END IF
  GOTO 1503
END IF
END IF
END IF
IF (DFCT(NODE).EQ.0) GO TO 100
IF (DFCT(AUGNOD).NE.0) SWITCH=.FALSE.
4096 CONTINUE
C
C IF NODE STILL HAS NONZERO DEFICIT AND ALL NEWLY
C LABELED NODES HAVE SAME SIGN FOR THEIR DEFICIT AS
C NODE, WE CAN CONTINUE LABELING. IN THIS CASE, CONTINUE
C LABELING ONLY WHEN FLOW AUGMENTATION IS DONE

```

```

C   RELATIVELY INFREQUENTLY.
C
C   IF (SWITCH.AND.(ITER.GT.8*NUM_AUGM)) GO TO 4120
C
C   RETURN TO DO ANOTHER RELAXATION ITERATION.
C
C   GO TO 100
C
C   PROBLEM IS FOUND TO BE INFEASIBLE
C
4400 PRINT*, 'PROBLEM IS FOUND TO BE INFEASIBLE.'
      PRINT*, 'PROGRAM ENDED; PRESS <CR> TO EXIT'
      PAUSE
      STOP
C
C   END
C
C
C   SUBROUTINE AUCTION
C   IMPLICIT INTEGER (A-Z)
C
C-----C
C
C   PURPOSE - THIS SUBROUTINE USES A VERSION OF THE AUCTION
C   ALGORITHM FOR MIN COST NETWORK FLOW TO COMPUTE A
C   GOOD INITIAL FLOW AND PRICES FOR THE PROBLEM.
C
C-----C
C
C   MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C   MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C   PARAMETER (MAXNN=10000, MAXNA=70000)
C
C   INPUT PARAMETERS
C
C   N      = NUMBER OF NODES
C   NA     = NUMBER OF ARCS
C   LARGE   = A VERY LARGE INTEGER TO REPRESENT INFINITY
C             (SEE NOTE 3)
C   STARTN(I) = STARTING NODE FOR THE I-TH ARC,  I = 1,...,NA
C   ENDN(I)  = ENDING NODE FOR THE I-TH ARC,    I = 1,...,NA
C   FOU(I)   = FIRST ARC LEAVING I-TH NODE,    I = 1,...,N
C   NXTOU(I) = NEXT ARC LEAVING THE STARTING NODE OF J-TH ARC,
C             I = 1,...,NA
C   FIN(I)   = FIRST ARC ENTERING I-TH NODE,    I = 1,...,N

```

```

C NXTIN(I) = NEXT ARC ENTERING THE ENDING NODE OF J-TH ARC,
C           I = 1,...,NA
C
C INTEGER STARTN(MAXNA),ENDN(MAXNA)
C INTEGER FOU(MAXNN),NXTOU(MAXNA),FIN(MAXNN),NXTIN(MAXNA)
C COMMON /INPUT/N,NA,LARGE
C COMMON /ARRAYS/STARTN/ARRAYE/ENDN
C COMMON /BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
C COMMON /CR/CRASH

C
C UPDATED PARAMETERS
C
C RC(J) = REDUCED COST OF ARC J,      J = 1,...,NA
C U(J)  = RESIDUAL CAPACITY OF ARC J,
C           J = 1,...,NA
C X(J)  = FLOW ON ARC J,      J = 1,...,NA
C DFCT(I) = DEFICIT AT NODE I,      I = 1,...,N
C
C INTEGER RC(MAXNA),U(MAXNA),X(MAXNA),DFCT(MAXNN)
C COMMON /ARRAYRC/RC/ARRAYU/U/ARRAYX/X/ARRAYB/DFCT
C
C OUTPUT PARAMETERS
C
C COMMON /OUTPUT/NMULTINODE,ITER,NUM_AUGM,NUM_ASCNT,NSP
C
C WORKING PARAMETERS
C
C INTEGER P(MAXNN),PRDCSR(MAXNN),SAVE(MAXNA)
C INTEGER FPUSHF(MAXNN),NXTPUSHF(MAXNA)
C INTEGER FPUSHB(MAXNN),NXTPUSHB(MAXNA)
C INTEGER NXTQUEUE(MAXNN),EXTEND_ARC(MAXNN)
C INTEGER SB_LEVEL(MAXNN),SB_ARC(MAXNN)
C LOGICAL*1 PATH_ID(MAXNN)
C COMMON /BLK1/P/BLK2/PRDCSR/BLK7/SAVE
C COMMON
C /BLK10/FPUSHF/BLK11/NXTPUSHF/BLK12/FPUSHB/BLK13/NXTPUSHB
C COMMON /BLK14/NXTQUEUE/BLK15/EXTEND_ARC
C COMMON /BLK16/SB_LEVEL/BLK17/SB_ARC
C COMMON /BLK9/PATH_ID

C
C START INITIALIZATION USING AUCTION
C
C NAUG=0
C PASS=0
C THRESH_DFCT=0
C

```

```

C   FACTOR DETERMINES BY HOW MUCH EPSILON IS REDUCED AT EACH
MINIMIZATION
C
    FACTOR=3
C
C   NUM_PASSES DETERMINES HOW MANY AUCTION SCALING PHASES
ARE PERFORMED
C
    NUM_PASSES=1

C   SET ARC FLOWS TO SATISFY CS AND CALCULATE MAXCOST AND
MINCOST

MAXCOST=-LARGE
MINCOST=LARGE
DO 49 ARC=1,NA
    START=STARTN(ARC)
    END=ENDN(ARC)
    RDCOST=RC(ARC)
    IF (MAXCOST.LT.RDCOST) MAXCOST=RDCOST
    IF (MINCOST.GT.RDCOST) MINCOST=RDCOST
    IF (RDCOST.LT.0) THEN
        DFCT(START)=DFCT(START)+U(ARC)
        DFCT(END)=DFCT(END)-U(ARC)
        X(ARC)=U(ARC)
        U(ARC)=0
    ELSE
        X(ARC)=0
    END IF
49  CONTINUE
C
C   SET INITIAL EPSILON
C
    IF ((MAXCOST-MINCOST).GE.8) THEN
        EPS=INT((MAXCOST-MINCOST)/8)
    ELSE
        EPS=1
    END IF
C
C   SET INITIAL PRICES TO ZERO
C
    DO 48 NODE=1,N
        P(NODE)=0
48  CONTINUE
C
C   INITIALIZATION USING AUCTION/SHORTEST PATHS.

```

```

C   START OF THE FIRST SCALING PHASE.
C
100 CONTINUE

PASS=PASS+1
IF ((PASS.EQ.NUM_PASSES).OR.(EPS.EQ.1)) CRASH=0
NOLIST=0
C
C   CONSTRUCT LIST OF POSITIVE SURPLUS NODES AND QUEUE OF
NEGATIVE SURPLUS
C   NODES
C
DO 110 NODE=1,N
PRDCSR(NODE)=0
PATH_ID(NODE)=.FALSE.
EXTEND_ARC(NODE)=0
SB_LEVEL(NODE)=-LARGE
NXTQUEUE(NODE)=NODE+1
IF (DFCT(NODE).GT.0) THEN
  NOLIST=NOLIST+1
  SAVE(NOLIST)=NODE
END IF
110 CONTINUE
C
NXTQUEUE(N)=1
ROOT=1
PREVNODE=N
LASTQUEUE=N
C
C   INITIALIZATION WITH DOWN ITERATIONS FOR NEGATIVE SURPLUS
NODES
C
DO 150 I=1,NOLIST
NODE=SAVE(I)
NSP=NSP+1
C
C   BUILD THE LIST OF ARCS W/ ROOM FOR PUSHING FLOW
C   AND FIND PROPER PRICE FOR DOWN ITERATION
C
BSTLEVEL=-LARGE
FPUSHF(NODE)=0
ARC=FOU(NODE)
152 IF (ARC.GT.0) THEN
  IF (U(ARC).GT.0) THEN
    IF (FPUSHF(NODE).EQ.0) THEN
      FPUSHF(NODE)=ARC

```

```

NXTPUSHF(ARC)=0
LAST=ARC
ELSE
  NXTPUSHF(LAST)=ARC
  NXTPUSHF(ARC)=0
  LAST=ARC
END IF
END IF
IF (X(ARC).GT.0) THEN
  NEW_LEVEL = P(ENDN(ARC)) + RC(ARC)
  IF (NEW_LEVEL.GT.BSTLEVEL) THEN
    BSTLEVEL=NEW_LEVEL
    EXTARC=ARC
  END IF
END IF
ARC=NXTOU(ARC)
GO TO 152
END IF
C
FPUSHB(NODE)=0
ARC=FIN(NODE)
154 IF (ARC.GT.0) THEN
  IF (X(ARC).GT.0) THEN
    IF (FPUSHB(NODE).EQ.0) THEN
      FPUSHB(NODE)=ARC
      NXTPUSHB(ARC)=0
      LAST=ARC
    ELSE
      NXTPUSHB(LAST)=ARC
      NXTPUSHB(ARC)=0
      LAST=ARC
    END IF
  END IF
  IF (U(ARC).GT.0) THEN
    NEW_LEVEL = P(STARTN(ARC)) - RC(ARC)
    IF (NEW_LEVEL.GT.BSTLEVEL) THEN
      BSTLEVEL=NEW_LEVEL
      EXTARC=-ARC
    END IF
  END IF
  ARC=NXTIN(ARC)
  GO TO 154
END IF
EXTEND_ARC(NODE)=EXTARC
P(NODE)=BSTLEVEL-EPS

```

```

150 CONTINUE
C
C   START THE AUGMENTATION CYCLES OF THE NEW SCALING PHASE.
C
200 CONTINUE

IF (DFCT(ROOT).GE.THRESH_DFCT) GOTO 3000

TERM=ROOT
PATH_ID(ROOT)=.TRUE.

C
C   MAIN FORWARD ALGORITHM WITH ROOT AS ORIGIN.
C
500 CONTINUE
C   START OF A NEW FORWARD ITERATION
C
PTERM=P(TERM)
EXTARC=EXTEND_ARC(TERM)

IF (EXTARC.EQ.0) THEN
C
C   BUILD THE LIST OF ARCS W/ ROOM FOR PUSHING FLOW
C
502 IF (ARC.GT.0) THEN
  IF (U(ARC).GT.0) THEN
    IF (FPUSHF(TERM).EQ.0) THEN
      FPUSHF(TERM)=ARC
      NXTPUSHF(ARC)=0
      LAST=ARC
    ELSE
      NXTPUSHF(LAST)=ARC
      NXTPUSHF(ARC)=0
      LAST=ARC
    END IF
  END IF
  ARC=NXTOU(ARC)
  GO TO 502
END IF
C
504 IF (ARC.GT.0) THEN
  IF (X(ARC).GT.0) THEN
    IF (FPUSHB(TERM).EQ.0) THEN

```

```

FPUSHB(TERM)=ARC
NXTPUSHB(ARC)=0
LAST=ARC
ELSE
    NXTPUSHB(LAST)=ARC
    NXTPUSHB(ARC)=0
    LAST=ARC
END IF
END IF
ARC=NXTIN(ARC)
GO TO 504
END IF

GO TO 600
END IF
C
C   SPECULATIVE PATH EXTENSION ATTEMPT
C   NOTE: ARC>0 MEANS THAT ARC IS ORIENTED FROM THE ROOT TO THE
DESTINATIONS
C   ARC<0 MEANS THAT ARC IS ORIENTED FROM THE DESTINATIONS TO
THE ROOT
C   EXTARC=0 OR PRDARC=0, MEANS THE EXTENSION ARC OR THE
PREDECESSOR ARC,
C   RESPECTIVELY, HAS NOT BEEN ESTABLISHED
C
510 CONTINUE

IF (EXTARC.GT.0) THEN

    IF (U(EXTARC).EQ.0) THEN
        SECLEVEL=SB_LEVEL(TERM)
        GO TO 580
    END IF
    END=ENDN(EXTARC)
    BSTLEVEL=P(END)+RC(EXTARC)
    IF (PTERM.GE.BSTLEVEL) THEN
        IF (PATH_ID(END)) GOTO 1200
        TERM=END
        PRDCSR(TERM)=EXTARC
        PATH_ID(TERM)=.TRUE.

C
C   IF NEGATIVE SURPLUS NODE IS FOUND, DO AN AUGMENTATION
C
        IF (DFCT(TERM).GT.0) GOTO 2000
C
C   RETURN FOR ANOTHER ITERATION

```

```

C
    GO TO 500
END IF
ELSE
    EXTARC=-EXTARC
    IF (X(EXTARC).EQ.0) THEN
        SECLEVEL=SB_LEVEL(TERM)
        GO TO 580
    END IF
    START=STARTN(EXTARC)
    BSTLEVEL=P(START)-RC(EXTARC)
    IF (PTERM.GE.BSTLEVEL) THEN
        IF (PATH_ID(START)) GOTO 1200
        TERM=START
        PRDCSR(TERM)=EXTARC
        PATH_ID(TERM)=.TRUE.

C
C   IF NEGATIVE SURPLUS NODE IS FOUND, DO AN AUGMENTATION
C
C       IF (DFCT(TERM).GT.0) GOTO 2000
C
C   RETURN FOR ANOTHER ITERATION
C
C       GO TO 500
C   END IF
C   END IF
C
C   SECOND BEST LOGIC TEST APPLIED TO SAVE A FULL NODE SCAN
C   IF OLD BEST LEVEL CONTINUES TO BE BEST GO FOR ANOTHER
CONTRACTION
C
550 SECLEVEL=SB_LEVEL(TERM)
    IF (BSTLEVEL.LE.SECLEVEL) GOTO 800
C
C   IF SECOND BEST CAN BE USED DO EITHER A CONTRACTION
C   OR START OVER WITH A SPECULATIVE EXTENSION
C
580 IF (SECLEVEL.GT.-LARGE) THEN
    EXTARC=SB_ARC(TERM)
    IF (EXTARC.GT.0) THEN
        IF (U(EXTARC).EQ.0) GOTO 600
        BSTLEVEL=P(ENDN(EXTARC))+RC(EXTARC)
    ELSE
        IF (X(-EXTARC).EQ.0) GOTO 600
        BSTLEVEL=P(STARTN(-EXTARC))-RC(-EXTARC)
    END IF

```

```

IF (BSTLEVEL.EQ.SECLEVEL) THEN
  SB_LEVEL(TERM)=LARGE
  EXTEND_ARC(TERM)=EXTARC
  GOTO 800
END IF
END IF

C
C  EXTENSION/CONTRACTION ATTEMPT WAS UNSUCCESSFUL, SO SCAN
TERMINAL NODE
C
600 CONTINUE
NSP=NSP+1

BSTLEVEL=LARGE
SECLEVEL=LARGE

ARC=FPUSHF(TERM)
700 IF (ARC.GT.0) THEN
  NEW_LEVEL = P(ENDN(ARC)) + RC(ARC)
  IF (NEW_LEVEL.LT.SECLEVEL) THEN
    IF (NEW_LEVEL.LT.BSTLEVEL) THEN
      SECLEVEL=BSTLEVEL
      BSTLEVEL=NEW_LEVEL
      SECARC=EXTARC
      EXTARC=ARC
    ELSE
      SECLEVEL=NEW_LEVEL
      SECARC=ARC
    END IF
  END IF
  ARC=NXTPUSHF(ARC)
  GOTO 700
END IF

ARC=FPUSHB(TERM)
710 IF (ARC.GT.0) THEN
  NEW_LEVEL = P(STARTN(ARC)) - RC(ARC)
  IF (NEW_LEVEL.LT.SECLEVEL) THEN
    IF (NEW_LEVEL.LT.BSTLEVEL) THEN
      SECLEVEL=BSTLEVEL
      BSTLEVEL=NEW_LEVEL
      SECARC=EXTARC
      EXTARC=-ARC
    ELSE
      SECLEVEL=NEW_LEVEL
      SECARC=-ARC
    END IF
  END IF

```

```

        END IF
    END IF
    ARC=NXTPUSHB(ARC)
    GOTO 710
END IF

SB_LEVEL(TERM)=SECLEVEL
SB_ARC(TERM)=SECARC
EXTEND_ARC(TERM)=EXTARC

C
C   END OF NODE SCAN.
C   IF THE TERMINAL NODE IS THE ROOT, ADJUST ITS PRICE AND CHANGE
ROOT
C
800 IF (TERM.EQ.ROOT) THEN
    P(TERM)=BSTLEVEL+EPS
    IF (PTERM.GE.LARGE) THEN
        PRINT*, 'NO PATH TO THE DESTINATION'
        PRINT*, 'PROBLEM IS FOUND TO BE INFEASIBLE.'
        PRINT*, 'PROGRAM ENDED; PRESS <CR> TO EXIT'
        PAUSE
        STOP
    END IF
    PATH_ID(ROOT)=.FALSE.
    PREVNODE=ROOT
    ROOT=NXTQUEUE(ROOT)
    GO TO 200
END IF

C
C   CHECK WHETHER EXTENSION OR CONTRACTION
C
PRD=PRDCSR(TERM)
IF (PRD.GT.0) THEN
    PR_TERM=STARTN(PRD)
    PREVLEVEL=P(PR_TERM)-RC(PRD)
ELSE
    PR_TERM=ENDN(-PRD)
    PREVLEVEL=P(PR_TERM)+RC(-PRD)
END IF

C
IF (PREVLEVEL.GT.BSTLEVEL) THEN
C
C   PATH EXTENSION
C
IF (PREVLEVEL.GE.BSTLEVEL+EPS) THEN
    P(TERM)=BSTLEVEL+EPS

```

```

ELSE
  P(TERM)=PREVLEVEL
END IF
IF (EXTARC.GT.0) THEN
  END=ENDN(EXTARC)
  IF (PATH_ID(END)) GOTO 1200
  TERM=END
ELSE
  START=STARTN(-EXTARC)
  IF (PATH_ID(START)) GOTO 1200
  TERM=START
END IF
PRDCSR(TERM)=EXTARC
PATH_ID(TERM)=.TRUE.

C
C  IF NEGATIVE SURPLUS NODE IS FOUND, DO AN AUGMENTATION
C
C  IF (DFCT(TERM).GT.0) GOTO 2000
C
C  RETURN FOR ANOTHER ITERATION
C
C  GO TO 500
C  ELSE
C
C  PATH CONTRACTION.

C
P(TERM)=BSTLEVEL+EPS
PATH_ID(TERM)=.FALSE.
TERM=PR_TERM
IF (PR_TERM.NE.ROOT) THEN
  IF (BSTLEVEL.LE.PTERM+EPS) THEN
    GOTO 2000
  END IF
END IF
PTERM=P(TERM)
EXTARC=PRD
IF (PRD.GT.0) THEN
  BSTLEVEL=BSTLEVEL+EPS+RC(PRD)
ELSE
  BSTLEVEL=BSTLEVEL+EPS-RC(-PRD)
END IF

C
C  DO A SECOND BEST TEST AND IF THAT FAILS, DO A FULL NODE SCAN
C
C  GOTO 550
END IF

```

```

C
C   A CYCLE IS ABOUT TO FORM; DO A RETREAT SEQUENCE.
C
1200 CONTINUE
C
    NODE=TERM
1600 IF (NODE.NE.ROOT) THEN
    PATH_ID(NODE)=.FALSE.
    PRD=PRDCSR(NODE)
    IF (PRD.GT.0) THEN
        PR_TERM=STARTN(PRD)
        IF (P(PR_TERM).EQ.P(NODE)+RC(PRD)+EPS) THEN
            NODE=PR_TERM
            GOTO 1600
        END IF
    ELSE
        PR_TERM=ENDN(-PRD)
        IF (P(PR_TERM).EQ.P(NODE)-RC(-PRD)+EPS) THEN
            NODE=PR_TERM
            GOTO 1600
        END IF
    END IF
C
C   DO A FULL SCAN AND PRICE RISE AT PR_TERM
C
    NSP=NSP+1
    BSTLEVEL=LARGE
    SECLEVEL=LARGE
    ARC=FPUSHF(PR_TERM)
1700 IF (ARC.GT.0) THEN
    NEW_LEVEL = P(ENDN(ARC)) + RC(ARC)
    IF (NEW_LEVEL.LT.SECLEVEL) THEN
        IF (NEW_LEVEL.LT.BSTLEVEL) THEN
            SECLEVEL=BSTLEVEL
            BSTLEVEL=NEW_LEVEL
            SECARC=EXTARC
            EXTARC=ARC
        ELSE
            SECLEVEL=NEW_LEVEL
            SECARC=ARC
        END IF
    END IF
    ARC=NXTPUSHF(ARC)
    GOTO 1700
END IF
C

```

```

ARC=FPUSHB(PR_TERM)
1710 IF (ARC.GT.0) THEN
    NEW_LEVEL = P(STARTN(ARC)) - RC(ARC)
    IF (NEW_LEVEL.LT.SECLEVEL) THEN
        IF (NEW_LEVEL.LT.BSTLEVEL) THEN
            SECLEVEL=BSTLEVEL
            BSTLEVEL=NEW_LEVEL
            SECARC=EXTARC
            EXTARC=-ARC
        ELSE
            SECLEVEL=NEW_LEVEL
            SECARC=-ARC
        END IF
    END IF
    ARC=NXTPUSHB(ARC)
    GOTO 1710
END IF

SB_LEVEL(PR_TERM)=SECLEVEL
SB_ARC(PR_TERM)=SECARC
EXTEND_ARC(PR_TERM)=EXTARC

P(PR_TERM)=BSTLEVEL+EPS
IF (PR_TERM.EQ.ROOT) THEN
    PREVNODE=ROOT
    PATH_ID(ROOT)=.FALSE.
    ROOT=NXTQUEUE(ROOT)
    GOTO 200
END IF

PATH_ID(PR_TERM)=.FALSE.
PRD=PRDCSR(PR_TERM)
IF (PRD.GT.0) THEN
    TERM=STARTN(PRD)
ELSE
    TERM=ENDN(-PRD)
END IF

IF (TERM.EQ.ROOT) THEN
    PREVNODE=ROOT
    PATH_ID(ROOT)=.FALSE.
    ROOT=NXTQUEUE(ROOT)
    GOTO 200
ELSE
    GOTO 2000
END IF

```

```

END IF
C
C   END OF AUCTION/SHORTEST PATH ROUTINE.
C   DO AUGMENTATION FROM ROOT AND CORRECT THE PUSH LISTS
C
2000 CONTINUE

INCR=-DFCT(ROOT)
NODE = ROOT
2050 EXTARC=EXTEND_ARC(NODE)
PATH_ID(NODE)=.FALSE.
IF (EXTARC.GT.0) THEN
  NODE=ENDN(EXTARC)
  IF (INCR.GT.U(EXTARC)) INCR=U(EXTARC)
ELSE
  NODE=STARTN(-EXTARC)
  IF (INCR.GT.X(-EXTARC)) INCR=X(-EXTARC)
END IF
IF (NODE.NE.TERM) GOTO 2050
PATH_ID(TERM)=.FALSE.
IF (DFCT(TERM).GT.0) THEN
  IF (INCR.GT.DFCT(TERM)) INCR=DFCT(TERM)
END IF
C
NODE = ROOT
2100 EXTARC=EXTEND_ARC(NODE)
IF (EXTARC.GT.0) THEN
  END=ENDN(EXTARC)
C
C   ADD ARC TO THE REDUCED GRAPH
C
IF (X(EXTARC).EQ.0) THEN
  NXTPUSHB(EXTARC)=FPUSHB(END)
  FPUSHB(END)=EXTARC
  NEW_LEVEL=P(NODE)-RC(EXTARC)
  IF (SB_LEVEL(END).GT.NEW_LEVEL) THEN
    SB_LEVEL(END)=NEW_LEVEL
    SB_ARC(END)=-EXTARC
  END IF
END IF
X(EXTARC)=X(EXTARC)+INCR
U(EXTARC)=U(EXTARC)-INCR
C
C   REMOVE ARC FROM THE REDUCED GRAPH
C

```

```

IF (U(EXTARC).EQ.0) THEN
  NAS=NAS+1
  ARC=FPUSHF(NODE)
  IF (ARC.EQ.EXTARC) THEN
    FPUSHF(NODE)=NXTYPUSHF(ARC)
  ELSE
    PREVARC=ARC
    ARC=NXTYPUSHF(ARC)
2200  IF (ARC.GT.0) THEN
    IF (ARC.EQ.EXTARC) THEN
      NXTYPUSHF(PREVARC)=NXTYPUSHF(ARC)
      GO TO 2250
    END IF
    PREVARC=ARC
    ARC=NXTYPUSHF(ARC)
    GOTO 2200
  END IF
END IF
ELSE
  EXTARC=-EXTARC
  START=STARTN(EXTARC)
C  ADD ARC TO THE REDUCED GRAPH
C
  IF (U(EXTARC).EQ.0) THEN
    NXTYPUSHF(EXTARC)=FPUSHF(START)
    FPUSHF(START)=EXTARC
    NEW_LEVEL=P(NODE)+RC(EXTARC)
    IF (SB_LEVEL(START).GT.NEW_LEVEL) THEN
      SB_LEVEL(START)=NEW_LEVEL
      SB_ARC(START)=EXTARC
    END IF
  END IF
  U(EXTARC)=U(EXTARC)+INCR
  X(EXTARC)=X(EXTARC)-INCR
C  REMOVE ARC FROM THE REDUCED GRAPH
C
  IF (X(EXTARC).EQ.0) THEN
    NAS=NAS+1
    ARC=FPUSHB(NODE)
    IF (ARC.EQ.EXTARC) THEN

```

```

FPUSHB(NODE)=NXTPUSHB(ARC)
ELSE
  PREVARC=ARC
  ARC=NXTPUSHB(ARC)
2300  IF (ARC.GT.0) THEN
    IF (ARC.EQ.EXTARC) THEN
      NXTPUSHB(PREVARC)=NXTPUSHB(ARC)
      GO TO 2350
    END IF
    PREVARC=ARC
    ARC=NXTPUSHB(ARC)
    GOTO 2300
  END IF
END IF

2350 NODE=START

END IF

IF (NODE.NE.TERM) GOTO 2100
DFCT(TERM)=DFCT(TERM)-INCR
DFCT(ROOT)=DFCT(ROOT)+INCR
C
C  INSERT TERM IN THE QUEUE IF IT HAS A LARGE ENOUGH SURPLUS
C
IF (DFCT(TERM).LT.THRESH_DFCT) THEN
  IF (NXTQUEUE(TERM).EQ.0) THEN
    NXTNODE=NXTQUEUE(ROOT)
    IF ((P(TERM).GE.P(NXTNODE)).AND.(ROOT.NE.NXTNODE)) THEN
      NXTQUEUE(ROOT)=TERM
      NXTQUEUE(TERM)=NXTNODE
    ELSE
      NXTQUEUE(PREVNODE)=TERM
      NXTQUEUE(TERM)=ROOT
      PREVNODE=TERM
    END IF
  END IF
END IF

C  IF ROOT HAS A LARGE ENOUGH SURPLUS, KEEP IT
C  IN THE QUEUE AND RETURN FOR ANOTHER ITERATION
C
IF (DFCT(ROOT).LT.THRESH_DFCT) THEN
  PREVNODE=ROOT
  ROOT=NXTQUEUE(ROOT)

```

```

        GO TO 200
    END IF
C
C    END OF AUGMENTATION CYCLE
C
3000 CONTINUE
C
C    CHECK FOR TERMINATION OF SCALING PHASE. IF SCALING PHASE IS
C    NOT FINISHED, ADVANCE THE QUEUE AND RETURN TO TAKE
ANOTHER NODE.
C
NXTNODE=NXTQUEUE(ROOT)
IF (ROOT.NE.NXTNODE) THEN
    NXTQUEUE(ROOT)=0
    NXTQUEUE(PREVNODE)=NXTNODE
    ROOT=NXTNODE
    GO TO 200
END IF
C
C    END OF SUBPROBLEM (SCALING PHASE).
C
3600 CONTINUE
C
C    REDUCE EPSILON.
C
EPS=INT(EPS/FACTOR)
IF (EPS.LT.1) EPS=1
THRESH_DFCT=INT(THRESH_DFCT/FACTOR)
IF (EPS.EQ.1) THRESH_DFCT=0
C
C    IF ANOTHER AUCTION SCALING PHASE REMAINS, RESET THE FLOWS &
THE PUSH LISTS
C    ELSE RESET ARC FLOWS TO SATISFY CS AND COMPUTE REDUCED
COSTS
C
IF (CRASH.EQ.1) THEN

    DO 3800 ARC=1,NA
        START=STARTN(ARC)
        END=ENDN(ARC)
        PSTART=P(START)
        PEND=P(END)
        IF (PSTART.GT.PEND+EPS+RC(ARC)) THEN
            RESID=U(ARC)
            IF (RESID.GT.0) THEN
                DFCT(START)=DFCT(START)+RESID

```

```

        DFCT(END)=DFCT(END)-RESID
        X(ARC)=X(ARC)+RESID
        U(ARC)=0
    END IF
ELSE
    IF (PSTART.LT.PEND-EPS+RC(ARC)) THEN
        FLOW=X(ARC)
        IF (FLOW.GT.0) THEN
            DFCT(START)=DFCT(START)-FLOW
            DFCT(END)=DFCT(END)+FLOW
            X(ARC)=0
            U(ARC)=U(ARC)+FLOW
        END IF
    END IF
END IF
3800 CONTINUE
C
C   RETURN FOR ANOTHER PHASE
C
3850 CONTINUE
GOTO 100

ELSE

CRASH=1
DO 3900 ARC=1,NA
    START=STARTN(ARC)
    END=ENDN(ARC)
    RED_COST=RC(ARC)+P(END)-P(START)
    IF (RED_COST.LT.0) THEN
        RESID=U(ARC)
        IF (RESID.GT.0) THEN
            DFCT(START)=DFCT(START)+RESID
            DFCT(END)=DFCT(END)-RESID
            X(ARC)=X(ARC)+RESID
            U(ARC)=0
        END IF
    ELSE
        IF (RED_COST.GT.0) THEN
            FLOW=X(ARC)
            IF (FLOW.GT.0) THEN
                DFCT(START)=DFCT(START)-FLOW
                DFCT(END)=DFCT(END)+FLOW
                X(ARC)=0
                U(ARC)=U(ARC)+FLOW
            END IF
        END IF
    END IF
3900 CONTINUE

```

```

        END IF
        END IF
        RC(ARC)=RED_COST
3900  CONTINUE

        END IF

        RETURN
        END

C
C
C      SUBROUTINE PRINTFLOWS(NODE)
C      IMPLICIT INTEGER (A-Z)
C
C-----C
C      PURPOSE - THIS ROUTINE PRINTS THE DEFICIT AND THE FLOWS
C      OF ARCS INCIDENT TO NODE. IT IS USED FOR DIAGNOSTIC
C      PURPOSES IN CASE OF AN INFEASIBLE PROBLEM HERE.
C      IT CAN BE USED ALSO FOR MORE GENERAL DIAGNOSTIC
C      PURPOSES.
C
C-----C
C      MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C      MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C      PARAMETER (MAXNN=10000, MAXNA=70000)
C
C      COMMON/ARRAYS/STARTN/ARRAYE/ENDN/ARRAYU/U/ARRAYX/X
C      $/ARRAYB/DFCT/BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
C
C      INTEGER
C      STARTN(MAXNA),ENDN(MAXNA),U(MAXNA),X(MAXNA),DFCT(MAXNN)
C      INTEGER FOU(MAXNN),NXTOU(MAXNA)
C      INTEGER FIN(MAXNN),NXTIN(MAXNA)
C
C-----C
C
C      PRINT*, 'DEFICIT (I.E., NET FLOW OUT) OF NODE ='DFCT(NODE)
C      PRINT*, 'FLOWS AND CAPACITIES OF INCIDENT ARCS OF NODE',NODE
C
C      CHECK ALL ARCS LEAVING NODE
C
C      IF (FOU(NODE).EQ.0) THEN
C          PRINT*, 'NO OUTGOING ARCS'

```

```

ELSE
ARC=FOU(NODE)
5 IF (ARC.GT.0) THEN
PRINT*, 'ARC', ARC, ' BETWEEN NODES', NODE, ENDN(ARC)
PRINT*, 'FLOW =', X(ARC)
PRINT*, 'RESIDUAL CAPACITY =', U(ARC)
ARC=NXTOU(ARC)
GO TO 5
END IF
END IF
C
C CHECK ALL ARCS INCOMING TO NODE
C
IF (FIN(NODE).EQ.0) THEN
PRINT*, 'NO INCOMING ARCS'
ELSE
ARC=FIN(NODE)
10 IF (ARC.GT.0) THEN
PRINT*, 'ARC', ARC, ' BETWEEN NODES', STARTN(ARC), NODE
PRINT*, 'FLOW =', X(ARC)
PRINT*, 'RESIDUAL CAPACITY =', U(ARC)
ARC=NXTIN(ARC)
GO TO 10
END IF
END IF
C
RETURN
END
C
C
SUBROUTINE ASCNT1(DM,DELX,NLABEL,FEASBL,SWITCH,
$NSCAN,CURNODE,PREVNODE)
IMPLICIT INTEGER (A-Z)
C
C-----
C
C PURPOSE - THIS SUBROUTINE PERFORMS THE MULTI-NODE PRICE
C ADJUSTMENT STEP FOR THE CASE WHERE THE SCANNED NODES
C HAVE POSITIVE DEFICIT. IT FIRST CHECKS IF DECREASING
C THE PRICE OF THE SCANNED NODES INCREASES THE DUAL COST.
C IF YES, THEN IT DECREASES THE PRICE OF ALL SCANNED NODES.
C THERE ARE TWO POSSIBILITIES FOR PRICE DECREASE:
C IF SWITCH=.TRUE., THEN THE SET OF SCANNED NODES
C CORRESPONDS TO AN ELEMENTARY DIRECTION OF MAXIMAL
C RATE OF ASCENT, IN WHICH CASE THE PRICE OF ALL SCANNED
C NODES ARE DECREASED UNTIL THE NEXT BREAKPOINT IN THE

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```

C DUAL COST IS ENCOUNTERED. AT THIS POINT, SOME ARC
C BECOMES BALANCED AND MORE NODE(S) ARE ADDED TO THE
C LABELED SET AND THE SUBROUTINE IS EXITED.
C IF SWITCH=.FALSE., THEN THE PRICE OF ALL SCANNED NODES
C ARE DECREASED UNTIL THE RATE OF ASCENT BECOMES
C NEGATIVE (THIS CORRESPONDS TO THE PRICE ADJUSTMENT
C STEP IN WHICH BOTH THE LINE SEARCH AND THE DEGENERATE
C ASCENT ITERATION ARE IMPLEMENTED).
C
C -----
C
C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C PARAMETER (MAXNN=10000, MAXNA=70000)
C
C INPUT PARAMETERS
C
C DM      = TOTAL DEFICIT OF SCANNED NODES
C SWITCH   = .TRUE. IF LABELING IS TO CONTINUE AFTER PRICE
C CHANGE
C NSCAN   = NUMBER OF SCANNED NODES
C CURNODE = MOST RECENTLY SCANNED NODE
C N       = NUMBER OF NODES
C NA      = NUMBER OF ARCS
C LARGE   = A VERY LARGE INTEGER TO REPRESENT INFINITY
C          (SEE NOTE 3)
C STARTN(I) = STARTING NODE FOR THE I-TH ARC,  I = 1,...,NA
C ENDN(I)  = ENDING NODE FOR THE I-TH ARC,   I = 1,...,NA
C FOU(I)   = FIRST ARC LEAVING I-TH NODE,    I = 1,...,N
C NXTOU(I) = NEXT ARC LEAVING THE STARTING NODE OF J-TH ARC,
C           I = 1,...,NA
C FIN(I)   = FIRST ARC ENTERING I-TH NODE,   I = 1,...,N
C NXTIN(I) = NEXT ARC ENTERING THE ENDING NODE OF J-TH ARC,
C           I = 1,...,NA
C
C INTEGER STARTN(MAXNA),ENDN(MAXNA)
C INTEGER FOU(MAXNN),NXTOU(MAXNA),FIN(MAXNN),NXTIN(MAXNA)
C COMMON /INPUT/N,NA,LARGE
C COMMON /ARRAYS/STARTN/ARRAYE/ENDN
C COMMON /BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
C
C UPDATED PARAMETERS
C
C DELX    = A LOWER ESTIMATE OF THE TOTAL FLOW ON BALANCED
ARCS

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C           IN THE SCANNED-NODES CUT
C   NLABEL = NUMBER OF LABELED NODES
C   FEASBL = .FALSE. IF PROBLEM IS FOUND TO BE INFEASIBLE
C   PREVNODE = THE NODE BEFORE CURNODE IN QUEUE
C   RC(J)  = REDUCED COST OF ARC J,      J = 1,...,NA
C   U(J)   = RESIDUAL CAPACITY OF ARC J,
C             J = 1,...,NA
C   X(J)   = FLOW ON ARC J,          J = 1,...,NA
C   DFCT(I) = DEFICIT AT NODE I,      I = 1,...,N
C   LABEL(K) = K-TH NODE LABELED,      K = 1,NLABEL
C   PRDCSR(I) = PREDECESSOR OF NODE I IN TREE OF LABELED NODES
C             (0 IF I IS UNLABELED),    I = 1,...,N
C   TFSTOU(I) = FIRST BALANCED ARC OUT OF NODE I, I = 1,...,N
C   TNXTOU(J) = NEXT BALANCED ARC OUT OF THE STARTING NODE OF
C   ARC J,
C             J = 1,...,NA
C   TFSTIN(I) = FIRST BALANCED ARC INTO NODE I, I = 1,...,N
C   TNXTIN(J) = NEXT BALANCED ARC INTO THE ENDING NODE OF ARC J,
C             J = 1,...,NA
C   NXTQUEUE(I) = NODE FOLLOWING NODE I IN THE FIFO QUEUE
C             (0 IF NODE IS NOT IN THE QUEUE), I = 1,...,N
C   SCAN(I)  = .TRUE. IF NODE I IS SCANNED,   I = 1,...,N
C   MARK(I)  = .TRUE. IF NODE I IS LABELED,   I = 1,...,N
C
C   INTEGER RC(MAXNA),U(MAXNA),X(MAXNA),DFCT(MAXNN)
C   INTEGER LABEL(MAXNN),PRDCSR(MAXNN)
C   INTEGER
TFSTOU(MAXNN),TNXTOU(MAXNA),TFSTIN(MAXNN),TNXTIN(MAXNA)
C   INTEGER NXTQUEUE(MAXNN)
LOGICAL*1 SCAN(MAXNN),MARK(MAXNN)
COMMON /ARRAYRC/RC/ARRAYU/U/ARRAYX/X/ARRAYB/DFCT
COMMON /BLK1/LABEL/BLK2/PRDCSR
COMMON /BLK10/TFSTOU/BLK11/TNXTOU/BLK12/TFSTIN/BLK13/TNXTIN
COMMON /BLK14/NXTQUEUE
COMMON /BLK8/SCAN/BLK9/MARK
C
C   WORKING PARAMETERS
C
C   INTEGER SAVE(MAXNA)
LOGICAL*1 SWITCH,FEASBL
COMMON /BLK7/SAVE
C
C   STORE THE ARCS BETWEEN THE SET OF SCANNED NODES AND
C   ITS COMPLEMENT IN SAVE AND COMPUTE DELPRC, THE STEPSIZE
C   TO THE NEXT BREAKPOINT IN THE DUAL COST IN THE DIRECTION
C   OF DECREASING PRICES OF THE SCANNED NODES.

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C [THE ARCS ARE STORED INTO SAVE BY LOOKING AT THE ARCS
C INCIDENT TO EITHER THE SET OF SCANNED NODES OR ITS
C COMPLEMENT, DEPENDING ON WHETHER NSCAN>N/2 OR NOT.
C THIS IMPROVES THE EFFICIENCY OF STORING.]
C
DELPRC=LARGE
DLX=0
NSAVE=0
IF (NSCAN.LE.N/2) THEN
DO 1 I=1,NSCAN
  NODE=LABEL(I)
  ARC=FOU(NODE)
500  IF (ARC.GT.0) THEN
C
C ARC POINTS FROM SCANNED NODE TO AN UNSCANNED NODE.
C
  NODE2=ENDN(ARC)
  IF (.NOT.SCAN(NODE2)) THEN
    NSAVE=NSAVE+1
    SAVE(NSAVE)=ARC
    RDCOST=RC(ARC)
    IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE2).NE.ARC))
$     DLX=DLX+X(ARC)
    IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC))
$     DELPRC=-RDCOST
    END IF
    ARC=NXTOU(ARC)
    GOTO 500
  END IF
  ARC=FIN(NODE)

501  IF (ARC.GT.0) THEN
C
C ARC POINTS FROM UNSCANNED NODE TO SCANNED NODE.
C
  NODE2=STARTN(ARC)
  IF (.NOT.SCAN(NODE2)) THEN
    NSAVE=NSAVE+1
    SAVE(NSAVE)=-ARC
    RDCOST=RC(ARC)
    IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE2).NE.-ARC))
$     DLX=DLX+U(ARC)
    IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC))
$     DELPRC=RDCOST
    END IF
    ARC=NXTIN(ARC)

```

```

        GOTO 501
    END IF
1    CONTINUE

    ELSE

        DO 2 NODE=1,N
        IF (SCAN(NODE)) GO TO 2
        ARC=FIN(NODE)

502    IF (ARC.GT.0) THEN
        NODE2=STARTN(ARC)
        IF (SCAN(NODE2)) THEN
            NSAVE=NSAVE+1
            SAVE(NSAVE)=ARC
            RDCOST=RC(ARC)
            IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE).NE.ARC))
$              DLX=DLX+X(ARC)
            IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC))
$              DELPRC=-RDCOST
            END IF
            ARC=NXTIN(ARC)
            GOTO 502
        END IF
        ARC=FOU(NODE)

503    IF (ARC.GT.0) THEN
        NODE2=ENDN(ARC)
        IF (SCAN(NODE2)) THEN
            NSAVE=NSAVE+1
            SAVE(NSAVE)=-ARC
            RDCOST=RC(ARC)
            IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE).NE.-ARC))
$              DLX=DLX+U(ARC)
            IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC))
$              DELPRC=RDCOST
            END IF
            ARC=NXTOU(ARC)
            GOTO 503
        END IF
2    CONTINUE
    END IF
C
C    CHECK IF THE SET OF SCANNED NODES TRULY CORRESPONDS
C    TO A DUAL ASCENT DIRECTION. [HERE DELX+DLX IS THE EXACT
C    SUM OF THE FLOW ON ARCS FROM THE SCANNED SET TO THE
C    UNSCANNED SET PLUS THE (CAPACITY - FLOW) ON ARCS FROM
C    THE UNSCANNED SET TO THE SCANNED SET.]
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```

C IF THIS WERE NOT THE CASE, SET SWITCH TO .TRUE.
C AND EXIT SUBROUTINE.
C
IF ((.NOT.SWITCH).AND.(DELX+DLX.GE.DM)) THEN
  SWITCH=.TRUE.
  RETURN
END IF
DELX=DELX+DLX
C
C CHECK THAT THE PROBLEM IS FEASIBLE.
C
4 IF (DELPRC.EQ.LARGE) THEN
C
C WE CAN INCREASE THE DUAL COST WITHOUT BOUND, SO
C THE PRIMAL PROBLEM IS INFEASIBLE.
C
  FEASBL=.FALSE.
  RETURN
END IF
C
C DECREASE THE PRICES OF THE SCANNED NODES, ADD MORE
C NODES TO THE LABELED SET AND CHECK IF A NEWLY LABELED NODE
C HAS NEGATIVE DEFICIT.
C
IF (SWITCH) THEN
  DO 7 I=1,NSAVE
    ARC=SAVE(I)
    IF (ARC.GT.0) THEN
      RC(ARC)=RC(ARC)+DELPRC
      IF (RC(ARC).EQ.0) THEN
        NODE2=ENDN(ARC)
        IF (TNXTOU(ARC) .LT. 0) THEN
          TNXTOU(ARC) = TFSTOU(STARTN(ARC))
          TFSTOU(STARTN(ARC)) = ARC
        END IF
        IF (TNXTIN(ARC) .LT. 0) THEN
          TNXTIN(ARC) = TFSTIN(NODE2)
          TFSTIN(NODE2) = ARC
        END IF
        IF (.NOT.MARK(NODE2)) THEN
          PRDCSR(NODE2)=ARC
          NLABEL=NLABEL+1
          LABEL(NLABEL)=NODE2
          MARK(NODE2)=.TRUE.
        END IF
      END IF
    END IF
  END IF

```

```

ELSE
ARC=-ARC
RC(ARC)=RC(ARC)-DELPRC
IF (RC(ARC).EQ.0) THEN
NODE2=STARTN(ARC)
IF (TNXTOU(ARC) .LT. 0) THEN
TNXTOU(ARC) = TFSTOU(NODE2)
TFSTOU(NODE2) = ARC
END IF
IF (TNXTIN(ARC) .LT. 0) THEN
TNXTIN(ARC) = TFSTIN(ENDN(ARC))
TFSTIN(ENDN(ARC)) = ARC
END IF
IF (.NOT.MARK(NODE2)) THEN
PRDCSR(NODE2)=-ARC
NLABEL=NLABEL+1
LABEL(NLABEL)=NODE2
MARK(NODE2)=.TRUE.
END IF
END IF
END IF
7 CONTINUE
RETURN

ELSE
C DECREASE THE PRICES OF THE SCANNED NODES BY DELPRC.
C ADJUST FLOW TO MAINTAIN COMPLEMENTARY SLACKNESS WITH
C THE PRICES.
C
NB = 0
DO 6 I=1,NSAVE
ARC=SAVE(I)
IF (ARC.GT.0) THEN
T1=RC(ARC)
IF (T1.EQ.0) THEN
T2=X(ARC)
T3=STARTN(ARC)
DFCT(T3)=DFCT(T3)-T2
IF (NXTQUEUE(T3).EQ.0) THEN
NXTQUEUE(PREVNODE)=T3
NXTQUEUE(T3)=CURNODE
PREVNODE=T3
END IF
T3=ENDN(ARC)
DFCT(T3)=DFCT(T3)+T2

```

```

IF (NXTQUEUE(T3).EQ.0) THEN
  NXTQUEUE(PREVNODE)=T3
  NXTQUEUE(T3)=CURNODE
  PREVNODE=T3
END IF
U(ARC)=U(ARC)+T2
X(ARC)=0
END IF
RC(ARC)=T1+DELPRC
IF (RC(ARC).EQ.0) THEN
  DELX=DELX+X(ARC)
  NB = NB + 1
  PRDCSR(NB) = ARC
END IF
ELSE
  ARC=-ARC
  T1=RC(ARC)
  IF (T1.EQ.0) THEN
    T2=U(ARC)
    T3=STARTN(ARC)
    DFCT(T3)=DFCT(T3)+T2
    IF (NXTQUEUE(T3).EQ.0) THEN
      NXTQUEUE(PREVNODE)=T3
      NXTQUEUE(T3)=CURNODE
      PREVNODE=T3
    END IF
    T3=ENDN(ARC)
    DFCT(T3)=DFCT(T3)-T2
    IF (NXTQUEUE(T3).EQ.0) THEN
      NXTQUEUE(PREVNODE)=T3
      NXTQUEUE(T3)=CURNODE
      PREVNODE=T3
    END IF
    X(ARC)=X(ARC)+T2
    U(ARC)=0
  END IF
  RC(ARC)=T1-DELPRC
  IF (RC(ARC).EQ.0) THEN
    DELX=DELX+U(ARC)
    NB = NB + 1
    PRDCSR(NB) = ARC
  END IF
END IF
6  CONTINUE
END IF

```

C

```

IF (DELX.LE.DM) THEN
C
C   THE SET OF SCANNED NODES STILL CORRESPONDS TO A
C   DUAL (POSSIBLY DEGENERATE) ASCENT DIRECTON. COMPUTE
C   THE STEPSIZE DELPRC TO THE NEXT BREAKPOINT IN THE
C   DUAL COST.
C
C   DELPRC=LARGE
DO 10 I=1,NSAVE
  ARC=SAVE(I)
  IF (ARC.GT.0) THEN
    RDCOST=RC(ARC)
    IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC)) DELPRC=-RDCOST
  ELSE
    ARC=-ARC
    RDCOST=RC(ARC)
    IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC)) DELPRC=RDCOST
  END IF
10  CONTINUE
  IF ((DELPRC.NE.LARGE).OR.(DELX.LT.DM)) GO TO 4
END IF
C
C   ADD NEW BALANCED ARCS TO THE SUPERSET OF BALANCED ARCS.
C
DO 9 I=1,NB
  ARC=PRDCSR(I)
  IF (TNXTIN(ARC).EQ.-1) THEN
    J=ENDN(ARC)
    TNXTIN(ARC)=TFSTIN(J)
    TFSTIN(J)=ARC
  END IF
  IF (TNXTOU(ARC).EQ.-1) THEN
    J=STARTN(ARC)
    TNXTOU(ARC)=TFSTOU(J)
    TFSTOU(J)=ARC
  END IF
9   CONTINUE

RETURN
END
C
C
SUBROUTINE ASCNT2(DM,DELX,NLABEL,FEASBL,SWITCH,
$NSCAN,CURNODE,PREVNODE)
IMPLICIT INTEGER (A-Z)
C

```

```

C-----
C
C PURPOSE - THIS ROUTINE IS ANALOGOUS TO ASCNT BUT FOR
C THE CASE WHERE THE SCANNED NODES HAVE NEGATIVE DEFICIT.
C
C-----
C
C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C PARAMETER (MAXNN=10000, MAXNA=70000)
C
C
INTEGER STARTN(MAXNA),ENDN(MAXNA)
INTEGER FOU(MAXNN),NXTOU(MAXNA),FIN(MAXNN),NXTIN(MAXNA)
COMMON /INPUT/N,NA,LARGE
COMMON /ARRAYS/STARTN/ARRAYE/ENDN
COMMON /BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
INTEGER RC(MAXNA),U(MAXNA),X(MAXNA),DFCT(MAXNN)
INTEGER LABEL(MAXNN),PRDCSR(MAXNN)
INTEGER
TFSTOU(MAXNN),TNXTOU(MAXNA),TFSTIN(MAXNN),TNXTIN(MAXNA)
INTEGER NXTQUEUE(MAXNN)
LOGICAL*1 SCAN(MAXNN),MARK(MAXNN)
COMMON /ARRAYRC/RC/ARRAYU/U/ARRAYX/X/ARRAYB/DFCT
COMMON /BLK1/LABEL/BLK2/PRDCSR
COMMON /BLK10/TFSTOU/BLK11/TNXTOU/BLK12/TFSTIN/BLK13/TNXTIN
COMMON /BLK14/NXTQUEUE
COMMON /BLK8/SCAN/BLK9/MARK
INTEGER SAVE(MAXNA)
LOGICAL*1 SWITCH,FEASBL
COMMON /BLK7/SAVE

C
C STORE THE ARCS BETWEEN THE SET OF SCANNED NODES AND
C ITS COMPLEMENT IN SAVE AND COMPUTE DELPRC, THE STEPSIZE
C TO THE NEXT BREAKPOINT IN THE DUAL COST IN THE DIRECTION
C OF INCREASING PRICES OF THE SCANNED NODES.
C
DELPRC=LARGE
DLX=0
NSAVE=0
IF (NSCAN.LE.N/2) THEN
  DO 1 I=1,NSCAN
    NODE=LABEL(I)
    ARC=FIN(NODE)
  500 IF (ARC.GT.0) THEN
      NODE2=STARTN(ARC)

```

```

        IF (.NOT.SCAN(NODE2)) THEN
          NSAVE=NSAVE+1
          SAVE(NSAVE)=ARC
          RDCOST=RC(ARC)
          IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE2).NE.ARC))
$           DLX=DLX+X(ARC)
          IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC))
$           DELPRC=-RDCOST
        END IF
        ARC=NXTIN(ARC)
        GOTO 500
      END IF
      ARC=FOU(NODE)
501    IF (ARC.GT.0) THEN
        NODE2=ENDN(ARC)
        IF (.NOT.SCAN(NODE2)) THEN
          NSAVE=NSAVE+1
          SAVE(NSAVE)=-ARC
          RDCOST=RC(ARC)
          IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE2).NE.-ARC))
$           DLX=DLX+U(ARC)
          IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC))
$           DELPRC=RDCOST
        END IF
        ARC=NXTOU(ARC)
        GOTO 501
      END IF
1     CONTINUE
      ELSE
        DO 2 NODE=1,N
          IF (SCAN(NODE)) GO TO 2
          ARC=FOU(NODE)
502    IF (ARC.GT.0) THEN
        NODE2=ENDN(ARC)
        IF (SCAN(NODE2)) THEN
          NSAVE=NSAVE+1
          SAVE(NSAVE)=ARC
          RDCOST=RC(ARC)
          IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE).NE.ARC))
$           DLX=DLX+X(ARC)
          IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC))
$           DELPRC=-RDCOST
        END IF
        ARC=NXTOU(ARC)
        GOTO 502
      END IF

```

```

        ARC=FIN(NODE)
503    IF (ARC.GT.0) THEN
        NODE2=STARTN(ARC)
        IF (SCAN(NODE2)) THEN
            NSAVE=NSAVE+1
            SAVE(NSAVE)=-ARC
            RDCOST=RC(ARC)
            IF ((RDCOST.EQ.0).AND.(PRDCSR(NODE).NE.-ARC))
$          DLX=DLX+U(ARC)
            IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC))
$          DELPRC=RDCOST
            END IF
            ARC=NXTIN(ARC)
            GOTO 503
        END IF
2      CONTINUE
        END IF
C
        IF ((.NOT.SWITCH).AND.(DELX+DLX.GE.-DM)) THEN
            SWITCH=.TRUE.
            RETURN
        END IF
        DELX=DELX+DLX
C
C      CHECK THAT THE PROBLEM IS FEASIBLE.
C
4      IF (DELPRC.EQ.LARGE) THEN
            FEASBL=.FALSE.
            RETURN
        END IF
C
C      INCREASE THE PRICES OF THE SCANNED NODES, ADD MORE
C      NODES TO THE LABELED SET AND CHECK IF A NEWLY LABELED NODE
C      HAS POSITIVE DEFICIT.
C
        IF (SWITCH) THEN
            DO 7 I=1,NSAVE
                ARC=SAVE(I)
                IF (ARC.GT.0) THEN
                    RC(ARC)=RC(ARC)+DELPRC
                    IF (RC(ARC).EQ.0) THEN
                        NODE2=STARTN(ARC)
                        IF (TNXTOU(ARC) .LT. 0) THEN
                            TNXTOU(ARC) = TFSTOU(NODE2)
                            TFSTOU(NODE2) = ARC

```

```

END IF
IF (TNXTIN(ARC) .LT. 0) THEN
  TNXTIN(ARC) = TFSTIN(ENDN(ARC))
  TFSTIN(ENDN(ARC)) = ARC
END IF
IF (.NOT.MARK(NODE2)) THEN
  PRDCSR(NODE2)=ARC
  NLABEL=NLABEL+1
  LABEL(NLABEL)=NODE2
  MARK(NODE2)=.TRUE.
END IF
END IF
ELSE
  ARC=-ARC
  RC(ARC)=RC(ARC)-DELPRC
  IF (RC(ARC).EQ.0) THEN
    NODE2=ENDN(ARC)
    IF (TNXTOU(ARC) .LT. 0) THEN
      TNXTOU(ARC) = TFSTOU(STARTN(ARC))
      TFSTOU(STARTN(ARC)) = ARC
    END IF
    IF (TNXTIN(ARC) .LT. 0) THEN
      TNXTIN(ARC) = TFSTIN(NODE2)
      TFSTIN(NODE2) = ARC
    END IF
    IF (.NOT.MARK(NODE2)) THEN
      PRDCSR(NODE2)=-ARC
      NLABEL=NLABEL+1
      LABEL(NLABEL)=NODE2
      MARK(NODE2)=.TRUE.
    END IF
  END IF
  END IF
CONTINUE
RETURN

7 ELSE
NB = 0
DO 6 I=1,NSAVE
  ARC=SAVE(I)
  IF (ARC.GT.0) THEN
    T1=RC(ARC)
    IF (T1.EQ.0) THEN
      T2=X(ARC)
      T3=STARTN(ARC)

```

```

DFCT(T3)=DFCT(T3)-T2
IF (NXTQUEUE(T3).EQ.0) THEN
  NXTQUEUE(PREVNODE)=T3
  NXTQUEUE(T3)=CURNODE
  PREVNODE=T3
END IF
T3=ENDN(ARC)
DFCT(T3)=DFCT(T3)+T2
IF (NXTQUEUE(T3).EQ.0) THEN
  NXTQUEUE(PREVNODE)=T3
  NXTQUEUE(T3)=CURNODE
  PREVNODE=T3
END IF
U(ARC)=U(ARC)+T2
X(ARC)=0
END IF
RC(ARC)=T1+DELPRC
IF (RC(ARC).EQ.0) THEN
  DELX=DELX+X(ARC)
  NB = NB + 1
  PRDCSR(NB) = ARC
END IF
ELSE
  ARC=-ARC
  T1=RC(ARC)
  IF (T1.EQ.0) THEN
    T2=U(ARC)
    T3=STARTN(ARC)
    DFCT(T3)=DFCT(T3)+T2
    IF (NXTQUEUE(T3).EQ.0) THEN
      NXTQUEUE(PREVNODE)=T3
      NXTQUEUE(T3)=CURNODE
      PREVNODE=T3
    END IF
    T3=ENDN(ARC)
    DFCT(T3)=DFCT(T3)-T2
    IF (NXTQUEUE(T3).EQ.0) THEN
      NXTQUEUE(PREVNODE)=T3
      NXTQUEUE(T3)=CURNODE
      PREVNODE=T3
    END IF
    X(ARC)=X(ARC)+T2
    U(ARC)=0
  END IF
  RC(ARC)=T1-DELPRC
  IF (RC(ARC).EQ.0) THEN

```

```

        DELX=DELX+U(ARC)
        NB = NB + 1
        PRDCSR(NB) = ARC
    END IF
    END IF
6   CONTINUE

    END IF
C
IF (DELX.LE.-DM) THEN
    DELPRC=LARGE
    DO 10 I=1,NSAVE
        ARC=SAVE(I)
        IF (ARC.GT.0) THEN
            RDCOST=RC(ARC)
            IF ((RDCOST.LT.0).AND.(RDCOST.GT.-DELPRC)) DELPRC=-RDCOST
        ELSE
            ARC=-ARC
            RDCOST=RC(ARC)
            IF ((RDCOST.GT.0).AND.(RDCOST.LT.DELPRC)) DELPRC=RDCOST
        END IF
10  CONTINUE
    IF ((DELPRC.NE.LARGE).OR.(DELX.LT.-DM)) GO TO 4
END IF
C
C   ADD NEW BALANCED ARCS TO THE SUPERSET OF BALANCED ARCS.
C
DO 9 I=1,NB
    ARC=PRDCSR(I)
    IF (TNXTIN(ARC).EQ.-1) THEN
        J=ENDN(ARC)
        TNXTIN(ARC)=TFSTIN(J)
        TFSTIN(J)=ARC
    END IF
    IF (TNXTOU(ARC).EQ.-1) THEN
        J=STARTN(ARC)
        TNXTOU(ARC)=TFSTOU(J)
        TFSTOU(J)=ARC
    END IF
9   CONTINUE

    RETURN
END
C
C   SUBROUTINE SENSTV

```

IMPLICIT INTEGER (A-Z)

```
C
C-----
C
C PURPOSE - THIS SUBROUTINE ALLOWS THE USER TO INTERACTIVELY
C EITHER CHANGE NODE SUPPLY, OR CHANGE FLOW UPPER BOUND
C OF AN EXISTING ARC, OR CHANGE COST OF AN EXISTING ARC,
C OR DELETE AN EXISTING ARC, OR ADD AN ARC.
C [NOTE: IF THE OPERATING SYSTEM RESETS ALL LOCAL VARIABLES
C TO SOME DEFAULT VALUE EACH TIME THIS SUBROUTINE IS CALLED,
C THEN THE USER MUST MAKE THE FOLLOWING CURRENTLY LOCAL
C VARIABLES:
C      DELARC, DARC, DU, ADDARC, AARC
C      GLOBAL (BY EITHER PUTTING THEM IN A COMMON BLOCK OR
C      PASSING THEM THROUGH THE CALLING PARAMETER).]
C
C-----
C
C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS
C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS
C
C PARAMETER (MAXNN=10000, MAXNA=70000)
C
C INPUT PARAMETERS
C
C      N      = NUMBER OF NODES
C      NA     = NUMBER OF ARCS
C      LARGE   = A VERY LARGE INTEGER TO REPRESENT INFINITY
C      STARTN(J) = STARTING NODE FOR ARC J,      J = 1,...,NA
C      ENDN(J)  = ENDING NODE FOR ARC J,      J = 1,...,NA
C      FOU(I)   = FIRST ARC OUT OF NODE I,      I = 1,...,N
C      NXTOU(J) = NEXT ARC OUT OF THE STARTING NODE OF ARC J,
C                  J = 1,...,NA
C      FIN(I)   = FIRST ARC INTO NODE I,      I = 1,...,N
C      NXTIN(J) = NEXT ARC INTO THE ENDING NODE OF ARC J,
C                  J = 1,...,NA
C      REPEAT   = .TRUE. IF CAP(J)=X(J)+U(J), J=1,...,NA, ON INPUT
C                  (.FALSE. OTHERWISE)
C
C      INTEGER STARTN(MAXNA),ENDN(MAXNA)
C      INTEGER FOU(MAXNN),NXTOU(MAXNA),FIN(MAXNN),NXTIN(MAXNA)
C      LOGICAL*1 REPEAT
C      COMMON /INPUT/N,NA,LARGE
C      COMMON /ARRAYS/STARTN/ARRAYE/ENDN
C      COMMON /BLK3/FOU/BLK4/NXTOU/BLK5/FIN/BLK6/NXTIN
C      COMMON /BLKR/REPEAT
```

```

C
C UPDATED PARAMETERS
C
C   C(J) = COST OF ARC J,           J = 1,...,NA
C   CAP(J) = CAPACITY OF ARC J,      J = 1,...,NA
C   RC(J) = REDUCED COST OF ARC J,   J = 1,...,NA
C   X(J) = FLOW ON ARC J,           J = 1,...,NA
C   U(J) = CAP(J) - X(J) ON OUTPUT,  J = 1,...,NA
C   DFCT(I) = DEMAND AT NODE I ON INPUT
C           AND ZERO ON OUTPUT,      I = 1,...,N
C   TFSTOU(I) = FIRST BALANCED ARC OUT OF NODE I, I = 1,...,N
C   TNXTOU(J) = NEXT BALANCED ARC OUT OF THE STARTING NODE OF
ARC J,
C                           J = 1,...,NA
C   TFSTIN(I) = FIRST BALANCED ARC INTO NODE I, I = 1,...,N
C   TNXTIN(J) = NEXT BALANCED ARC INTO THE ENDING NODE OF ARC J,
C                           J = 1,...,NA
C
C   INTEGER C(MAXNA),CAP(MAXNA)
C   INTEGER RC(MAXNA),X(MAXNA),U(MAXNA),DFCT(MAXNN)
C   INTEGER
TFSTOU(MAXNN),TNXTOU(MAXNA),TFSTIN(MAXNN),TNXTIN(MAXNA)
COMMON /ARRAYC/C/BLKCAP/CAP
COMMON /ARRAYRC/RC/ARRAYX/X/ARRAYU/U/ARRAYB/DFCT
COMMON/BLK10/TFSTOU/BLK11/TNXTOU/BLK12/TFSTIN/BLK13/TNXTIN
C
C WORKING PARAMETERS
C
C   INTEGER LABEL(MAXNN),PRICE(MAXNN),SAVE(MAXNA)
C   LOGICAL*1 ADDARC,DELARC,MARK(MAXNN)
C   COMMON/BLK1/LABEL/BLK2/PRICE/BLK7/SAVE
C   COMMON/BLK9/MARK
C
C   IF (.NOT.REPEAT) THEN
C
C   RESTORE THE ARC CAPACITY TO THAT OF THE ORIGINAL PROBLEM
C   [RECALL THAT, IN SOLVING THE ORIGINAL PROBLEM, RELAX4
C   MAY HAVE DECREASED THE ARC CAPACITIES DURING
C   INITIALIZATION PHASE I.] THEN UPDATE FLOW AND THE
C   NODE DEFICITS TO MATCH THIS "NEW" CAPACITY.
C
DO 10 I=1,NA
  IF (RC(I).LT.0) THEN
    DFCT(STARTN(I))=DFCT(STARTN(I))+CAP(I)-X(I)
    DFCT(ENDN(I))=DFCT(ENDN(I))-CAP(I)+X(I)
    X(I)=CAP(I)

```

```

        ELSE
          U(I)=CAP(I)-X(I)
        END IF
10      CONTINUE
        REPEAT=.TRUE.
      END IF
20      WRITE(6,30)
        WRITE(6,40)
        WRITE(6,50)
        WRITE(6,60)
        WRITE(6,70)
        WRITE(6,80)
      IF (ADDARC) WRITE(6,90) AARC
      IF (DELARC) WRITE(6,100) DARC
      WRITE(6,105)
30      FORMAT(' INPUT 0 TO SOLVE THE MODIFIED PROBLEM')
40      FORMAT(' 1 TO CHANGE NODE FLOW SUPPLY')
50      FORMAT(' 2 TO CHANGE ARC FLOW UPPER BOUND')
60      FORMAT(' 3 TO CHANGE ARC COST')
70      FORMAT(' 4 TO DELETE AN ARC')
80      FORMAT(' 5 TO ADD AN ARC')
90      FORMAT(' 6 TO DELETE LAST ARC',I8,' ADDED')
100     FORMAT(' 7 TO RESTORE LAST ARC',I8,'DELETED')
105     FORMAT(' 8 TO QUIT PROGRAM')
      READ(5,*)SEL
      IF (SEL.EQ.8) THEN
        STOP
      ELSE IF (SEL.EQ.0) THEN
        RETURN
      ELSE IF (SEL.EQ.1) THEN
C
C      CHANGE NODE FLOW SUPPLY.
C
110     WRITE(6,120)
120     FORMAT(' INPUT NODE # WHERE FLOW SUPPLY IS INCREASED')
      READ(5,*)NODE
      IF ((NODE.LE.0).OR.(NODE.GT.N)) GO TO 110
      WRITE(6,130)
130     FORMAT(' INPUT AMOUNT OF INCREASE (<0 VALUE ALLOWED)')
      READ(5,*)DELSUP
      DFCT(NODE)=DFCT(NODE)-DELSUP
140     WRITE(6,150)
150     FORMAT(' INPUT NODE NO. WHERE FLOW SUPPLY IS DECREASED')
      READ(5,*)NODE
      IF ((NODE.LE.0).OR.(NODE.GT.N)) GO TO 140
      DFCT(NODE)=DFCT(NODE)+DELSUP

```

```

ELSE IF (SEL.EQ.2) THEN
C
C CHANGE ARC FLOW CAPACITY.
C [NOTE: U IS THE RESIDUAL CAPACITY, I.E., U = CAPACITY - X.]
C
160   WRITE(6,170)
170   FORMAT('INPUT ARC NO. AND THE INCREASE IN UPPER BOUND')
      READ(5,*)ARC,DELUB
      IF ((ARC.LE.0).OR.(ARC.GT.NA)) GO TO 160
      IF (RC(ARC).LT.0) THEN
C
C ARC IS ACTIVE, SO MAINTAIN FLOW AT (NEW) CAPACITY.
C
        DFCT(STARTN(ARC))=DFCT(STARTN(ARC))+DELUB
        DFCT(ENDN(ARC))=DFCT(ENDN(ARC))-DELUB
        X(ARC)=X(ARC)+DELUB
        IF (X(ARC).LT.0) WRITE(6,180)
      ELSE IF (RC(ARC).EQ.0) THEN
        IF (U(ARC).GE.-DELUB) THEN
          U(ARC)=U(ARC)+DELUB
        ELSE
C
C NEW CAPACITY IS LESS THAN CURRENT FLOW, SO DECREASE
C FLOW TO NEW CAPACITY.
C
          DEL=-DELUB-U(ARC)
          DFCT(STARTN(ARC))=DFCT(STARTN(ARC))-DEL
          DFCT(ENDN(ARC))=DFCT(ENDN(ARC))+DEL
          X(ARC)=X(ARC)-DEL
          IF (X(ARC).LT.0) WRITE(6,180)
          U(ARC)=0
        END IF
      ELSE
        U(ARC)=U(ARC)+DELUB
        IF (U(ARC).LT.0) WRITE(6,180)
      END IF
    ELSE IF (SEL.EQ.3) THEN
C
C CHANGE ARC COST.
C
    180   FORMAT('FLOW UPPER BOUND IS NOW < 0')
    END IF
  ELSE IF (SEL.EQ.3) THEN
C
C CHANGE ARC COST.
C
    190   WRITE(6,200)
    200   FORMAT('INPUT ARC NO. & INCREASE IN COST')
      READ(5,*)ARC,DELC
      IF ((ARC.LE.0).OR.(ARC.GT.NA)) GO TO 190
      IF ((RC(ARC).GE.0).AND.(RC(ARC)+DELC.LT.0)) THEN

```

```

C
C ARC BECOMES ACTIVE, SO INCREASE FLOW TO CAPACITY.
C
    DFCT(STARTN(ARC))=DFCT(STARTN(ARC))+U(ARC)
    DFCT(ENDN(ARC))=DFCT(ENDN(ARC))-U(ARC)
    X(ARC)=U(ARC)+X(ARC)
    U(ARC)=0
    ELSE IF ((RC(ARC).LE.0).AND.(RC(ARC)+DELC.GT.0))THEN
C
C ARC BECOMES INACTIVE, SO DECREASE FLOW TO ZERO.
C
    DFCT(STARTN(ARC))=DFCT(STARTN(ARC))-X(ARC)
    DFCT(ENDN(ARC))=DFCT(ENDN(ARC))+X(ARC)
    U(ARC)=U(ARC)+X(ARC)
    X(ARC)=0
    END IF
    RC(ARC)=RC(ARC)+DELC
    C(ARC)=C(ARC)+DELC
C
C IF ARC BECOMES BALANCED, CHECK TO ADD ARC TO TFSTOU,
TFSTIN,....
C
    IF ((RC(ARC).EQ.0).AND.(DELC.NE.0)) THEN
        CALL ADDR(ARC)
    END IF
C
    ELSE IF ((SEL.EQ.4).OR.(SEL.EQ.6)) THEN
C
C DELETE AN ARC.
C
    IF (SEL.EQ.6) THEN
        IF (.NOT.ADDARC) GO TO 20
        ADDARC=.FALSE.
        ARC=AARC
    ELSE
        210   WRITE(6,220)
        220   FORMAT('INPUT ARC NO. FOR DELETION')
        READ(5,*)ARC
        IF ((ARC.LE.0).OR.(ARC.GT.NA)) GO TO 210
        DELARC=.TRUE.
        DARC=ARC
        DU=U(ARC)+X(ARC)
    END IF
C
C REMOVE ARC FROM THE ARRAY FIN, FOU, NXTIN, NXTOU.
C

```

```

ARC1=FOU(STARTN(ARC))
IF (ARC1.EQ.ARC) THEN
  FOU(STARTN(ARC))=NXTOU(ARC1)
ELSE
230   ARC2=NXTOU(ARC1)
  IF (ARC2.EQ.ARC) THEN
    NXTOU(ARC1)=NXTOU(ARC2)
    GO TO 240
  END IF
  ARC1=ARC2
  IF (NXTOU(ARC1).GT.0) GO TO 230
END IF

240   ARC1=FIN(ENDN(ARC))
  IF (ARC1.EQ.ARC) THEN
    FIN(ENDN(ARC))=NXTIN(ARC1)
  ELSE
250   ARC2=NXTIN(ARC1)
  IF (ARC2.EQ.ARC) THEN
    NXTIN(ARC1)=NXTIN(ARC2)
    GO TO 260
  END IF
  ARC1=ARC2
  IF (NXTIN(ARC1).GT.0) GO TO 250
END IF

C
C REMOVE ARC FROM THE ARRAY TFSTIN, TFSTOU, TNXTIN, TNXTOU.
C

260   ARC1=TFSTOU(STARTN(ARC))
  IF (ARC1.EQ.0) GO TO 262
  IF (ARC1.EQ.ARC) THEN
    TFSTOU(STARTN(ARC))=TNXTOU(ARC1)
  ELSE
261   ARC2=TNXTOU(ARC1)
  IF (ARC2.EQ.ARC) THEN
    TNXTOU(ARC1)=TNXTOU(ARC2)
    GO TO 262
  END IF
  ARC1=ARC2
  IF (TNXTOU(ARC1).GT.0) GO TO 261
END IF

262   ARC1=TFSTIN(ENDN(ARC))
  IF (ARC1.EQ.0) GO TO 264
  IF (ARC1.EQ.ARC) THEN
    TFSTIN(ENDN(ARC))=TNXTIN(ARC1)
  ELSE
263   ARC2=TNXTIN(ARC1)

```

```

        IF (ARC2.EQ.ARC) THEN
          TNXTIN(ARC1)=TNXTIN(ARC2)
          GO TO 264
        END IF
        ARC1=ARC2
        IF (TNXTIN(ARC1).GT.0) GO TO 263
      END IF
264    TNXTOU(ARC) = -1
      TNXTIN(ARC) = -1
C
C    REMOVE FLOW OF ARC FROM NETWORK BY SETTING ITS FLOW
C    AND CAPACITY TO 0.
C
      DFCT(STARTN(ARC))=DFCT(STARTN(ARC))-X(ARC)
      DFCT(ENDN(ARC))=DFCT(ENDN(ARC))+X(ARC)
      X(ARC)=0
      U(ARC)=0
      ELSE IF ((SEL.EQ.5).OR.(SEL.EQ.7)) THEN
        IF (SEL.EQ.7) THEN
          IF (.NOT.DELARC) GO TO 20
          IARC=DARC
          IH=STARTN(IARC)
          IT=ENDN(IARC)
          DELARC=.FALSE.
          IU=DU
        ELSE
270      WRITE(6,280)NA+1
280      FORMAT(' INPUT HEAD & TAIL NODES OF NEW ARC',I8)
      READ(5,*)IH,IT
      IF ((IH.LE.0).OR.(IH.GT.N).OR.(IT.LE.0).OR.(IT.GT.N))GO TO 270
290      WRITE(6,300)
300      FORMAT(' INPUT COST & FLOW UPPER BD')
      READ(5,*)IC,IU
      IF (IU.LT.0) GO TO 290
      ADDARC=.TRUE.
      AARC=NA+1
      NA=NA+1
      C(NA)=IC
      STARTN(NA)=IH
      ENDN(NA)=IT
      IARC=NA
      END IF
C
C    DETERMINE THE DUAL PRICES AT IH AND IT:
C    FIRST SET THE PRICE AT IH TO ZERO AND THEN CONSTRUCT THE
C    PRICE AT OTHER NODES BY BREADTH-FIRST SEARCH AND USING

```

C THE FACT THAT
C $RC(ARC) = C(ARC) - PRICE(STARTN(ARC)) + PRICE(ENDN(ARC))$.
C THE NETWORK (GIVEN BY FOU, NXTOU, FIN, NXTIN) NEED NOT BE
CONNECTED.

C

```
NSCAN=0
NLABEL=1
LABEL(1)=IH
PRICE(IH)=0
DO 310 I=1,N
310  MARK(I)=.FALSE.
      MARK(IH)=.TRUE.
320  IF (NLABEL.GT.NSCAN) THEN
      NSCAN=NSCAN+1
      NODE=LABEL(NSCAN)
      ARC=FOU(NODE)
330  IF (ARC.GT.0) THEN
      NODE2=ENDN(ARC)
      IF (.NOT.MARK(NODE2)) THEN
          MARK(NODE2)=.TRUE.
          PRICE(NODE2)=RC(ARC)-C(ARC)+PRICE(NODE)
          IF (NODE2.EQ.IT) GO TO 370
          NLABEL=NLABEL+1
          LABEL(NLABEL)=NODE2
      END IF
      ARC=NXTOU(ARC)
      GO TO 330
  END IF
  ARC=FIN(NODE)
340  IF (ARC.GT.0) THEN
      NODE2=STARTN(ARC)
      IF (.NOT.MARK(NODE2)) THEN
          MARK(NODE2)=.TRUE.
          PRICE(NODE2)=C(ARC)-RC(ARC)+PRICE(NODE)
          IF (NODE2.EQ.IT) GO TO 370
          NLABEL=NLABEL+1
          LABEL(NLABEL)=NODE2
      END IF
      ARC=NXTIN(ARC)
      GO TO 340
  END IF
  GO TO 320
END IF
PRICE(IT)=-C(IARC)
```

C

C COMPUTE REDUCED COST OF THE NEW ARC AND UPDATE FLOW AND DEFICIT

C ACCORDINGLY.

C

370 RC(IARC)=C(IARC)+PRICE(IT)

IF (RC(IARC).LT.0) THEN

DFCT(IH)=DFCT(IH)+IU

DFCT(IT)=DFCT(IT)-IU

X(IARC)=IU

U(IARC)=0

ELSE

X(IARC)=0

U(IARC)=IU

END IF

NXTOU(IARC)=FOU(IH)

FOU(IH)=IARC

NXTIN(IARC)=FIN(IT)

FIN(IT)=IARC

IF (RC(IARC).EQ.0) THEN

TNXTOU(IARC)=TFSTOU(IH)

TFSTOU(IH)=IARC

TNXTIN(IARC)=TFSTIN(IT)

TFSTIN(IT)=IARC

END IF

END IF

GO TO 20

END

C

C

SUBROUTINE ADDTR(ARC)

IMPLICIT INTEGER (A-Z)

C

C-----

C

C PURPOSE - THIS SUBROUTINE CHECKS IF ARC IS IN THE ARRAYS
TFSTOU, TNXTOU,

C TFSTIN, TNXTIN AND, IF NOT, ADDS ARC TO THEM.

C

C-----

C

C MAXNN = DIMENSION OF NODE-LENGTH ARRAYS

C MAXNA = DIMENSION OF ARC-LENGTH ARRAYS

C

PARAMETER (MAXNN=10000, MAXNA=70000)

C

COMMON/ARRAYS/STARTN/ARRAYE/ENDN

```

COMMON/BLK10/TFSTOU/BLK11/TNXTOU/BLK12/TFSTIN/BLK13/TNXTIN
INTEGER STARTN(MAXNA),ENDN(MAXNA)
INTEGER
TFSTOU(MAXNN),TNXTOU(MAXNA),TFSTIN(MAXNN),TNXTIN(MAXNA)
C
NODE=STARTN(ARC)
ARC1=TFSTOU(NODE)
10 IF (ARC1.GT.0) THEN
    IF (ARC1.EQ.ARC) GO TO 20
    ARC1=TNXTOU(ARC1)
    GO TO 10
END IF
TNXTOU(ARC)=TFSTOU(NODE)
TFSTOU(NODE)=ARC
20 NODE=ENDN(ARC)
ARC1=TFSTIN(NODE)
30 IF (ARC1.GT.0) THEN
    IF (ARC1.EQ.ARC) RETURN
    ARC1=TNXTIN(ARC1)
    GO TO 30
END IF
TNXTIN(ARC)=TFSTIN(NODE)
TFSTIN(NODE)=ARC
RETURN
END
C

```

GRAPHICAL USER INTERFACE CODE

The following codes are individual files that use the output from the Relax-IV solution set to produce the output for the OffSite software.

```

/*-----
statbar.cpp
-----*/
#include <windows.h>
#include <commctrl.h>

DWORD dwStatusBarStyles = WS_CHILD |  

    WS_VISIBLE |  

    WS_CLIPSIBLINGS |  

    CCS_BOTTOM |  

    SBARS_SIZEGRIP ;  
  

HWND init_status_bar (HWND hwndParent)  

{

```

```

HWND hwndSB ;

hwndSB = CreateStatusBar (dwStatusBarStyles,
                         "",
                         hwndParent,
                         2) ;
return hwndSB ;
}

#ifndef __conf_macros_h__
#define __conf_macros_h__

#define min(a,b) ((a)<(b) ? (a) : (b))
#define max(a,b) ((a)>(b) ? (a) : (b))

#endif

void lat_long_to_x_y(
    double origin_lat, // in decimal degrees
    double origin_long, // in decimal degrees
    double pt_lat, // lat of a point in decimal deg
    double pt_long, // long of a point in decimal deg
    double *x_coord,
    double *y_coord
);

void rhumbline_latlong_to_range_bear(
    double lat1, // 1st pt latitude in decimal degrees
    double long1, // 1st pt longitude in decimal degrees
    double lat2, // 2nd pt latitude in decimal degrees
    double long2, // 2nd pt longitude in decimal degrees
    double *range, // in kilometers
    double *bearing // from pt 1 to pt 2 in degrees
);

#include <math.h>
#include "constants.h"
#include "lat_long.h"

/*
Function: lat_long_to_x_y

```

File: lat_long.cpp

Description: lat_long_to_x_y converts a specific latitude and longitude to rectangular coordinates x and y.

```

*/
```

```

void lat_long_to_x_y(
    double origin_lat, // in decimal degrees
    double origin_long, // in decimal degrees
    double pt_lat, // lat of a point in decimal deg
    double pt_long, // long of a point in decimal deg
    double *x_coord,
    double *y_coord)
{
    double distance;
    double bearing;
    double theta;

    // Get the distance and bearing from the origin to the point
    rhumbline_latlong_to_range_bear(origin_lat, origin_long, pt_lat, pt_long,
                                    &distance, &bearing);

    // Convert direction from bearing to standard notation measured
    // counterclockwise from east

    theta = 450. - bearing;

    if (theta >= 360.) theta -= 360.;

    theta /= DEG_PER_RAD; // convert direction to radians

    // Convert polar coordinates to rectangular coordinates

    *x_coord = distance * cos(theta);
    *y_coord = distance * sin(theta);

} // end of lat_long_to_x_y
```

```

/*
Function: rhumbline_latlong_to_range_bear

Description: rhumbline_latlong_to_range_bear calculates the rhumbline
             distance and bearing between two points.
*/

```

```

void rhumbline_latlong_to_range_bear(
    double lat1, // 1st pt latitude in decimal degrees
              double long1, // 1st pt longitude in decimal degrees
    double lat2, // 2nd pt latitude in decimal degrees
              double long2); // 2nd pt longitude in decimal degrees
```

```

        double long2, // 2nd pt longitude in decimal degrees
        double *range, // in kilometers
        double *bearing) // from pt 1 to pt 2 in degrees
{
    double delta_lat;
    double delta_long;
    double cosine_lat1;
    double cosine_lat2;
    double delta_y;
    double delta_x;
    double prelim_delta_x;

    delta_lat = lat2 - lat1;
    delta_long = long2 - long1;

    // Convert the input coordinates to radians

    lat1 /= DEG_PER_RAD;
    lat2 /= DEG_PER_RAD;
    long1 /= DEG_PER_RAD;
    long2 /= DEG_PER_RAD;

    if (delta_lat == 0. && delta_long == 0.)
    {
        *range = 0.;
        *bearing = 0.;
        return;
    }

    cosine_lat1 = cos(lat1);
    cosine_lat2 = cos(lat2);

    if (delta_long > 180.0)
    {
        delta_long -= TWO_PI;
    }
    else
    {
        if (delta_long < -180.0)
            delta_long += TWO_PI;
    }

    // Convert from degrees to nautical miles

    delta_y = delta_lat * NM_PER_DEG;
    prelim_delta_x = delta_long * NM_PER_DEG;
}

```

```

// Correct for longitude

delta_x = prelim_delta_x * ((cosine_lat1 + cosine_lat2) * 0.5);

// Calculate the range and convert to Kilometers

*range = sqrt((delta_x * delta_x) + (delta_y * delta_y));
*range *= KM_PER_NM;

// Calculate the bearing

if (delta_y != 0.)
{
    *bearing = atan2(delta_x, delta_y);
}
else
{
    if (delta_x > 0.)
        *bearing = M_PI / 2.0;
    else
        *bearing = -M_PI / 2.0;
}

// Convert to degrees

*bearing *= DEG_PER_RAD;

if (*bearing < 0.)
    *bearing += 360.0;

} // end of rhumbline_latlong_to_range_bear

/*
FILE:      TLIST.H

DESCRIPTION: This file contains the generic class definition of the doubly
linked list.

*/
#ifndef __tlist_h__
#define __tlist_h__

template <class T> class _CLASSTYPE TEntry
{
public:

```

```

T      *Data;
TEntry *Next;
TEntry *Previous;

TEntry(T *);
virtual ~TEntry(void);
};

template <class T> class _CLASSTYPE TList
{
protected:
    int    NumberEntries;
    TEntry<T> *head;
    TEntry<T> *tail;

public:
    TList(void);
    virtual ~TList(void);
    virtual void AddEntry(T *);
    virtual void ClearList(void);
    void Initialize(void);
    int GetNumberEntries(void) { return NumberEntries; } ;
    virtual T *GetEntry(int);
    virtual T *RemoveEntry(TEntry<T> *);
    virtual T *RemoveNextEntry(void);
};

template <class T> class _CLASSTYPE TPathList : public TList<T>
{
public:
    virtual void Draw(int, int, HDC, BOOL, HPEN *);
};

template <class T> class _CLASSTYPE TMapEntityList : public TList<T>
{
public:
    virtual void Draw(HDC, BOOL, HPEN *);
};

//-----
// TEntry's method implementations:
//-----

template <class T> TEntry<T>::TEntry(T *new_data)
{
    Data = new_data;
}

```

```

    Next = NULL;
    Previous = NULL;
}

template <class T> TEntry<T>::~TEntry(void)
{
}

//-----
// TList's method implementations:
//-----

template <class T> TList<T>::TList(void)
{
    // Initialize the list

    head = NULL;
    tail = NULL;
    NumberEntries = 0;
}

template <class T> TList<T>::~TList(void)
{
    ClearList();
}

template <class T> void TList<T>::ClearList(void)
{
    T *the_data;

    // Clear the list

    while ((the_data = RemoveNextEntry()) != NULL)
    {
        delete the_data;
    }
}

template <class T> void TList<T>::Initialize(void)
{
    // Initialize the list

    head = NULL;
    tail = NULL;
    NumberEntries = 0;
}

```

```

template <class T> T *TList<T>::GetEntry(int the_position)
{
    int      i;      // current position in the list
    TEntry<T> *the_entry; // pointer for traversing the list

    i = 1;
    the_entry = head;

    while(i < the_position)
    {
        i++;
        the_entry = the_entry->Next;
    }

    return(the_entry->Data);
}

template <class T> T *TList<T>::RemoveEntry(TEntry<T> *del_entry)
{
    T *the_data;

    if (del_entry == NULL)
    {
        the_data = NULL;
    }
    else
    {
        the_data = del_entry->Data;

        if ( del_entry->Previous != NULL )
            del_entry->Previous->Next = del_entry->Next;
        else
            head = del_entry->Next;

        if ( del_entry->Next != NULL )
            del_entry->Next->Previous = del_entry->Previous;
        else
            tail = del_entry->Previous;

        // The list's links are in place, free the removed entry and decrement
        // the counter.

        delete del_entry;
        --NumberEntries;
    }
}

```

```

    return(the_data);

}

template <class T> T *TList<T>::RemoveNextEntry(void)
{
    TEntry<T> *the_entry; // next entry to return
    T      *the_data;

    // Get the first entry in the list

    the_entry = head;

    // If the list is empty, return a NULL pointer

    if (the_entry == NULL)
    {
        the_data = NULL;
    }
    else
    {
        the_data = the_entry->Data;

        // If there are more entries in the list, the next entry becomes the
        // first entry and its previous_entry link no longer points to an
        // entry. If the list is empty, however, the list's tail link no
        // longer points to an entry.

        head = the_entry->Next;
        if (head != NULL)
        {
            head->Previous = NULL;
        }
        else
        {
            tail = NULL;
        }

        // The list's links are in place, free the removed entry and decrement
        // the counter.

        delete the_entry;
        --NumberEntries;
    }
}

```

```

    return(the_data);

}

template <class T> void TList<T>::AddEntry(T *new_data)
{
    TEntry<T> *new_entry;
    TEntry<T> *entry_ptr; // pointer for traversing the list

    // Create a new entry and increment the counter

    new_entry = new TEntry<T>(new_data);
    ++NumberEntries;

    // If the list is empty, set the head and tail pointers to the new entry.

    if (head == NULL)
    {
        head = new_entry;
        tail = new_entry;
    }
    else
    {
        // Add the new entry to the back of the list

        entry_ptr = tail;

        // Set the new entry's pointers

        new_entry->Next = entry_ptr->Next;
        new_entry->Previous = entry_ptr;

        // Link the new entry

        entry_ptr->Next = new_entry;
        tail = new_entry;
    }
}

#endif

#include <windows.h>
#include "map_entity.h"

map_entity :: map_entity(unsigned entity_type, unsigned size)

```

```

{
unsigned i;

type = entity_type;
number_of_pts = size;

if ((pt = new POINT[size]) == NULL)
{
    MessageBox (NULL, "Unable to allocate pt array - out of memory", "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

for(i = 0; i < size; i++)
    pt[i].x = pt[i].y = 0;
}

map_entity :: ~map_entity(void)
{
    delete [] pt;
}

void map_entity :: set_xy_coord(unsigned index, long x, long y)
{
    pt[index].x = x;
    pt[index].y = y;
}

#include <windows.h>
#include "offsite.h"

template <class T> void TMapEntityList<T>::Draw(HDC hdc, BOOL show,
                                                HPEN *hPen)
{
    TEntry<T> *entry_ptr;
    map_entity *me;
    POINT *pt;

    if (!show) return;

    entry_ptr = head;

    while (entry_ptr != NULL)
    {
        me = entry_ptr->Data;
        pt = me->get_pt();

```

```

    SelectObject(hdc, hPen[PEN_BLACK]);
    Polyline(hdc, pt, me->get_number_of_pts());

    entry_ptr = entry_ptr->Next;
}

#include <windows.h>
#include "offsite.h"

template <class T> void TPPathList<T>::Draw(int start, int destin,
                                              HDC hdc, BOOL show_names,
                                              HPEN *hPen)
{
    TEntry<T> *entry_ptr;
    int index;
    int node1, node2;
    RECT rect;

    entry_ptr = head;

    if (start < destin)
    {
        index = destin - start;
        if (G_node_array[start].cost[index].is_drive_cost)
        {
            SelectObject(hdc, hPen[PEN_BLUE]);
            MoveToEx(hdc, (int) G_node_array[start].x, (int) G_node_array[start].y, NULL);
            LineTo(hdc, (int) G_node_array[destin].x, (int) G_node_array[destin].y);
            return;
        }
    }
    else
    {
        index = start - destin;
        if (G_node_array[destin].cost[index].is_drive_cost)
        {
            SelectObject(hdc, hPen[PEN_BLUE]);
            MoveToEx(hdc, (int) G_node_array[start].x, (int) G_node_array[start].y, NULL);
            LineTo(hdc, (int) G_node_array[destin].x, (int) G_node_array[destin].y);
            return;
        }
    }
}

```

```

while (entry_ptr != NULL)
{
    node1 = entry_ptr->Data->node1;
    node2 = entry_ptr->Data->node2;

    SelectObject(hdc, hPen[PEN_BLUE]);
    MoveToEx(hdc, (int) G_node_array[node1].x, (int) G_node_array[node1].y, NULL);
    LineTo(hdc, (int) G_node_array[node2].x, (int) G_node_array[node2].y);

    SelectObject(hdc, hPen[PEN_GREEN]);
    if ((node1 != start) && (node1 != destin))
    {
        rect.left = (long) G_node_array[node1].x - 20 ;
        rect.top = (long) G_node_array[node1].y + 20 ;
        rect.right = (long) G_node_array[node1].x + 20 ;
        rect.bottom = (long) G_node_array[node1].y - 20 ;

        Ellipse ( hdc, rect.left, rect.top, rect.right, rect.bottom ) ;

        if (show_names)
        {
            TextOut(hdc, rect.left, rect.top, G_node_array[node1].rics,
                    strlen(G_node_array[node2].rics)) ;
        }
    }

    if ((node2 != start) && (node2 != destin))
    {
        rect.left = (long) G_node_array[node2].x - 20 ;
        rect.top = (long) G_node_array[node2].y + 20 ;
        rect.right = (long) G_node_array[node2].x + 20 ;
        rect.bottom = (long) G_node_array[node2].y - 20 ;

        Ellipse ( hdc, rect.left, rect.top, rect.right, rect.bottom ) ;

        if (show_names)
        {
            TextOut(hdc, rect.left, rect.top, G_node_array[node2].rics,
                    strlen(G_node_array[node2].rics)) ;
        }
    }

    entry_ptr = entry_ptr->Next;
}

}

```

```

#include <iostream.h>
#include <dir.h>
#include <stdio.h>
#include <stdlib.h>
#include "offsite.h"

void determine_travel_costs(void)
{
FILE *cost_fp;
int i, j;
int node_index;
char message[256];

if ((cost_fp = fopen(G_cost_filename, "w")) == NULL)
{
    sprintf (message, "Can't open output file %s", G_cost_filename) ;
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING ) ;
    return;
}

G_number_sites = 0;

for (i = 1; i <= G_number_nodes; i++)
{
    G_best_sites[i].cost = -1;
}

for (i = 1; i <= G_number_nodes; i++)
{
    if (G_node_array[i].is_site)
    {
        int cost = 0;
        fprintf(cost_fp,
                "Conference site: %s (%s, %s)\n\n",
                G_node_array[i].rics, G_node_array[i].city,
                state_code[G_node_array[i].state]);
        fprintf(cost_fp,
                "      # of   |     Costs\n");
        fprintf(cost_fp,
                " Node | Participants | Travel | Meals | Lodging | Total\n");
    }

    for (j = 1; j <= G_number_nodes; j++)
    {
        if (G_node_array[j].participants_solve)
        {
            cost += tdy_cost_to_site(i, j, cost_fp);
        }
    }
}

```

```

        }
    }
    fprintf(cost_fp,
            "-----\n");
    fprintf(cost_fp,
            " Total %10.2f\n\n",
            (float) cost);

if (G_number_sites)
{
    for (j = 1; j <= G_number_sites; j++)
    {
        if (cost < G_best_sites[j].cost)
        {
            for (int k = G_number_sites+1; k >= j+1; k--)
            {
                int prev_index = k-1;
                G_best_sites[k].site = G_best_sites[prev_index].site;
                G_best_sites[k].cost = G_best_sites[prev_index].cost;
            }

            G_best_sites[j].site = i;
            G_best_sites[j].cost = cost;

            break;
        }
    }

    if (j > G_number_sites)
    {
        G_best_sites[j].site = i;
        G_best_sites[j].cost = cost;
    }
}
else
{
    G_best_sites[1].site = i;
    G_best_sites[1].cost = cost;
}

G_number_sites++;
}

if (G_number_sites > 1)
{

```

```

if (G_number_sites > 10)
    fprintf(cost_fp, " Ten Best Sites\n");
else
    fprintf(cost_fp, " Cost to Sites\n");

fprintf(cost_fp, " Site | Cost\n");
for (i = 1; i <= G_number_sites && i <= 10; i++)
{
    node_index = G_best_sites[i].site;

    fprintf(cost_fp, " %4s | %10.2f\n",
            G_node_array[node_index].rics, (float) G_best_sites[i].cost);
}
}
else
{
    node_index = G_best_sites[G_number_sites].site;
    fprintf(cost_fp, " Cost to %s: %10.2f\n",
            G_node_array[node_index].rics,
            (float) G_best_sites[G_number_sites].cost);
}
fclose(cost_fp);
}

int tdy_cost_to_site(unsigned site, unsigned origin, FILE *cost_fp)
{
int tot_cost;
int travel_cost = 0;
int meals_travel;
int meals = 0;
int lodging = 0;
unsigned char cost_is_for_driving;

fprintf(cost_fp, " %4s | %4d |",
       G_node_array[origin].rics, G_node_array[origin].participants_solve);

if (site != origin)
{
    int index;
    if (origin < site )
    {
        index = site - origin;
        travel_cost = G_node_array[origin].cost[index].amount;
        cost_is_for_driving = G_node_array[origin].cost[index].is_drive_cost;
    }
    else

```

```

{
index = origin - site;
travel_cost = G_node_array[site].cost[index].amount;
cost_is_for_driving = G_node_array[site].cost[index].is_drive_cost;
}
}

tot_cost = G_node_array[origin].participants_solve * 2 * travel_cost;

fprintf(cost_fp, " %10.2f !", (float) tot_cost);

if (site != origin)
{
if (cost_is_for_driving)
{
lodging = G_node_array[site].lodging *
G_node_array[origin].participants_solve *
(G_conf_duration - 1);

if (G_conf_duration > 1)
{
meals_travel = (float) 0.75 * (float) G_node_array[site].meals *
(float) G_node_array[origin].participants_solve *
(float) 2.0;
meals = meals_travel +
(G_node_array[site].meals *
G_node_array[origin].participants_solve *
(G_conf_duration - 2));
}
else
{
meals_travel = (float) 0.75 * (float) G_node_array[site].meals *
(float) G_node_array[origin].participants_solve;
meals = meals_travel;
}
}
else
{
lodging = G_node_array[site].lodging *
G_node_array[origin].participants_solve * G_conf_duration;

meals_travel = (float) 0.75 * (float) G_node_array[site].meals *
(float) G_node_array[origin].participants_solve *
(float) 2.0;

if (G_conf_duration > 1)
}
}

```

```

    {
        meals = meals_travel +
            (G_node_array[site].meals *
                G_node_array[origin].participants_solve *
                (G_conf_duration - 1));
    }
}

tot_cost += meals + lodging;

fprintf(cost_fp, " %10.2f | %10.2f | %10.2f\n",
    (float) meals, (float) lodging, (float) tot_cost);

return tot_cost;
}

#include <iostream.h>
#include <ctype.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "offsite.h"
#include "read.h"
#include "lat_long.h"
#include "constants.h"
#include "macros.h"

#define TOKEN_NOT_VALID 0
#define TOKEN_WEST_COAST_DATA 1
#define TOKEN_EAST_COAST_DATA 2
#define TOKEN_CONFERENCE_PARTICIPANT_DATA 3

static float min_lat, max_lat, min_long, max_long, center_lat, center_long;

```

/*
Function: is_comment

Date: January 1995

Programmer: David J. Ward

Description:

This function determines if the supplied text is considered a comment line. A comment line is an input line that is empty or

begins with the '#' character.

Modifications:

```
/*
int is_comment(char *token)
{
    int index, length;

    /* If a null pointer is passed in return as if the line was a comment */
    if (token == NULL) return 1;

    /* Get the length of the text that was passed in to this function */
    length = (int) strlen(token);

    /* If this is a blank line */
    if (length == 0) return 1;

    /* starting at the begining of the text determine if this line is a comment */
    for (index = 0; index < length; index++)
    {
        /* if the character is white space continue to the next character */
        if (isspace(token[index])) continue;

        /* if we encounter a '#' then this line is a comment */
        if (token[index] == '#') return 1;

        /* if we reach the end of the text the line must have been blank */
        if (token[index] == '\0') return 1;

        /* If we have encontered a non-white space character and it wasn't
           a '#' or '\0', which was checked above, this line is not a
           comment line so we return 0. */
        return 0;
    }
}

/*
Function:    is_token
```

Date: January 1995

Programmer: David J. Ward

Description:

This function determines if the first word of the input text is one of the recognized tokens. If it is the token value is returned.

Modifications:

```
*/  
int is_token(char *text)  
{  
    char token[256];  
  
    sscanf(text, "%s", token);  
  
    if (strcmp(token, "WestCoast") == 0)  
        return TOKEN_WEST_COAST_DATA;  
    if (strcmp(token, "EastCoast") == 0)  
        return TOKEN_EAST_COAST_DATA;  
    if (strcmp(token, "NumberOfParticipants") == 0)  
        return TOKEN_CONFERENCE_PARTICIPANT_DATA;  
    return TOKEN_NOT_VALID;  
}  
  
void parse_arc_line(int line_number, char *buf)  
{  
    static int index = 0;  
    int start, end, cost;  
  
    index++;  
  
    if (sscanf(buf, "%d%d%d", &start, &end, &cost) != 3)  
    {  
        cout << "Unrecognizable arc data specified at line "  
            << line_number << endl;  
        return;  
    }  
  
    if (start < 1 || start > G_number_nodes)  
    {  
        cout << "Arc " << index << " has out of bounds start node ID "  
            << start << " specified at line " << line_number << endl;  
        return;  
    }  
  
    G_arc_array[index].start_node = start;
```

```

if (end < 1 || end > G_number_nodes)
{
    cout << "Arc " << index << " has out of bounds end node ID "
        << end << " specified at line " << line_number << endl;
    return;
}

G_arc_array[index].end_node = end;
G_arc_array[index].cost = cost;

}

void parse_conference_duration_line(int line_number, char *buf)
{
    if (sscanf(buf, "%d", &G_conf_duration) != 1)
        cout << "Unrecognizable conference duration specified at line "
            << line_number << endl;
}

void parse_conference_site_line(int line_number, char *buf)
{
    char airport_id[128];
    int hash_val;
    int node_id;

    if (sscanf(buf, "%s", &airport_id) != 1)
    {
        cout << "Unrecognizable airport ID specified at line"
            << line_number << endl;
        return;
    }

    if ((hash_val = G_airports->find_entry_in_lookup_table(airport_id)) == -1)
    {
        cout << "Unknown airport ID " << airport_id << " specified at line "
            << line_number << endl;
        return;
    }

    node_id = G_airports->get_node_id(hash_val);
    G_node_array[node_id].is_site = TRUE;
}

void parse_drive_cost_line(int line_number, char *buf)
{
    int start, end;
}

```

```

int drive_cost;
float distance;
int index;

if (sscanf(buf, "%d%d%f%d",
           &start, &end, &distance, &drive_cost) != 4)
{
    cout << "Unrecognizable cost data specified at line "
         << line_number << endl;
    return;
}

if (start < 1 || start > G_number_nodes)
{
    cout << "Out of bounds start node ID " << start << " specified at line "
         << line_number << endl;
    return;
}

if (end < 1 || end > G_number_nodes)
{
    cout << "Out of bounds end node ID " << start << " specified at line "
         << line_number << endl;
    return;
}

if (start < end)
{
    index = end - start;
    G_node_array[start].cost[index].amount = drive_cost;
    G_node_array[start].cost[index].is_drive_cost = TRUE;
}
else
{
    index = start - end;
    G_node_array[end].cost[index].amount = drive_cost;
    G_node_array[end].cost[index].is_drive_cost = TRUE;
}
}

void parse_flight_cost_line(int line_number, char *buf)
{
int origin, destin;
float fcost;

if (sscanf(buf, "%d%d%f", &origin, &destin, &fcost) != 3)

```

```

    {
        cout << "Unrecognizable cost data specified at line "
            << line_number << endl;
    return;
}

if (destin > origin)
{
    int index = destin - origin;

    G_node_array[origin].cost[index].amount = (unsigned) fcost;
}

void parse_node_line(int line_number, char *buf)
{
int node;
int lat_deg, lat_min, lat_sec, lat_dec_sec;
int long_deg, long_min, long_sec, long_dec_sec;
double x, y;

if (sscanf(buf, "%d%d%d%d%d%d%d",
            &node, &lat_deg, &lat_min, &lat_sec, &lat_dec_sec,
            &long_deg, &long_min, &long_sec, &long_dec_sec) != 9)
{
    cout << "Unrecognizable node data specified at line "
        << line_number << endl;
    return;
}

if (node < 1 || node > G_number_nodes)
{
    cout << "Out of bounds node ID " << node << " specified at line "
        << line_number << endl;
    return;
}

G_node_array[node].x = lat_deg + (lat_min / MINUTES_PER_DEGREE) +
    ((lat_sec + (ONE_THOUSANDTH * lat_dec_sec)) /
     SECONDS_PER_DEGREE);
G_node_array[node].y = long_deg + (long_min / MINUTES_PER_DEGREE) +
    ((long_sec + (ONE_THOUSANDTH * long_dec_sec)) /
     SECONDS_PER_DEGREE);

lat_long_to_x_y(center_lat, center_long,

```

```

        G_node_array[node].x, G_node_array[node].y, &x, &y);
G_node_array[node].x = x;
G_node_array[node].y = y;

// min_lat = min(min_lat, G_node_array[node].x);
// min_long = min(min_long, G_node_array[node].y);
// max_lat = max(max_lat, G_node_array[node].x);
// max_long = max(max_long, G_node_array[node].y);
}

void parse_per_diem_line(int line_number, char *buf)
{
int node;
int meals, lodging;
char *tokptr;
char state[3];
char city_name[12], short_name[10];
int hash_val, city_id;

tokptr = strtok(buf, " ");
node = atoi(tokptr);

if (node < 1 || node > G_number_nodes)
{
    cout << "Out of bounds node ID " << node << " specified at line "
        << line_number << endl;
    return;
}

skip_leading_whitespace(&tokptr);

tokptr = strtok(NULL, " ");
meals = atoi(tokptr);

if (meals < 0)
{
    cout << "Meal per diem for node " << node
        << " is not positive" << " at line " << line_number << endl;
    return;
}

G_node_array[node].meals = meals;

skip_leading_whitespace(&tokptr);

```

```

tokptr = strtok(NULL, " ");

lodging = atoi(tokptr);

if (lodging < 0)
{
    cout << "Lodging per diem for node " << node
        << " is not positive" << " at line " << line_number << endl;
    return;
}

G_node_array[node].lodging = lodging;

skip_leading_whitespace(&tokptr);

tokptr = strtok(NULL, " ");

strncpy(G_node_array[node].rics, tokptr, 3);

G_airports->insert_entry_in_lookup_table(tokptr, node);

tokptr = strtok(NULL, "");
tokptr = strtok(NULL, "");

strncpy(G_node_array[node].city, tokptr, 15);

memset(short_name, '\0', 10);
strncpy(short_name, G_node_array[node].city, 9);

skip_leading_whitespace(&tokptr);

tokptr = strtok(NULL, "\n");
strncpy(state, tokptr, 3);

if ((G_node_array[node].state = state_index(state)) == -1)
{
    cout << "Unknown state abbreviation for node " << node
        << " at line " << line_number << endl;
}

sprintf(city_name, "%s%s", short_name, state);
hash_val = G_cities->find_entry_in_lookup_table(city_name);

if (hash_val == -1)
{

```

```

city_id = ++G_number_cities;
hash_val = G_cities->insert_entry_in_lookup_table(city_name);
G_cities->set_city_id(hash_val, city_id);

strcpy(G_city_array[city_id].city, G_node_array[node].city);

if ((G_city_array[G_number_cities].airports = new TList<airport_record>) ==
NULL)
{
    MessageBox (NULL, "Unable to allocate airport list - out of memory",
               "", MB_OK | MB_ICONWARNING );
    exit(-1);
}
else
{
    city_id = G_cities->get_city_id(hash_val);
}

airport_record *new_airport = new airport_record;
if (new_airport == NULL)
{
    MessageBox (NULL, "Unable to allocate airport record - out of memory",
               "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

new_airport->id = node;
G_city_array[city_id].airports->AddEntry(new_airport);
G_city_array[city_id].state = G_node_array[node].state;
}

void read_arc_file(char *arc_filename)
{
FILE *arc_fp;
int i;
char message[256];
char input_line[1024];
char *bufptr;
int lineno = 0;

if ((arc_fp = fopen(arc_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", arc_filename);
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

```

```

}

fgets(input_line, sizeof(input_line), arc_fp);
sscanf(input_line, "%d %d", &G_number_nodes, &G_number_arcs);

G_arc_array = new arc[G_number_arcs+1];

if (G_arc_array == NULL)
{
    MessageBox (NULL, "Unable to allocate G_arc_array - out of memory", "",
               MB_OK | MB_ICONWARNING );
    exit(-1);
}

G_node_array = new node[G_number_nodes+1];

if (G_node_array == NULL)
{
    MessageBox (NULL, "Unable to allocate G_node_array - out of memory", "",
               MB_OK | MB_ICONWARNING );
    exit(-1);
}

for (i = 1; i <= G_number_nodes; i++)
{
    G_node_array[i].rics[0] = '\0';
    G_node_array[i].city[0] = '\0';
    G_node_array[i].state = 0;
    G_node_array[i].participants_temp = 0;
    G_node_array[i].participants_solve = 0;
    G_node_array[i].meals = 0;
    G_node_array[i].lodging = 0;
    G_node_array[i].is_site = FALSE;
    G_node_array[i].cost = NULL;
}

G_best_sites = new potential_site[G_number_nodes+1];

if (G_best_sites == NULL)
{
    MessageBox (NULL, "Unable to allocate G_best_sites - out of memory", "",
               MB_OK | MB_ICONWARNING );
    exit(-1);
}

for (i = 1; i <= G_number_nodes; i++)

```

```

{
G_best_sites[i].site = 0;
G_best_sites[i].cost = 0;
}

G_city_array = new city_and_airport[G_number_nodes+1];

if (G_city_array == NULL)
{
    MessageBox (NULL, "Unable to allocate G_city_array - out of memory", "",
               MB_OK | MB_ICONWARNING );
exit(-1);
}

for (i = 1; i <= G_number_nodes; i++)
{
    G_city_array[i].city[0] = '\0';
    G_city_array[i].airports = NULL;
}

cout << "Reading " << arc_filename << endl;

for(;;)
{
    // Get the next input line
    fgets(input_line, sizeof(input_line), arc_fp);
    lineno++;

    // If we are at the end of file break, out of this loop
    if (feof(arc_fp)) break;

    // Assign bufptr the base address of the input line
    bufptr = input_line;

    // Make sure bufptr is pointing to the first non-whitespace
    // character in the input line.
    skip_leading_whitespace(&bufptr);

    // If this line is a comment line continue to the next line
    if (is_comment(bufptr)) continue;

    parse_arc_line(lineno, bufptr);
}
cout << "Done with " << arc_filename << endl;
fclose(arc_fp);
}

```

```

void read_drive_cost(char *cost_filename)
{
FILE *cost_fp;
char message[256];
char input_line[1024];
char *bufptr;
int lineno = 0;

if ((cost_fp = fopen(cost_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", cost_filename);
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

cout << "Reading " << cost_filename << endl;

for(;;)
{
    // Get the next input line
    fgets(input_line, sizeof(input_line), cost_fp);
    lineno++;

    // If we are at the end of file break, out of this loop
    if (feof(cost_fp)) break;

    // Assign bufptr the base address of the input line
    bufptr = input_line;

    // Make sure bufptr is pointing to the first non-whitespace
    // character in the input line.
    skip_leading_whitespace(&bufptr);

    // If this line is a comment line continue to the next line
    if (is_comment(bufptr)) continue;

    parse_drive_cost_line(lineno, bufptr);
}
cout << "Done with " << cost_filename << endl;
fclose(cost_fp);
}

void read_flight_cost(char *cost_filename)
{
FILE *cost_fp;

```

```

int i;
char message[256];
char input_line[1024];
char *bufptr;
int lineno = 0;

if ((cost_fp = fopen(cost_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", cost_filename);
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING);
    exit(-1);
}

for (i = 1; i < G_number_nodes; i++)
{
    int number_of_destins = G_number_nodes - i;

    G_node_array[i].cost = new travel_cost[number_of_destins+1];

    if (G_node_array[i].cost == NULL)
    {
        MessageBox (NULL, "Unable to allocate cost array - out of memory", "",
                   MB_OK | MB_ICONWARNING);
        exit(-1);
    }

    for (int j = 1; j <= number_of_destins; j++)
    {
        G_node_array[i].cost[j].amount = 0;
        G_node_array[i].cost[j].is_drive_cost = FALSE;
        G_node_array[i].cost[j].path = new TPathList<transit_record>;

        if (G_node_array[i].cost[j].path == NULL)
        {
            MessageBox (NULL, "Unable to allocate path list - out of memory", "",
                       MB_OK | MB_ICONWARNING);
            exit(-1);
        }
    }
}

G_node_array[0].cost = G_node_array[G_number_nodes].cost = NULL;

cout << "Reading " << cost_filename << endl;

for(;;)

```

```

{
// Get the next input line
fgets(input_line, sizeof(input_line), cost_fp);
lineno++;

// If we are at the end of file break, out of this loop
if (feof(cost_fp)) break;

// Assign bufptr the base address of the input line
bufptr = input_line;

// Make sure bufptr is pointing to the first non-whitespace
// character in the input line.
skip_leading_whitespace(&bufptr);

// If this line is a comment line continue to the next line
if (is_comment(bufptr)) continue;

parse_flight_cost_line(lineno, bufptr);
}
cout << "Done with " << cost_filename << endl;
fclose(cost_fp);

#endif ECHO
for (i=1; i <= G_number_nodes; i++)
{
int number_of_destins = G_number_nodes - i;
int j;

for (j=1; j <= number_of_destins; j++)
    cout << i << " " << i+j << " " << G_node_array[i].cost[j].amount << endl;
}
#endif
}

void read_node_file(char *node_filename)
{
FILE *node_fp;
//int i;
char message[256];
char input_line[1024];
char *bufptr;
int lineno = 0;
//float center_lat, center_long;
//double x, y;

```

```

if ((node_fp = fopen(node_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", node_filename);
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

// min_lat = 90.0;
// min_long = 180.0;
// max_lat = -90.0;
// max_long = -180.0;

cout << "Reading " << node_filename << endl;

for(;;)
{
    // Get the next input line
    fgets(input_line, sizeof(input_line), node_fp);
    lineno++;

    // If we are at the end of file break, out of this loop
    if (feof(node_fp)) break;

    // Assign bufptr the base address of the input line
    bufptr = input_line;

    // Make sure bufptr is pointing to the first non-whitespace
    // character in the input line.
    skip_leading_whitespace(&bufptr);

    // If this line is a comment line continue to the next line
    if (is_comment(bufptr)) continue;

    parse_node_line(lineno, bufptr);
}

cout << "Done with " << node_filename << endl;
fclose(node_fp);

// lat_long_to_x_y(min_lat, min_long, max_lat, max_long,
//                  &x, &y);

// G_map_width = x;
// G_map_height = y;
// center_lat = (min_lat + max_lat) / 2.0;
// center_long = (min_long + max_long) / 2.0;

```

```

// for (i = 1; i <= G_number_nodes; i++)
// {
//     lat_long_to_x_y(center_lat, center_long,
//                      G_node_array[i].x, G_node_array[i].y, &x, &y);
//     G_node_array[i].x = x;
//     G_node_array[i].y = y;
// }
}

void read_per_diem_file(char *per_diem_filename)
{
FILE *per_diem_fp;
char message[256];
char input_line[1024];
char *bufptr;
int lineno = 0;

if ((per_diem_fp = fopen(per_diem_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", per_diem_filename) ;
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING ) ;
    exit(-1);
}

cout << "Reading " << per_diem_filename << endl;

for(;;)
{
    // Get the next input line
    fgets(input_line, sizeof(input_line), per_diem_fp);
    lineno++;

    // If we are at the end of file break, out of this loop
    if (feof(per_diem_fp)) break;

    // Assign bufptr the base address of the input line
    bufptr = input_line;

    // Make sure bufptr is pointing to the first non-whitespace
    // character in the input line.
    skip_leading_whitespace(&bufptr);

    // If this line is a comment line continue to the next line
    if (is_comment(bufptr)) continue;

    parse_per_diem_line(lineno, bufptr);
}

```

```

        }

cout << "Done with " << per_diem_filename << endl;
fclose(per_diem_fp);

#endif ECHO
int i;
for (i=1; i <= G_number_nodes; i++)
{
    cout << "Per diem at node " << i << " is "
        << G_node_array[i].meals << " (meals) "
        << G_node_array[i].lodging << " (lodging)" << endl;
}
#endif
}

void read_route_file(char *route_filename)
{
FILE *route_fp;
char message[256] ;
char input_line[1024];
char label[15];
char arc_label[15];
int start_node, destin_node;
int arc_id, from_node, to_node, index;
long lineno = 0;

if ((route_fp = fopen(route_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", route_filename);
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

cout << "Reading " << route_filename << endl;

while (!feof(route_fp))
{
    fgets(input_line, sizeof(input_line), route_fp);
    lineno++;

    if (feof(route_fp)) break;

    if (sscanf(input_line, "%s%s%d%s%s%d",
               label, label, &start_node,
               label, label, &destin_node) != 6)
    {

```

```

        sprintf (message, "Unrecognizable node data specified at line %d",
            lineno);
        MessageBox (NULL, message, route_filename, MB_OK | MB_ICONWARNING );
        fclose(route_fp);
        return;
    }

if (start_node > destin_node)
{
    for (;;)
    {
        fgets(input_line, sizeof(input_line), route_fp);
        lineno++;

        if (feof(route_fp)) break;

        if (isspace(input_line[0]))
        {
            fgets(input_line, sizeof(input_line), route_fp);
            lineno++;
            break;
        }
    }

    continue;
}

for (;;)
{
    fgets(input_line, sizeof(input_line), route_fp);
    lineno++;

    if (feof(route_fp)) break;

    if (isspace(input_line[0]))
    {
        fgets(input_line, sizeof(input_line), route_fp);
        lineno++;
        break;
    }

    if (sscanf(input_line, "%s%d%s%s%d%s%s%d",
        label, &arc_id,
        label, label, &from_node,
        label, label, &to_node) != 8)
    {

```

```

        sprintf (message, "Unrecognizable arc data specified at line %d",
                  lineno);
        MessageBox (NULL, message, route_filename, MB_OK | MB_ICONWARNING
    );
        fclose(route_fp);
        return;
    }

transit_record *new_transit = new transit_record;
if (new_transit == NULL)
{
    MessageBox (NULL, "Unable to allocate transit record - out of memory",
               "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

new_transit->node1 = from_node;
new_transit->node2 = to_node;

if (start_node < destin_node)
{
    index = destin_node - start_node;
    G_node_array[start_node].cost[index].path->AddEntry(new_transit);
}
else
{
    index = start_node - destin_node;
    G_node_array[destin_node].cost[index].path->AddEntry(new_transit);
}

} // loop and read the next arc
} // loop and read the next line

cout << "Done with " << route_filename << endl;
fclose(route_fp);
}

void read_usa_map(char *map_filename)
{
FILE *map_fp;
char message[256];
char input_line[1024];
int i;
int type, size;
float latitude, longitude;
double x, y;

```

```

map_entity *me;

if ((G_map_entities = new TMapEntityList<map_entity>) == NULL)
{
    MessageBox (NULL, "Unable to allocate graphic entities list - out of memory",
               "", MB_OK | MB_ICONWARNING );
    exit(-1);
}

if ((map_fp = fopen(map_filename, "r")) == NULL)
{
    sprintf (message, "Can't open input file %s", map_filename) ;
    MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING ) ;
    exit(-1);
}

min_lat = 90.0;
min_long = 180.0;
max_lat = -90.0;
max_long = -180.0;

cout << "Reading " << map_filename << endl;

fgets(input_line, sizeof(input_line), map_fp);

if (sscanf(input_line, "%f%f", &center_lat, &center_long) != 2)
{
    MessageBox (NULL, "Unrecognizable center lat/long specified", "",
               MB_OK | MB_ICONWARNING );
    exit(-1);
}

center_long = fabs(center_long);

for(;;)
{
    fgets(input_line, sizeof(input_line), map_fp);

    if (feof(map_fp)) break;

    if (sscanf(input_line, "%d%d", &type, &size) != 2)
    {
        MessageBox (NULL, "Unrecognizable coordinate block type and size specified",
                   "", MB_OK | MB_ICONWARNING );
        exit(-1);
    }
}

```

```

    }

if ((me = new map_entity(type, size)) == NULL)
{
    MessageBox (NULL, "Unable to allocate graphic entity - out of memory", "",
               MB_OK | MB_ICONWARNING );
    exit(-1);
}

for (i = 0; i < size; i++)
{
    fscanf(map_fp, "%f%f", &latitude, &longitude);
    longitude = fabs(longitude);

    min_lat = min(min_lat, latitude);
    min_long = min(min_long, longitude);
    max_lat = max(max_lat, latitude);
    max_long = max(max_long, longitude);

    lat_long_to_x_y(center_lat, center_long, latitude, longitude, &x, &y);
    me->set_xy_coord(i, (long) x, (long) y);
}

G_map_entities->AddEntry(me);

fgets(input_line, sizeof(input_line), map_fp);
if (feof(map_fp)) break;
}
cout << "Done with " << map_filename << endl;
fclose(map_fp);

lat_long_to_x_y(min_lat, min_long, max_lat, max_long,
                &x, &y);

G_map_width = x;
G_map_height = y;
}

/*
Function: skip_leading_whitespace

```

Date: January 1995

Programmer: David J. Ward

Description:

This function skips the leading white space in the text pointed to by *tokenptr.

Modifications:

```
/*
void skip_leading_whitespace(char **tokenptr)
{
int index, length;
char *token = *tokenptr;

/* If a null pointer is passed in return */
if (token == NULL) return;

/* Get the length of the text that was passed in to this function */
length = (int) strlen(token);

/* starting at the begining of the text move forward until a non-white
space character is found */
for (index = 0; index < length; index++)
{
    /* if the character is white space continue to the next character */
    if (isspace(token[index])) continue;

    break;
}

/* Change the value of the pointer pointed to by tokenptr so
that it points to the first non-white space character. */
*tokenptr = &token[index];
}

int state_index(char *state)
{
int i;

for (i = 0; i < 52; i++)
{
    if (strcmp(state, state_code[i]) == 0) return i;
}

return -1;
}
```

```

#ifndef __constants_h__
#define __constants_h__

#include <math.h>

#define MINUTES_PER_DEGREE 60.0
#define SECONDS_PER_DEGREE 3600.0

#define DEG_PER_RAD 57.29577951 // degrees per radian
#define NM_PER_DEG 60.0        // nautical miles per degree
#define KM_PER_NM 1.853        // Kilometers per nautical mile
#define NM_PER_KM 0.5396
#define TWO_PI    2.0 * M_PI

#define ONE_THOUSANDTH 0.001

#endif

#ifndef __conf_map_entity_h__
#define __conf_map_entity_h__


class map_entity
{
private:
    unsigned type;
    unsigned number_of_pts;
    POINT *pt;

public:
    map_entity(unsigned entity_type, unsigned size);
    ~map_entity();
    unsigned get_number_of_pts(void) { return number_of_pts; } ;
    POINT *get_pt(void) { return pt; } ;
    void set_xy_coord(unsigned index, long x, long y);
};

#endif

#ifndef __read_h__
#define __read_h__


int is_comment(char *token);
int is_token(char *text);
void parse_arc_line(int line_number, char *buf);
void parse_conference_duration_line(int line_number, char *buf);
void parse_conference_site_line(int line_number, char *buf);

```

```

void parse_drive_cost_line(int line_number, char *buf);
void parse_flight_cost_line(int line_number, char *buf);
void parse_node_line(int line_number, char *buf);
void parse_per_diem_line(int line_number, char *buf);
void read_drive_cost(char *cost_filename);
void read_flight_cost(char *cost_filename);
void read_arc_file(char *arc_filename);
void read_node_file(char *node_filename);
void read_per_diem_file(char *per_diem_filename);
void read_route_file(char *route_filename);
void read_usa_map(char *map_filename);
void skip_leading_whitespace(char **tokenptr);
int state_index(char *state);

#endif

/*-----
file_ops.cpp
-----*/
#include <windows.h>
#include "offsite.h"

void init_openfilename_struct (HWND hwnd, OPENFILENAME *ofn)
{
static char szFilter[]= "Text Files (*.TXT)\0*.txt\0" \
                    "All Files (*.*)\0*.*\0\0" ;
static char szInitialDir[] = "..\out" ;

ofn->lStructSize = sizeof (OPENFILENAME) ;
ofn->hwndOwner = hwnd ;
ofn->hInstance = NULL ;
ofn->lpstrFilter = szFilter ;
ofn->lpstrCustomFilter = NULL ;
ofn->nMaxCustFilter = 0 ;
ofn->nFilterIndex = 0 ;
ofn->lpstrFile = NULL ;
ofn->nMaxFile = _MAX_PATH ;
ofn->lpstrFileTitle = NULL ;
ofn->nMaxFileTitle = _MAX_FNAME + _MAX_EXT ;
ofn->lpstrInitialDir = szInitialDir ;
ofn->lpstrTitle = NULL ;
ofn->Flags = 0 ;
ofn->nFileOffset = 0 ;
ofn->nFileExtension = 0 ;
ofn->lpstrDefExt = "txt" ;

```

```

ofn->lCustData = 0L ;
ofn->lpfnHook = NULL ;
ofn->lpTemplateName = NULL ;
}

void save_as_dlg(HWND hwnd, OPENFILENAME *ofn)
{
char buffer[256];
char szFile[] = "noname.txt" ;
FILE *read_fp, *write_fp;

ofn->hwndOwner = hwnd ;
ofn->lpstrFile = szFile ;
ofn->Flags = OFN_HIDEREADONLY | OFN_OVERWRITEPROMPT ;

if (GetSaveFileName(ofn))
{
if ((read_fp = fopen(G_cost_filename, "r")) == NULL ||
(write_fp = fopen(ofn->lpstrFile, "w")) == NULL)
{
sprintf (buffer, "Can't save %s", ofn->lpstrFile) ;
MessageBox (hwnd, buffer, "", MB_OK | MB_ICONWARNING ) ;
return ;
}

while(fgets(buffer, sizeof(buffer), read_fp) != NULL)
{
fprintf(write_fp, "%s", buffer);
}

fclose (read_fp) ;
fclose (write_fp) ;
}

#include "offsresource.h"

IDD_SolveDialog DIALOG 5, 1, 349, 298
STYLE DS_MODALFRAME | DS_3DLOOK | WS_POPUP | WS_VISIBLE |
WS_CAPTION | WS_SYSMENU | WS_MINIMIZEBOX
CAPTION ""
FONT 8, "MS Sans Serif"
{
CONTROL "&Cancel", IDCANCEL, "BUTTON", BS_PUSHBUTTON | BS_CENTER
| WS_CHILD | WS_VISIBLE | WS_TABSTOP, 179, 276, 50, 14

```

```

CONTROL "Conference duration (days):", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 8, 9, 88, 8
CONTROL "", IDC_Duration, "edit", ES_LEFT | ES_NUMBER | WS_CHILD | WS_VISIBLE | WS_BORDER | WS_TABSTOP, 100, 6, 32, 12
CONTROL "Departing city:", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 20, 43, 52, 8
CONTROL "", IDC_DepartingCity, "listbox", LBS_STANDARD | LBS_MULTIPLESEL | WS_CHILD | WS_VISIBLE | WS_TABSTOP, 16, 52, 104, 60
CONTROL "Departing airport:", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 136, 43, 60, 8
CONTROL "", IDC.DepartingAirport, "combobox", CBS_DROPDOWNLIST | CBS_SORT | CBS_NOINTEGRALHEIGHT | WS_CHILD | WS_VISIBLE | WS_TABSTOP, 140, 52, 56, 56
CONTROL "Number of participants:", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 208, 56, 76, 8
CONTROL "", IDC_Participants, "edit", ES_LEFT | ES_NUMBER | WS_CHILD | WS_VISIBLE | WS_BORDER | WS_TABSTOP, 288, 53, 32, 12
CONTROL "Solve:", IDC_GROUPBOX1, "button", BS_GROUPBOX | WS_CHILD | WS_VISIBLE | WS_GROUP, 8, 125, 324, 142
CONTROL "Restrict conference sites to departure points", IDC_Case1, "button", BS_AUTORADIOBUTTON | WS_CHILD | WS_VISIBLE | WS_TABSTOP, 32, 138, 156, 12
CONTROL "Case 2", IDC_Case2, "button", BS_AUTORADIOBUTTON | WS_CHILD | WS_VISIBLE | WS_TABSTOP, 32, 159, 112, 12
CONTROL "Specify site", IDC_Case3, "button", BS_AUTORADIOBUTTON | WS_CHILD | WS_VISIBLE | WS_TABSTOP, 32, 181, 52, 12
CONTROL "Arriving city:", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 104, 183, 40, 8
CONTROL "", IDC_ArrivingCity, "listbox", LBS_STANDARD | WS_CHILD | WS_VISIBLE | WS_DISABLED | WS_TABSTOP, 104, 194, 104, 60
CONTROL "Arriving airport:", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 232, 183, 52, 8
CONTROL "", IDC_ArrivingAirport, "combobox", CBS_DROPDOWNLIST | CBS_SORT | CBS_NOINTEGRALHEIGHT | WS_CHILD | WS_VISIBLE | WS_DISABLED | WS_TABSTOP, 232, 194, 56, 56
CONTROL "E&execute", IDC_Execute, "button", BS_DEFPUSHBUTTON | BS_CENTER | WS_CHILD | WS_VISIBLE | WS_DISABLED | WS_TABSTOP, 119, 276, 50, 14
CONTROL "Departure point(s):", IDC_GROUPBOX2, "button", BS_GROUPBOX | WS_CHILD | WS_VISIBLE | WS_GROUP, 8, 26, 324, 91
}

```

```

IDD_SummaryDialog DIALOG 5, 1, 276, 294
STYLE DS_MODALFRAME | DS_3DLOOK | WS_POPUP | WS_VISIBLE | WS_CAPTION | WS_SYSMENU | WS_MINIMIZEBOX
CAPTION "Summary"

```

```

FONT 8, "Fixedsys"
{
    CONTROL "&OK", IDOK, "BUTTON", BS_PUSHBUTTON | BS_CENTER | 
    WS_CHILD | WS_VISIBLE | WS_TABSTOP, 145, 260, 46, 24
    CONTROL "", IDC_DurationSummary, "static", SS_LEFT | WS_CHILD | 
    WS_VISIBLE, 8, 9, 100, 8
    CONTROL "Departure point(s):", IDC_GROUPBOX1, "button", BS_GROUPBOX | 
    WS_CHILD | WS_VISIBLE | WS_GROUP, 8, 26, 260, 91
    CONTROL "City", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 20, 43, 20, 8
    CONTROL "Airport", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE, 148, 43, 28,
    8
    CONTROL "# of participants", -1, "static", SS_LEFT | WS_CHILD | WS_VISIBLE,
    188, 43, 68, 8
    CONTROL "", IDC_DeparturePoint, "listbox", LBS_STANDARD | 
    LBS_USETABSTOPS | LBS_NOSEL | WS_CHILD | WS_VISIBLE | WS_TABSTOP,
    20, 52, 236, 60
    CONTROL "", IDC_SingleSiteCost, "static", SS_LEFT | SS_SUNKEN | WS_CHILD | 
    NOT WS_VISIBLE, 8, 124, 260, 10
    CONTROL "", IDC_CostGroupBox, "button", BS_GROUPBOX | WS_CHILD | NOT
    WS_VISIBLE | WS_GROUP, 8, 125, 260, 125
    CONTROL "", IDC_TotalCost, "listbox", LBS_NOTIFY | LBS_USETABSTOPS | 
    LBS_NOSEL | WS_CHILD | NOT WS_VISIBLE | WS_BORDER | WS_TABSTOP, 20,
    153, 232, 88
    CONTROL "&Detailed Costs", IDC_DetailedCosts, "button", BS_DEFPUSHBUTTON
    | BS_CENTER | BS_VCENTER | BS_MULTILINE | WS_CHILD | WS_VISIBLE |
    WS_TABSTOP, 85, 260, 46, 24
    CONTROL "City", IDC_SiteStaticText, "static", SS_LEFT | WS_CHILD | NOT
    WS_VISIBLE, 24, 145, 32, 8
    CONTROL "Airport", IDC_AirportStaticText, "static", SS_LEFT | WS_CHILD | NOT
    WS_VISIBLE, 148, 145, 28, 8
    CONTROL "Total cost", IDC_CostStaticText, "static", SS_LEFT | WS_CHILD | NOT
    WS_VISIBLE, 200, 145, 40, 8
}

```

```

IDM_MainMenu MENU
{
    POPUP "&File"
    {
        MENUITEM "&Save As...", IDM_SaveAs, GRAYED
        MENUITEM SEPARATOR
        MENUITEM "E&xit", IDM_Exit
    }

    POPUP "&Solve"
    {
        MENUITEM "&Run...", IDM_Run
    }
}

```

```

}

POPUP "S&how"
{
    MENUITEM "&Airport Names", IDM_AirportNames
    MENUITEM "&Map", IDM_Map
}

ICO_Network ICON "network.ico"

#ifndef __OFFSRESOURCE__
#define __OFFSRESOURCE__

#define IDM_MainMenu      100
#define IDM_SaveAs        101
#define IDM_Exit          102
#define IDM_Run           103
#define IDM_AirportNames  104
#define IDM_Map           105

#define IDD_SolveDialog   200
#define IDC_Duration      201
#define IDC_GROUPBOX1     202
#define IDC_DepartingCity 203
#define IDC_DepartingAirport 204
#define IDC_Participants  205
#define IDC_GROUPBOX2     206
#define IDC_Case1          207
#define IDC_Case2          208
#define IDC_Case3          209
#define IDC_ArrivingCity   210
#define IDC_ArrivingAirport 211
#define IDC_Execute        212

#define IDD_SummaryDialog 300
#define IDC_DurationSummary 301
#define IDC_DeparturePoint 302
#define IDC_SingleSiteCost 303
#define IDC_CostGroupBox   304
#define IDC_SiteStaticText 305
#define IDC_AirportStaticText 306
#define IDC_CostStaticText 307
#define IDC_TotalCost      308
#define IDC_DetailedCosts  309

```

```

#define ICO_Network      400

#endif /* __OFFSRESOURCE__ */

/*
-----summary_dlg_proc.cpp-----
*/

#include <windows.h>
#include "offsite.h"
#include "offsresource.h"

BOOL CALLBACK summary_dlg_proc (HWND hDlg, UINT iMsg, WPARAM wParam, LPARAM lParam)
{
    int i;
    char buffer[256];

    switch (iMsg)
    {
        case WM_INITDIALOG :
        {
            char temp[256];
            int node_index;

            // Display the conference duration in the duration static field
            HWND hwndStaticTxt = GetDlgItem(hDlg, IDC_DurationSummary) ;

            sprintf(buffer, "Conference duration: %d days", G_conf_duration) ;
            SetWindowText(hwndStaticTxt, buffer) ;

            HWND hwndList1 = GetDlgItem(hDlg, IDC_DeparturePoint) ;
            SendMessage(hwndList1, WM_SETREDRAW, FALSE, 0) ;

            for (i = 1; i <= G_number_nodes; i++)
            {
                if (G_node_array[i].participants_solve)
                {
                    sprintf(temp, "%s, %s",
                           G_node_array[i].city,
                           state_code[G_node_array[i].state]) ;
                    sprintf(buffer, "%-20s\t\t%s\t\t%d",
                           temp,
                           G_node_array[i].rics,
                           G_node_array[i].participants_solve) ;
                }
            }
        }
    }
}

```

```

        SendMessage(hwndList1, LB_ADDSTRING, 0, (LPARAM) buffer) ;
    }
}

SendMessage(hwndList1, WM_SETREDRAW, TRUE, 0) ;

if (G_number_sites > 1)
{
    HWND hwndGroupBox = GetDlgItem(hDlg, IDC_CostGroupBox) ;
    ShowWindow(hwndGroupBox, SW_SHOWNORMAL) ;
    if ( G_number_sites > 10)
        strcpy(buffer, "Ten Best Sites") ;
    else
        strcpy(buffer, "Cost to Sites") ;

    SetWindowText(hwndGroupBox, buffer) ;

    HWND hwndList2 = GetDlgItem(hDlg, IDC_TotalCost) ;
    ShowWindow(hwndList2, SW_SHOWNORMAL) ;
    SendMessage(hwndList2, WM_SETREDRAW, FALSE, 0) ;

    for (i = 1; i <= G_number_sites && i <= 10; i++)
    {
        node_index = G_best_sites[i].site;

        sprintf(temp, "%s, %s",
               G_node_array[node_index].city,
               state_code[G_node_array[node_index].state]) ;
        sprintf(buffer, "%-20s\t%s\t%-10.2f",
               temp,
               G_node_array[node_index].rics,
               (float) G_best_sites[i].cost) ;

        SendMessage(hwndList2, LB_ADDSTRING, 0, (LPARAM) buffer) ;
    }

    SendMessage(hwndList2, WM_SETREDRAW, TRUE, 0) ;

    ShowWindow(GetDlgItem(hDlg, IDC_SiteStaticText), SW_SHOWNORMAL)
;
    ShowWindow(GetDlgItem(hDlg, IDC_AirportStaticText),
SW_SHOWNORMAL) ;
    ShowWindow(GetDlgItem(hDlg, IDC_CostStaticText), SW_SHOWNORMAL)
;
}
else

```

```

{
node_index = G_best_sites[G_number_sites].site;
sprintf(buffer, " Cost to %s (%s, %s): %10.2f\n",
        G_node_array[node_index].rics,
        G_node_array[node_index].city,
        state_code[G_node_array[node_index].state],
        (float) G_best_sites[G_number_sites].cost);
hwndStaticTxt = GetDlgItem(hDlg, IDC_SingleSiteCost) ;
ShowWindow(hwndStaticTxt, SW_SHOWNORMAL) ;
SetWindowText(hwndStaticTxt, buffer) ;
}

return TRUE ;
}

case WM_COMMAND :
switch (LOWORD (wParam))
{
case IDCANCEL :
case IDOK :
{
HWND hwndButton = GetDlgItem(GetParent(hDlg), IDC_Execute) ;
EnableWindow(hwndButton, TRUE) ;
DestroyWindow(hDlg) ;
return TRUE ;
}

case IDC_DetailedCosts :
{
char command_line[256];
STARTUPINFO si;
PROCESS_INFORMATION pi;

sprintf (command_line, "notepad.exe %s", G_cost_filename) ;
memset((char *)&si, '\0', sizeof(si)) ;
si.cb = sizeof(si) ;
si.wShowWindow = SW_SHOWNORMAL ;
if (!CreateProcess(NULL,
                  command_line,
                  NULL,
                  NULL,
                  FALSE,
                  0,
                  NULL,
                  NULL,
                  &si,

```

```

        &pi))
    {
        sprintf(buffer, "Unable to execute\n%s", command_line) ;
        MessageBox (NULL, buffer, "", MB_OK | MB_ICONWARNING ) ;
        return TRUE ;
    }
    CloseHandle(pi.hProcess) ;
    CloseHandle(pi.hThread) ;
    return TRUE ;
}
}

return FALSE ;

} // end of summary_dlg_proc

/*
-----  

solv_dlg_proc.cpp  

-----*/

```

```

#include <windows.h>
#include "offsite.h"
#include "offsresource.h"
#include "read.h"

BOOL CALLBACK solve_dlg_proc (HWND hDlg, UINT iMsg, WPARAM wParam,
LPARAM lParam)
{
int i ;
char buffer[80] ;
HWND hwndList1, hwndList2, hwndButton ;

switch (iMsg)
{
case WM_INITDIALOG :
{
// Display the conference duration in the duration edit control
HWND hwndEdit = GetDlgItem(hDlg, IDC_Duration) ;

sprintf(buffer, "%d", G_conf_duration) ;
SetWindowText(hwndEdit, buffer) ;
}

// Cities will be displayed in arriving and departure list boxes.
// Don't allow either list box to update its window until they

```

```

// are filled.

hwndList1 = GetDlgItem(hDlg, IDC_DepartingCity) ;
SendMessage(hwndList1, WM_SETREDRAW, FALSE, 0) ;

hwndList2 = GetDlgItem(hDlg, IDC_ArrivingCity) ;
SendMessage(hwndList2, WM_SETREDRAW, FALSE, 0) ;

for (i = 1; i <= G_number_cities; i++)
{
    sprintf(buffer, "%s, %s", G_city_array[i].city,
           state_code[G_city_array[i].state]) ;
    SendMessage(hwndList1, LB_ADDSTRING, 0, (LPARAM) buffer) ;
    SendMessage(hwndList2, LB_ADDSTRING, 0, (LPARAM) buffer) ;
}

// Finished filling the list boxes, turn the redraw flag back on

SendMessage(hwndList1, WM_SETREDRAW, TRUE, 0) ;
SendMessage(hwndList2, WM_SETREDRAW, TRUE, 0) ;

if (G_city_is_selected == NULL)
{
    if ((G_city_is_selected = new BOOL[G_number_cities]) == NULL)
    {
        MessageBox (NULL, "Unable to allocate city array - out of memory", "",
                   MB_OK | MB_ICONWARNING ) ;
        exit(-1);
    }

    for (i = 0; i < G_number_cities; i++)
        G_city_is_selected[i] = FALSE ;
}

for (i = 0; i < G_number_cities; i++)
{
    if (G_city_is_selected[i])
        SendMessage(hwndList1, LB_SETSEL, TRUE, i) ;
}

// Place a label next to the case 2 radio button

hwndButton = GetDlgItem(hDlg, IDC_Case2) ;
sprintf(buffer, "Best cost over %d sites", G_number_nodes) ;
SetWindowText(hwndButton, buffer);

```

```

    return TRUE ;

case WM_COMMAND :
    switch (LOWORD (wParam))
    {
        case IDCANCEL :
            {
                HWND hwndEdit = GetDlgItem(hDlg, IDC_Participants) ;
                HWND hwndCombo = GetDlgItem(hDlg, IDC_DepartingAirport) ;
                save_number_of_participants(hwndEdit, hwndCombo) ;
                EnableMenuItem(GetMenu(GetParent(hDlg)), IDM_Run, MF_ENABLED) ;
                DestroyWindow(hDlg) ;
                return TRUE;
            }

        case IDC_Case1 :
            disable_Arriving_controls(hDlg) ;
            return TRUE;

        case IDC_Case2 :
            disable_Arriving_controls(hDlg) ;
            return TRUE;

        case IDC_Case3 :
            handle_Case3_radiobutton(hDlg) ;
            return TRUE;

        case IDC_Execute :
            handle_Execute_button(hDlg) ;
            return TRUE;
    }
switch (HIWORD (wParam))
{
    case LBN_SELCHANGE : // == CBN_SELCHANGE

        switch (LOWORD (wParam))
        {
            case IDC_DepartingCity :
                handle_DepartingCity_listbox(hDlg, lParam) ;
                return TRUE;

            case IDC_ArrivingCity :
                handle_ArrivingCity_listbox(hDlg, lParam) ;
                return TRUE;

            case IDC_DepartingAirport :

```

```

        handle_DepartingAirport_combobox(hDlg, lParam) ;
        return TRUE;

    case IDC_ArrivingAirport :
        // Do nothing
        return TRUE;
    }

}

return FALSE ;

} // end of solve_dlg_proc

void disable_Arriving_controls(HWND hDlg)
{
HWND hwndList = GetDlgItem(hDlg, IDC_ArrivingCity);
HWND hwndCombo = GetDlgItem(hDlg, IDC_ArrivingAirport);
HWND hwndButton = GetDlgItem(hDlg, IDC_Execute);

EnableWindow(hwndList, FALSE) ;
EnableWindow(hwndCombo, FALSE) ;
EnableWindow(hwndButton, TRUE) ;

} // end of disable_Arriving_controls

void handle_ArrivingCity_listbox(HWND hDlg, LPARAM lParam)
{
HWND hwndList = (HWND) lParam ;
HWND hwndCombo = GetDlgItem(hDlg, IDC_ArrivingAirport) ;
int index = SendMessage(hwndList, LB_GETCURSEL, 0, 0) ;
int j;
int hash_val, city_id;
int node_id;
char buffer[80] ;
char *tokptr;
char city_name[12], short_name[10];
airport_record *data;

// Clear out the arriving airport combo box
SendMessage(hwndCombo, CB_RESETCONTENT, 0, 0) ;

// Get the city and state from the list box's current selection
SendMessage(hwndList, LB_GETTEXT, index, (LPARAM) buffer) ;

```

```

// Extract the city name
tokptr = strtok(buffer, ",") ;

// Truncate the city name to first nine charaters
memset(short_name, '\0', 10) ;
strncpy(short_name, tokptr, 9) ;

// Go to the two-letter state abbreviation
tokptr = strtok(NULL, " ") ;
skip_leading_whitespace(&tokptr);

// Append state to city string for hash table search
sprintf(city_name, "%s%2s", short_name, tokptr) ;

// Obtain the city index
hash_val = G_cities->find_entry_in_lookup_table(city_name) ;
city_id = G_cities->get_city_id(hash_val) ;

// Fill out the arriving airport combo box with the airports located
// at this city
for (j = 1; j <= G_city_array[city_id].airports->GetNumberEntries(); j++)
{
    data = G_city_array[city_id].airports->GetEntry(j) ;
    node_id = data->id ;
    SendMessage(hwndCombo, CB_ADDSTRING, 0,
               (LPARAM) G_node_array[node_id].rics) ;
}

// Make the first entry in the combo box the default selection
SendMessage(hwndCombo, CB_SETCURSEL, 0, 0) ;

} // end of handle_ArrivingCity_listbox

void handle_Case3_radiobutton(HWND hDlg)
{
    HWND hwndList = GetDlgItem(hDlg, IDC_ArrivingCity);
    HWND hwndCombo = GetDlgItem(hDlg, IDC_ArrivingAirport);
    HWND hwndButton = GetDlgItem(hDlg, IDC_Execute);

    EnableWindow(hwndList, TRUE) ;
    EnableWindow(hwndCombo, TRUE) ;
    EnableWindow(hwndButton, TRUE) ;

} // end of handle_Case3_radiobutton

void handle_DepartingAirport_combobox(HWND hDlg, LPARAM lParam)

```

```

{
    HWND hwndCombo = (HWND) lParam;
    HWND hwndEdit = GetDlgItem(hDlg, IDC_Participants);
    int index;
    int hash_val, node_id;
    char buffer[80];

    // Get the current selection
    index = SendMessage(hwndCombo, CB_GETCURSEL, 0, 0);

    // Get the rics (airport) of the current selection
    SendMessage(hwndCombo, CB_GETLBTEXT, index, (LPARAM) buffer);

    // Obtain the node (airport) index and display the number of participants
    // departing that node in the participants edit control.
    hash_val = G_airports->find_entry_in_lookup_table(buffer);
    node_id = G_airports->get_node_id(hash_val);
    sprintf(buffer, "%d", G_node_array[node_id].participants_temp);
    SetWindowText(hwndEdit, buffer);

} // end of handle_DepartingAirport_combobox

void handle_DepartingCity_listbox(HWND hDlg, LPARAM lParam)
{
    HWND hwndList = (HWND) lParam;
    HWND hwndEdit = GetDlgItem(hDlg, IDC_Participants);
    HWND hwndCombo = GetDlgItem(hDlg, IDC_DepartingAirport);
    int i;
    char buffer[80];

    if (SendMessage(hwndCombo, CB_GETCOUNT, 0, 0) > 0)
    {
        save_number_of_participants(hwndEdit, hwndCombo);

        // Clear out the departing airport combo box
        SendMessage(hwndCombo, CB_RESETCONTENT, 0, 0);
    }

    // Clear out the number of participants edit control
    SendMessage(hwndEdit, EM_SETSEL, 0, -1);
    SendMessage(hwndEdit, WM_CLEAR, 0, 0);

    for (i = 0; i < G_number_cities; i++)
    {
        int j;
        int city_id;

```

```

int hash_val, node_id;
int combo_box_entry;
char *tokptr;
char city_name[12], short_name[10];
airport_record *data;

if (SendMessage(hwndList, LB_GETSEL, i, 0))
{
    // City i has been selected

    if (!G_city_is_selected[i])
    {
        // Add airport(s) to combo list
        G_city_is_selected[i] = TRUE ;

        // Get the city and state from the list box's selection
        SendMessage(hwndList, LB_GETTEXT, i, (LPARAM) buffer) ;

        // Extract the city name
        tokptr = strtok(buffer, ",") ;

        // Truncate the city name to first nine charaters
        memset(short_name, '\0', 10) ;
        strncpy(short_name, tokptr, 9) ;

        // Go to the two-letter state abbreviation
        tokptr = strtok(NULL, " ") ;
        skip_leading_whitespace(&tokptr);

        // Append state to city string for hash table search
        sprintf(city_name, "%s%2s", short_name, tokptr) ;

        // Obtain the city index
        hash_val = G_cities->find_entry_in_lookup_table(city_name) ;
        city_id = G_cities->get_city_id(hash_val) ;

        combo_box_entry = 0;

        for (j = 1; j <= G_city_array[city_id].airports->GetNumberEntries(); j++)
        {
            data = G_city_array[city_id].airports->GetEntry(j) ;
            node_id = data->id ;
            SendMessage(hwndCombo, CB_ADDSTRING, 0,
                       (LPARAM) G_node_array[node_id].rics) ;
            if (G_node_array[node_id].participants_temp)
                combo_box_entry = j - 1 ;
        }
    }
}

```

```

        }

    // Make combo_box_entry the default selection
    SendMessage(hwndCombo, CB_SETCURSEL, combo_box_entry, 0);

    // Get the rics of the default selection
    SendMessage(hwndCombo, CB_GETLBTEXT, combo_box_entry,
        (LPARAM) buffer);

    hash_val = G_airports->find_entry_in_lookup_table(buffer);
    node_id = G_airports->get_node_id(hash_val);
    sprintf(buffer, "%d", G_node_array[node_id].participants_temp);

    SetWindowText(hwndEdit, buffer);
    break;
}
}

else
{
    // City i is not selected

    if (G_city_is_selected[i])
        G_city_is_selected[i] = FALSE;
}
}

} // end of handle_DepartingCity_listbox

void handle_Execute_button(HWND hDlg)
{
    HWND hwndButton = GetDlgItem(hDlg, IDC_Execute);
    HWND hwndEditDur = GetDlgItem(hDlg, IDC_Duration);
    HWND hwndEditPart = GetDlgItem(hDlg, IDC_Participants);
    HWND hwndList = GetDlgItem(hDlg, IDC_DepartingCity);
    HWND hwndRadio1 = GetDlgItem(hDlg, IDC_Case1);
    HWND hwndRadio2 = GetDlgItem(hDlg, IDC_Case2);
    HWND hwndRadio3 = GetDlgItem(hDlg, IDC_Case3);
    HWND hwndComboDep = GetDlgItem(hDlg, IDC_DepartingAirport);
    HWND hwndComboArr = GetDlgItem(hDlg, IDC_ArrivingAirport);
    BOOL zero_departure_pts_specified = TRUE;
    int i, j;
    int hash_val, node_id;
    char amount[10];
    char buffer[80];

    // Get the conference duration from the duration edit control.

}

```

```

GetWindowText(hwndEditDur, amount, GetWindowTextLength(hwndEditDur)+1) ;

if ((G_conf_duration = atoi(amount)) < 1)
{
    MessageBox (hDlg, "Conference duration is not greater than 0",
                "", MB_OK | MB_ICONWARNING ) ;
    return ;
}

save_number_of_participants(hwndEditPart, hwndComboDep) ;

// if (SendMessage(hwndComboDep, CB_GETCOUNT, 0, 0) > 0)
// {
// Get the number of participants from the participants edit control.
//   GetWindowText(hwndEditPart, amount, GetWindowTextLength(hwndEditPart)+1)
;

// // Get the current selection from the departing airport combo box
//   i = SendMessage(hwndComboDep, CB_GETCURSEL, 0, 0) ;

// // Get the rics of the current selection
//   SendMessage(hwndComboDep, CB_GETLBTEXT, i, (LPARAM) buffer) ;

// // Obtain the node (airport) index and set the number of participants
// // departing that node.
//   hash_val = G_airports->find_entry_in_lookup_table(buffer) ;
//   node_id = G_airports->get_node_id(hash_val) ;
//   G_node_array[node_id].participants_temp = atoi(amount) ;
// }

for (i = 1; i <= G_number_nodes; i++)
{
    G_node_array[i].participants_solve = 0 ;
    G_node_array[i].is_site = FALSE ;
}

for (i = 0; i < G_number_cities; i++)
{
    int city_id;
    char city_name[12], short_name[10];
    char *tokptr;
    airport_record *data;

    if (SendMessage(hwndList, LB_GETSEL, i, 0))
    {
        // City i has been selected

```

```

// Get the city and state from the list box's selection
SendMessage(hwndList, LB_GETTEXT, i, (LPARAM) buffer) ;

// Extract the city name
tokptr = strtok(buffer, ",") ;

// Truncate the city name to first nine charaters
memset(short_name, '\0', 10) ;
strncpy(short_name, tokptr, 9) ;

// Go to the two-letter state abbreviation
tokptr = strtok(NULL, " ") ;
skip_leading_whitespace(&tokptr);

// Append state to city string for hash table search
sprintf(city_name, "%s%2s", short_name, tokptr) ;

// Obtain the city index
hash_val = G_cities->find_entry_in_lookup_table(city_name) ;
city_id = G_cities->get_city_id(hash_val) ;

for (j = 1; j <= G_city_array[city_id].airports->GetNumberEntries(); j++)
{
    data = G_city_array[city_id].airports->GetEntry(j) ;
    node_id = data->id ;

    if (G_node_array[node_id].participants_temp)
    {
        // Airport has been selected
        zero_departure_pts_specified = FALSE ;
        G_node_array[node_id].participants_solve =
            G_node_array[node_id].participants_temp ;
    }
}
}

} // loop to the next entry in the departing city list box

if (zero_departure_pts_specified)
{
    MessageBox (hDlg, "No departure points have been specified or\nzero participants
from all departure points",
        "", MB_OK | MB_ICONWARNING ) ;
    return ;
}

if (SendMessage(hwndRadio1, BM_GETCHECK, 0, 0)) //Case 1

```

```

{
// Conference sites restricted to departing cities/airports
for (i = 1; i <= G_number_nodes; i++)
{
    if (G_node_array[i].participants_solve)
    {
        // Participants departing from airport i
        G_node_array[i].is_site = TRUE;
    }
}
}
else if (SendMessage(hwndRadio2, BM_GETCHECK, 0, 0)) // Case 2
{
// All nodes considered as conference sites
for (i = 1; i <= G_number_nodes; i++)
    G_node_array[i].is_site = TRUE;
}
else if (SendMessage(hwndRadio3, BM_GETCHECK, 0, 0)) // Case 3
{
// Single conference site specified

if (SendMessage(hwndComboArr, CB_GETCOUNT, 0, 0) < 1)
{
    MessageBox (hDlg, "You chose the third Solve option but\ndid not specify the
arriving airport",
    "", MB_OK | MB_ICONWARNING );
    return ;
}

// Get the current selection from the arriving airport combo box
j = SendMessage(hwndComboArr, CB_GETCURSEL, 0, 0);

// Get the rics of the current selection
SendMessage(hwndComboArr, CB_GETLBTEXT, j, (LPARAM) buffer);

// Obtain the node (airport) index and set that node's conference site
// flag.
hash_val = G_airports->find_entry_in_lookup_table(buffer);
node_id = G_airports->get_node_id(hash_val);
G_node_array[node_id].is_site = TRUE;
}

SetCursor(LoadCursor(NULL, IDC_WAIT));
ShowCursor(TRUE);

EnableWindow(hwndButton, FALSE);

```

```

determine_travel_costs();

ShowCursor(FALSE);
SetCursor(LoadCursor(NULL, IDC_ARROW));

CreateDialog(G_hInstance, MAKEINTRESOURCE(IDD_SummaryDialog),
hDlg, (DLGPROC) summary_dlg_proc);

EnableMenuItem(GetMenu(GetParent(hDlg)), IDM_SaveAs, MF_ENABLED) ;
InvalidateRect(GetParent(hDlg), NULL, TRUE) ;

} // end of handle_Execute_button

void save_number_of_participants(HWND hwndEdit, HWND hwndCombo)
{
int index;
int hash_val, node_id;
char amount[10];
char buffer[80];

if (SendMessage(hwndCombo, CB_GETCOUNT, 0, 0) < 1) return ;

// Get the number of participants from the participants edit control.
// (One is added to GetWindowTextLength because for some reason the
// function returns one less than the actual length of the text in the
// edit control.)
GetWindowText(hwndEdit, amount, GetWindowTextLength(hwndEdit)+1) ;

// Get the current selection from the departing airport combo box
index = SendMessage(hwndCombo, CB_GETCURSEL, 0, 0) ;

// Get the rics of the current selection
SendMessage(hwndCombo, CB_GETLBTEXT, index, (LPARAM) buffer) ;

// Obtain the node (airport) index and set the number of participants
// departing that node.
hash_val = G_airports->find_entry_in_lookup_table(buffer) ;
node_id = G_airports->get_node_id(hash_val) ;
G_node_array[node_id].participants_temp = atoi(amount) ;

} // end of save_number_of_participants

/*
-----winmain.cpp-----
*/

```

```

#include <windows.h>
#define _COMMON_OFFSITE_
#include "offsite.h"
#include "offsresource.h"

int WINAPI WinMain (HINSTANCE hInstance, HINSTANCE hPrevInstance,
                    PSTR szCmdLine, int iCmdShow)
{
    static char szAppName[] = "Off-Site" ;
    HWND      hwnd ;
    MSG       msg ;
    WNDCLASSEX wndclass ;

    wndclass.cbSize      = sizeof (wndclass) ;
    wndclass.style       = CS_HREDRAW | CS_VREDRAW ;
    wndclass.lpfnWndProc = WndProc ;
    wndclass.cbClsExtra  = 0 ;
    wndclass.cbWndExtra  = 0 ;
    wndclass.hInstance   = hInstance ;
    wndclass.hIcon       = LoadIcon (hInstance, MAKEINTRESOURCE(ICO_Network))
;

    wndclass.hCursor     = LoadCursor (NULL, IDC_ARROW) ;
    wndclass.hbrBackground = (HBRUSH) GetStockObject (WHITE_BRUSH) ;
    wndclass.lpszMenuName = NULL ;
    wndclass.lpszClassName = szAppName ;
    wndclass.hIconSm     = LoadIcon (hInstance,
                                    MAKEINTRESOURCE(ICO_Network)) ;

    RegisterClassEx (&wndclass) ;

    hwnd = CreateWindow (szAppName,      // window class name
                        szAppName,          // window caption
                        WS_OVERLAPPEDWINDOW, // window style
                        0,                  // initial x position
                        0,                  // initial y position
                        GetSystemMetrics(SM_CXFULLSCREEN),      // initial x size
                        GetSystemMetrics(SM_CYFULLSCREEN),      // initial y size
                        NULL,                // parent window handle
                        LoadMenu(hInstance,
                                MAKEINTRESOURCE(IDM_MainMenu)), // window menu handle
                        hInstance,           // program instance handle
                        NULL) ;             // creation parameters

    ShowWindow (hwnd, iCmdShow) ;
    UpdateWindow (hwnd) ;
}

```

```

while (GetMessage (&msg, NULL, 0, 0))
{
    TranslateMessage (&msg) ;
    DispatchMessage (&msg) ;
}
return msg.wParam ;
}

#include <windows.h>
#include <iostream.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "offsite_hash.h"

city_table :: city_table()
{
int i;

for(i = 0; i < CITY_TABLE_SIZE; i++)
{
    city[i].city_id = NULL;
    memset(city[i].name, '\0', 12) ;
}
}

int city_table :: hash_value(char *text)
{
int i;
int hash_val = 0;
int incrementer = 1;

// Obtain the sum of characters in the supplied text
for(i = 0; text[i] != '\0'; i++)
    hash_val += text[i] * incrementer++;

// Return the hash value modulo CITY_TABLE_SIZE

return ((hash_val * CITY_TABLE_DISPERSION_FACTOR) %
CITY_TABLE_SIZE);
}

int city_table :: find_entry_in_lookup_table(char *name)
{
int i, inc;

```

```

i = this->hash_value(name);
inc = 1;
for(;;)
{
    // If the entry for this index has no name assigned then this
    // name is not in the table
    if (city[i].name[0] == '\0') return (-1);

    if (strcmp(name, city[i].name) == 0) return(i);

    i += inc++;
    i %= CITY_TABLE_SIZE;
    if (inc > CITY_TABLE_SIZE)
    {
        return(-1);
    }
}
}

int city_table :: insert_entry_in_lookup_table(char *name)
{
int i, inc;

i = this->hash_value(name);
inc = 1;
for(;;)
{
    // If the entry for this index has no symbol assigned then this
    // name is not in the table
    if (city[i].name[0] == '\0')
    {
        strncpy(city[i].name, name, 11);
        return(i);
    }

    if (strcmp(name, city[i].name) == 0) return(i);

    i += inc++;
    i %= CITY_TABLE_SIZE;
    if (inc > CITY_TABLE_SIZE)
    {
        char message[256] ;
        sprintf (message, "Hash table overflow on %s", name) ;
        MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING ) ;
    }
}
}

```

```

        exit(-1);
    }
}
}

#ifndef __offsite_hash_h__
#define __offsite_hash_h__


// The maximum number of entries for the airport and city hash tables.
#define AIRPORT_TABLE_SIZE 2048
#define CITY_TABLE_SIZE 2048

// The dispersion constant used in calculating a hash value.
#define AIRPORT_TABLE_DISPERSION_FACTOR 42
#define CITY_TABLE_DISPERSION_FACTOR 42

class airport_table
{
private:
    typedef struct
    {
        char  airport_id[4];
        unsigned node_id;
    } airport_designator;

    airport_designator rics[AIRPORT_TABLE_SIZE];

public:
    airport_table();
    ~airport_table() {};

    int hash_value(char *text);
    int find_entry_in_lookup_table(char *name);
    int insert_entry_in_lookup_table(char *name, int node_id);
    int get_node_id(int hash_val) { return rics[hash_val].node_id; };
};

class city_table
{
private:
    typedef struct
    {
        char  name[12];
        unsigned city_id;
    } city_info;

```

```

city_info city[CITY_TABLE_SIZE];

public:
    city_table();
    ~city_table() { };

    int hash_value(char *text);
    int find_entry_in_lookup_table(char *name);
    int insert_entry_in_lookup_table(char *name);
    int get_city_id(int hash_val) { return city[hash_val].city_id; };
    void set_city_id(int hash_val, int id) {city[hash_val].city_id = id; };
};

#endif

#include <windows.h>
#include <iostream.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "offsite_hash.h"

airport_table :: airport_table()
{
    int i, j;

    for(i = 0; i < AIRPORT_TABLE_SIZE; i++)
    {
        rics[i].node_id = NULL;
        memset(rics[i].airport_id, '\0', 4);
    }
}

int airport_table :: hash_value(char *text)
{
    int i;
    int hash_val = 0;
    int incrementer = 1;

    // Obtain the sum of characters in the supplied text
    for(i = 0; text[i] != '\0'; i++)
        hash_val += text[i] * incrementer++;

    // Return the hash value modulo AIRPORT_TABLE_SIZE
}

```

```

    return ((hash_val * AIRPORT_TABLE_DISPERSION_FACTOR) %
AIRPORT_TABLE_SIZE);
}

int airport_table :: find_entry_in_lookup_table(char *name)
{
int i, inc;

i = this->hash_value(name);
inc = 1;
for(;;)
{
// If the entry for this index has no name assigned then this
// name is not in the table
if (rics[i].airport_id[0] == '\0') return (-1);

if (strcmp(name, rics[i].airport_id) == 0) return(i);

i += inc++;
i %= AIRPORT_TABLE_SIZE;
if (inc > AIRPORT_TABLE_SIZE)
{
    return(-1);
}
}
}

int airport_table :: insert_entry_in_lookup_table(char *name, int node_id)
{
int i, inc;

i = this->hash_value(name);
inc = 1;
for(;;)
{
// If the entry for this index has no symbol assigned then this
// name is not in the table
if (rics[i].airport_id[0] == '\0')
{
    strncpy(rics[i].airport_id, name, 3);
    rics[i].node_id = node_id;
    return(i);
}

if (strcmp(name, rics[i].airport_id) == 0) return(i);
}
}

```

```

    i += inc++;
    i %= AIRPORT_TABLE_SIZE;
    if (inc > AIRPORT_TABLE_SIZE)
    {
        char message[256];
        sprintf (message, "Hash table overflow on %s", name);
        MessageBox (NULL, message, "", MB_OK | MB_ICONWARNING );
        exit(-1);
    }
}

/*
-----winproc.cpp-----
*/

```

```

#include <windows.h>
#include "offsite.h"
#include "offsresource.h"
#include "read.h"

LRESULT CALLBACK WndProc (HWND hwnd, UINT iMsg, WPARAM wParam,
LPARAM lParam)
{
    static HWND hWndStatusBar ;
    static OPENFILENAME ofn ;
    static int cxClient ; // width of client area
    static int cyClient ; // height of client area
    HMENU hMenu = GetMenu(hwnd) ;
    HDC hdc ;
    BOOL show_names, show_map;

    switch (iMsg)
    {
        case WM_CREATE :
            {
                G_hInstance = ((LPCREATESTRUCT) lParam)->hInstance ;

                G_airports = new airport_table();
                G_cities = new city_table();
                G_number_cities = 0;
                G_city_is_selected = NULL;

                char arc_filename[] = "..\\data\\airport_arc.dat";

```

```

char drv_cost_filename[] = "..\\data\\airport_drive_cost.dat";
char flt_cost_filename[] = "..\\data\\airport_fly_cost.dat";
char map_filename[] = "..\\maps\\usa.map";
char node_filename[] = "..\\data\\airport_node.dat";
char per_diem_filename[] = "..\\data\\per_diem.dat";
char route_filename[] = "..\\data\\airport_route.txt";

read_usa_map(map_filename);
read_arc_file(arc_filename);
read_node_file(node_filename);
read_per_diem_file(per_diem_filename);
read_flight_cost(flt_cost_filename);
read_drive_cost(drv_cost_filename);
read_route_file(route_filename);

// Create status bar
hwndStatusBar = init_status_bar (hwnd) ;

init_openfilename_struc (hwnd, &ofn) ;

CheckMenuItem(hMenu, IDM_AirportNames , MF_BYCOMMAND | MF_CHECKED) ;
CheckMenuItem(hMenu, IDM_Map , MF_BYCOMMAND | MF_CHECKED) ;

return 0 ;
}

case WM_COMMAND :
switch (LOWORD (wParam))
{
case IDM_SaveAs :
{
char buffer[256];
char szFile[] = "noname.txt" ;
FILE *read_fp, *write_fp;

ofn.hwndOwner = hwnd ;
ofn.lpstrFile = szFile ;
ofn.Flags = OFN_HIDEREADONLY | OFN_OVERWRITEPROMPT ;

if (GetSaveFileName(&ofn))
{
if ((read_fp = fopen(G_cost_filename, "r")) == NULL ||
(write_fp = fopen(ofn.lpstrFile, "w")) == NULL)
{
sprintf (buffer, "Can't save %s", ofn.lpstrFile) ;
}
}
}
}

```

```

    MessageBox (hwnd, buffer, "", MB_OK | MB_ICONWARNING ) ;
    return 0;
}

while(fgets(buffer, sizeof(buffer), read_fp) != NULL)
{
    fprintf(write_fp, "%s", buffer);
}

fclose (read_fp) ;
fclose (write_fp) ;
}

return 0;

case IDM_Exit :
    SendMessage(hwnd, WM_CLOSE, 0, 0L);
    return 0 ;

case IDM_Run :
    EnableMenuItem(hMenu, IDM_Run, MF_GRAYED) ;
    CreateDialog(G_hInstance, MAKEINTRESOURCE(IDD_SolveDialog),
                hwnd, (DLGPROC) solve_dlg_proc) ;
    return 0 ;

case IDM_AirportNames :
    // Retrieve the state of the Show Airport Names item
    show_names = GetMenuState(hMenu, IDM_AirportNames,
                              MF_BYCOMMAND) & MF_CHECKED ;

    // Toggle the state of the item
    CheckMenuItem(hMenu, IDM_AirportNames , MF_BYCOMMAND |
                  (show_names ? MF_UNCHECKED : MF_CHECKED)) ;

    InvalidateRect(hwnd, NULL, TRUE) ;
    return 0 ;

case IDM_Map :
    // Retrieve the state of the Show Map item
    show_map = GetMenuState(hMenu, IDM_Map,
                           MF_BYCOMMAND) & MF_CHECKED ;

    // Toggle the state of the item
    CheckMenuItem(hMenu, IDM_Map , MF_BYCOMMAND |

```

```

        (show_map ? MF_UNCHECKED : MF_CHECKED)) ;

        InvalidateRect(hwnd, NULL, TRUE) ;
        return 0 ;

    }

break;

case WM_LBUTTONDOWN :
    return 0 ;

case WM_MOUSEMOVE :
    return 0 ;

case WM_LBUTTONUP :
    return 0 ;

case WM_PAINT :
{
    PAINTSTRUCT ps ;
    int i, site_index ;
    int extent ;
    RECT rect ;
    HPEN hPen[NUMBER_OF_PENS] ;

    hPen[PEN_BLACK] = CreatePen(PS_SOLID, 1, RGB(0, 0, 0)) ;
    hPen[PEN_RED] = CreatePen(PS_SOLID, 1, RGB(255, 0, 0)) ;
    hPen[PEN_GREEN] = CreatePen(PS_SOLID, 1, RGB(0, 255, 0)) ;
    hPen[PEN_BLUE] = CreatePen(PS_SOLID, 1, RGB(0, 0, 255)) ;

    extent = max(G_map_width, G_map_height) / 2.0 ;

    hdc = BeginPaint (hwnd, &ps) ;

    SetMapMode(hdc, MM_ISOTROPIC) ;
    SetWindowExtEx(hdc, extent, extent, NULL) ;
    SetViewportExtEx(hdc, -cxClient / 2, -cyClient / 2, NULL) ;
    SetViewportOrgEx(hdc, cxClient / 2, cyClient / 2, NULL) ;

    // Retrieve the state of the Show Map item
    show_map = GetMenuState(hMenu, IDM_Map,
                           MF_BYCOMMAND) & MF_CHECKED ;

    G_map_entities->Draw(hdc, show_map, hPen);

#ifndef CHECK_MAP_ALIGNMENT

```

```

if ((site_index = G_best_sites[1].site) < 1)
{
    EndPaint (hwnd, &ps) ;

    for (i = 0; i < NUMBER_OF_PENS; i++)
        DeleteObject(hPen[i]) ;

    return 0 ;
}
#endif
// Retrieve the state of the Show Airport Names item
show_names = GetMenuState(hMenu, IDM_AirportNames,
    MF_BYCOMMAND) & MF_CHECKED ;

#ifndef CHECK_MAP_ALIGNMENT
for (i = 1; i <= G_number_nodes; i++)
{
    int index;

    if ((i != site_index) && G_node_array[i].participants_solve)
    {
        if (i < site_index)
        {
            index = site_index - i;
            G_node_array[i].cost[index].path->Draw(i, site_index,
                hdc, show_names,
                hPen) ;
        }
        else
        {
            index = i - site_index;
            G_node_array[site_index].cost[index].path->
                Draw(i, site_index,
                    hdc, show_names,
                    hPen) ;
        }
    }
}

for (i = 1; i <= G_number_nodes; i++)
{
    if ((i != site_index) && G_node_array[i].participants_solve)
    {
        SelectObject(hdc, hPen[PEN_BLACK]) ;
        rect.left = (long) G_node_array[i].x - 20 ;
        rect.top = (long) G_node_array[i].y + 20 ;

```

```

rect.right = (long) G_node_array[i].x + 20 ;
rect.bottom = (long) G_node_array[i].y - 20 ;

Ellipse (hdc, rect.left, rect.top, rect.right, rect.bottom) ;

if (show_names)
{
    TextOut(hdc, rect.left, rect.top, G_node_array[i].rics,
            strlen(G_node_array[i].rics)) ;
}
}

rect.left = (long) G_node_array[site_index].x - 20 ;
rect.top = (long) G_node_array[site_index].y + 20 ;
rect.right = (long) G_node_array[site_index].x + 20 ;
rect.bottom = (long) G_node_array[site_index].y - 20 ;

SelectObject(hdc, hPen[PEN_RED]) ;
Ellipse (hdc, rect.left, rect.top, rect.right, rect.bottom) ;

if (show_names)
{
    TextOut(hdc, rect.left, rect.top, G_node_array[site_index].rics,
            strlen(G_node_array[site_index].rics)) ;
}
#else
for (i = 1; i <= G_number_nodes; i++)
{
    SelectObject(hdc, hPen[PEN_BLACK]) ;
    rect.left = (long) G_node_array[i].x - 20 ;
    rect.top = (long) G_node_array[i].y + 20 ;
    rect.right = (long) G_node_array[i].x + 20 ;
    rect.bottom = (long) G_node_array[i].y - 20 ;

    Ellipse (hdc, rect.left, rect.top, rect.right, rect.bottom) ;

    if (show_names)
    {
        TextOut(hdc, rect.left, rect.top, G_node_array[i].rics,
                strlen(G_node_array[i].rics)) ;
    }
}
#endif
EndPaint (hwnd, &ps) ;

```

```

for (i = 0; i < NUMBER_OF_PENS; i++)
    DeleteObject(hPen[i]) ;

return 0 ;
}

case WM_SIZE :
{
int cyStatus ;
RECT rWindow ;

cxClient = LOWORD (lParam) ;
cyClient = HIWORD (lParam) ;

// Adjust status bar size
GetWindowRect (hwndStatusBar, &rWindow) ;
cyStatus = rWindow.bottom - rWindow.top ;
MoveWindow (hwndStatusBar, 0, cyClient - cyStatus,
            cxClient, cyStatus, TRUE) ;
return 0 ;
}

case WM_DESTROY :
if (G_city_is_selected != NULL)
    delete [] G_city_is_selected ;

delete [] G_arc_array ;

for (int i = 1; i < G_number_nodes; i++)
{
    int number_of_destins = G_number_nodes - i ;

    for (int j = 1; j <= number_of_destins; j++)
    {
        if (G_node_array[i].cost[j].path != NULL)
            delete G_node_array[i].cost[j].path ;
    }

    delete [] G_node_array[i].cost ;

    if (G_city_array[i].airports != NULL)
        delete G_city_array[i].airports ;
}

delete [] G_node_array ;
delete [] G_best_sites ;

```

```

        delete G_cities ;
        delete G_airports ;
        delete G_map_entities ;

        PostQuitMessage (0) ;
        return 0 ;
    }

    return DefWindowProc (hwnd, iMsg, wParam, lParam) ;
}

void init_openfilename_struc (HWND hwnd, OPENFILENAME *ofn)
{
    static char szFilter[]= "Text Files (*.TXT)\0*.txt\0" \
                           "All Files (*.*)\0*.*\0\0" ;
    static char szInitialDir[] = "..\out" ;

    ofn->lStructSize = sizeof (OPENFILENAME) ;
    ofn->hwndOwner = hwnd ;
    ofn->hInstance = NULL ;
    ofn->lpstrFilter = szFilter ;
    ofn->lpstrCustomFilter = NULL ;
    ofn->nMaxCustFilter = 0 ;
    ofn->nFilterIndex = 0 ;
    ofn->lpstrFile = NULL ;
    ofn->nMaxFile = _MAX_PATH ;
    ofn->lpstrFileTitle = NULL ;
    ofn->nMaxFileTitle = _MAX_FNAME + _MAX_EXT ;
    ofn->lpstrInitialDir = szInitialDir ;
    ofn->lpstrTitle = NULL ;
    ofn->Flags = 0 ;
    ofn->nFileOffset = 0 ;
    ofn->nFileExtension = 0 ;
    ofn->lpstrDefExt = "txt" ;
    ofn->lCustData = 0L ;
    ofn->lpfnHook = NULL ;
    ofn->lpTemplateName = NULL ;
}

#ifndef __offsite_h__
#define __offsite_h__

#ifndef __COMMON_OFFSITE__
#define __COMMON_OFFSITE__ extern
#endif

```

```

#include <windows.h>
#include <stdio.h>
#include "Tlist.h"
#include "offsite_hash.h"
#include "map_entity.h"

#ifndef FALSE
#define FALSE 0
#endif

#ifndef TRUE
#define TRUE 1
#endif

#define NUMBER_OF_PENS 4
#define PEN_BLACK 0
#define PEN_RED 1
#define PEN_GREEN 2
#define PEN_BLUE 3

typedef struct
{
    unsigned start_node;
    unsigned end_node;
    int cost;
} arc;

typedef struct
{
    unsigned node1;
    unsigned node2;
} transit_record;

typedef struct
{
    unsigned amount; // cost to fly or drive
    unsigned char is_drive_cost; // cost represents driving cost (TRUE/FALSE)
    TPathList<transit_record>
        *path; // list of nodes to visit while transiting
} travel_cost;

typedef struct

```

```

{
char rics[4]; // three-letter airport designator
char city[16]; // city name
int state;
float x; // in kilometers
float y; // in kilometers
unsigned participants_temp; // # of participants extracted from dialog box
unsigned participants_solve; // # of participants actually travelling
unsigned meals; // meal per diem
unsigned lodging; // lodging per diem
unsigned is_site; // designated conference site (TRUE/FALSE)
travel_cost *cost; // travel cost to other nodes
} node;

typedef struct
{
unsigned site;
int cost;
} potential_site;

typedef struct
{
unsigned id; // index to node
} airport_record;

typedef struct
{
char city[16];
int state;
TList<airport_record> *airports; // list of airports
} city_and_airport;

__COMMON_OFFSITE__ char *state_code[] =
{
"AK", "AL", "AR", "AZ", "CA", "CO", "CT", "DC", "DE", "FL", "GA", "HI",
"IA", "ID", "IL", "IN", "KS", "KY", "LA", "MA", "MD", "ME", "MI", "MN",
"MO", "MS", "MT", "NC", "ND", "NE", "NH", "NJ", "NM", "NV", "NY", "OH",
"OK", "OR", "PA", "PR", "RI", "SC", "SD", "TN", "TX", "UT", "VA", "VT",
"WA", "WI", "WV", "WY"
};

__COMMON_OFFSITE__ char G_cost_filename[] = "..\\out\\travel_cost.txt";

__COMMON_OFFSITE__ unsigned G_number_arcs;
__COMMON_OFFSITE__ unsigned G_number_nodes;
__COMMON_OFFSITE__ unsigned G_number_cities;

```

```

__COMMON_OFFSITE__ arc *G_arc_array;
__COMMON_OFFSITE__ node *G_node_array;

__COMMON_OFFSITE__ unsigned G_conf_duration;

__COMMON_OFFSITE__ unsigned G_number_sites;
__COMMON_OFFSITE__ potential_site *G_best_sites;

__COMMON_OFFSITE__ airport_table *G_airports;
__COMMON_OFFSITE__ city_table *G_cities;

__COMMON_OFFSITE__ city_and_airport *G_city_array;

__COMMON_OFFSITE__ BOOL *G_city_is_selected;

__COMMON_OFFSITE__ float G_map_width; // in kilometers
__COMMON_OFFSITE__ float G_map_height; // in kilometers

__COMMON_OFFSITE__ TMapEntityList<map_entity> *G_map_entities;

__COMMON_OFFSITE__ HINSTANCE G_hInstance;

LRESULT CALLBACK WndProc (HWND, UINT, WPARAM, LPARAM);
HWND init_status_bar (HWND hwndParent);

void init_openfilename_struc (HWND hwnd, OPENFILENAME *ofn);
void save_as_dlg(HWND hwnd, OPENFILENAME *ofn);

BOOL CALLBACK solve_dlg_proc (HWND, UINT, WPARAM, LPARAM);
void disable_Arriving_controls(HWND);
void handle_ArrivingCity_listbox(HWND, LPARAM);
void handle_Case3_radiobutton(HWND);
void handle_DepartingCity_listbox(HWND, LPARAM);
void handle_DepartingAirport_combobox(HWND, LPARAM);
void handle_Execute_button(HWND);
void save_number_of_participants(HWND, HWND);

BOOL CALLBACK summary_dlg_proc (HWND, UINT, WPARAM, LPARAM);

void determine_travel_costs(void);
int tdy_cost_to_site(unsigned site, unsigned origin, FILE *cost_fp);

#endif

```

REPORT DOCUMENTATION PAGE

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13. ABSTRACT (Maximum 200 Words) A recurrent reason for DCMC employee travel is to attend professional conferences or development training. The location of the conference or training site is often an arbitrary decision with little regard for travel cost. We developed a methodology to evaluate relevant travel costs and return the least expensive conference site given over 260 cities in the US with Government contracted airfares. This schema involves a new use of Dykstra's algorithm modified for non-capacitated shortest path network optimization as well as the computation of inter-airport distances using latitude and longitude data. This paper introduces a program called OffSite which optimizes the selection of collective training events or conferences where people need to come together from geographically dispersed locations. OffSite requires meeting or conference planners to input a list of origin cities for conference participants. It then determines the least cost location for hosting the conference. Additionally, OffSite is flexible enough to allow planners to choose a preferred destination. This system can also restrict the search for meeting venues to origin locations should an organizer wish to have one of the meeting's participants "host" the conference.			
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